Algorithms for Model Checking (2IW55) Lecture 11 Parameterised Boolean Equation Systems (3)

Background material:

- Verification of Reactive Systems via Instantiation of Parameterised Boolean Equation Systems, B. Ploeger, J.W. Wesselink and T.A.C. Willemse (I&C 2010/2011)
- Static Analysis Techniques for Parameterised Boolean Equation Systems, S. Orzan, J.W. Wesselink and T.A.C. Willemse (TACAS 2009)

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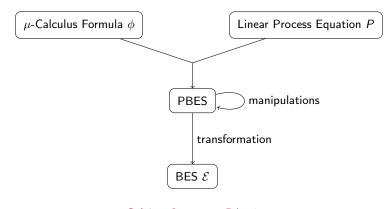


Instantiation

Manipulations



Verification Methodology:



Problem Description

- 1. Given a process P(e) described by an LPE P over Act
- 2. Given a first-order modal μ -calculus formula $\sigma X.\phi$
- 3. Given environments η, ε
- 4. Check whether $P(e) \models \sigma X.\phi$ holds, where:

$$P(e) \models \sigma X.\phi \text{ iff } e \in \llbracket \sigma X.\phi \rrbracket \eta \varepsilon$$

5. Conversion to PBES:

$$P(e) \models \sigma X.\phi \text{ iff } e \in \llbracket \mathsf{E} (\sigma X.\phi) \rrbracket \eta \varepsilon (\tilde{X}) \text{ (or, more informally: } \tilde{X}(e) = \mathsf{true})$$

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How to solve PBESs

$$X_i(e) \stackrel{?}{=} \text{true in } \mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

Known techniques for solving/simplifying \mathcal{E} :

- Gauß Elimination on PBES + symbolic approximation of equations
- Instantiation to BES and subsequently solve the BES
- Using patterns
- Using under/over approximation
- Invariants

Definition (Logical Equivalence)

Let ϕ, ψ be two predicates. Then ψ is logically equivalent to ϕ , denoted $\phi \leftrightarrow \psi$ iff

$$\forall \varepsilon, \eta: \ \llbracket \phi \rrbracket \eta \varepsilon = \llbracket \psi \rrbracket \eta \varepsilon$$

- If $\phi \leftrightarrow \psi$, then equation $\nu X(d:D) = \phi$ has the same solution as $\nu X(d:D) = \psi$ (likewise for μ)
- Useful simplifications:
 - false $\wedge \phi \leftrightarrow$ false
 - true $\lor \phi \leftrightarrow \mathsf{true}$
 - if $d \notin FV(\phi)$, then $(\exists d : D. \phi) \leftrightarrow (\forall d : D. \phi) \leftrightarrow \phi$
 - One-point rule: $(\exists d: D: \phi) \land (\forall d: D: \phi) \leftrightarrow \phi(e)$
 - One-point rule: $(\forall d: D.d = e \Rightarrow \phi(d)) \leftrightarrow \phi(e)$
- Apply logical simplifications before applying PBES manipulations/solving techniques.

Instantiation to BES:

$$X_i(e) \stackrel{?}{=} \text{true in } \mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

- Let X_i^e be a fresh propositional variable representing instance $X_i(e)$.
- ▶ The procedure below creates a BES from \mathcal{E} s.t. $X_i(e) = \text{true}$ iff $X_i^e = \text{true}$
 - 1. For each $X_j(e_j)$ occurring in eval $(\phi_i[d_i:=e])$ create a fresh variable $X_i^{e_j}$
 - 2. Create an equation $\sigma_i X_i^e = \tilde{\phi}_i$, where:
 - $\overline{\phi_i} = \text{eval}(\phi_i[d_i := e]),$
 - $\tilde{\phi_i}$ is $\overline{\phi_i}$ in which every $X_j(e_j)$ is replaced by $X_j^{e_j}$
 - 3. Repeat step 1 and 2 for every $X_i^{e_j}$ introduced in step 1, for which there is no equation
 - 4. Order all equations $\sigma_i X_i^e = ...$ according to the ordering of \mathcal{E} (ordering within a block may be arbitrary)



Instantiation

 ${\sf Manipulations}$



Definition (Simple Formula)

A simple formula is a formula not containing predicate variables

Observations:

- 1. Consider the equation $\nu X(n : Nat) = \text{true} \wedge X(n+1)$
 - X has solution Nat (check!)
 - Consider formal parameter n:
 - It does not affect the value of the simple subformula true
 - It appears to be redundant for the solution to X
- 2. Consider the equation $\nu X(n:Nat,m:Nat)=n\leq 5 \wedge X(n+m,m)$
 - X has solution $\{(n,0) \in Nat \times Nat \mid n \leq 5\}$ (check!)
 - Consider formal parameter m:
 - It does not affect the value of the simple formula $n \le 5$
 - Via a single recursion through X, it does affect the value of $n \leq 5$
 - It appears to become significant for the solution to X



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\begin{array}{lll} \operatorname{sig}(b) & = \operatorname{FV}(b) & \operatorname{dep}(b) & = \emptyset \\ \operatorname{sig}(X(e)) & = \emptyset & \operatorname{dep}(X(e)) & = \{X(e)\} \\ \operatorname{sig}(\phi \wedge \psi) & = \operatorname{sig}(\phi) \cup \operatorname{sig}(\psi) & \operatorname{dep}(\phi \wedge \psi) & = \operatorname{dep}(\phi) \cup \operatorname{dep}(\psi) \\ \operatorname{sig}(\psi \vee \psi) & = \operatorname{sig}(\phi) \cup \operatorname{sig}(\psi) & \operatorname{dep}(\psi \vee \psi) & = \operatorname{dep}(\phi) \cup \operatorname{dep}(\psi) \\ \operatorname{sig}(\forall d:D.\ \phi) & = \operatorname{sig}(\phi) \setminus \{d\} & \operatorname{dep}(\exists d:D.\ \phi) & = \operatorname{dep}(\phi) \\ \operatorname{sig}(\exists d:D.\ \phi) & = \operatorname{sig}(\phi) \setminus \{d\} & \operatorname{dep}(\exists d:D.\ \phi) & = \operatorname{dep}(\phi) \end{array}
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Examples:

- ▶ $sig(true \land X(n+1)) = \emptyset$, $sig(n \le 5 \land X(n+m,m)) = \{n\}$
- ▶ $dep(true \land X(n+1)) = \{X(n+1)\}, dep(n \le 5 \land X(n+m, m)) = \{X(n+m, m)\}$



Assume the following PBES:

$$\mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

- ightharpoonup arity(X_i): the length of vector d_i
- ▶ Construct a marked influence graph $G(\mathcal{E}) = \langle V, \longrightarrow, M \rangle$:
- ▶ $V = \{(X_i, j) \mid 1 \le j \le arity(X_i)\}$ is the set of vertices
- ▶ $(X_i, k) \longrightarrow (X_j, l)$ iff for some expression e: $X_j(e) \in dep(\phi_i)$ and $d_i[k] \in FV(e[l])$
- ▶ $M = \{(X_i, j) \mid 1 \le i \le n \text{ and } d_i[j] \in \text{sig}(\phi_i)\}$ is the marking

Definition (Positively redundant parameters)

Given a Marked Influence Graph $G(\mathcal{E}) = \langle V, \longrightarrow, M \rangle$.

The set of positively redundant parameters of ${\cal E}$ is:

$$\mathcal{R} = \{d_i[j] \mid \neg (\exists (X_k, I) \in M: \ (X_i, j) \longrightarrow^* (X_k, I))\}$$

- ▶ Computing the set \mathcal{R} requires $\mathcal{O}(|\longrightarrow|)$ steps at most
- $ightharpoonup \mathcal{R}$ can be computed using a standard least fixed point computation, a depth-first search or a breadth-first search.

Given closed equation system ${\mathcal E}$ with no unbound data variables

Procedure for eliminating redundant parameters in \mathcal{E}

- 1. Step 1 (compute redundant parameters)
 - 1.1 Construct Marked Influence Graph of \mathcal{E}
 - 1.2 Compute the set \mathcal{R} of positive redundant parameters of \mathcal{E}
- 2. Step 2 (remove redundant parameters): for every equation $\sigma_i X_i(d_i:D_i) = \phi_i$ in \mathcal{E} :
 - 2.1 remove parameter $d_i[j]$ from $X_i(d_i:D_i)$ iff $d_i[j] \in \mathcal{R}$
 - 2.2 remove expression e[j] from an occurrence $X_k(e)$ in ϕ_i iff $d_k[j] \in \mathcal{R}$

Theorem (Redundancy)

The modified equation system $\mathcal E$ has the "same" solution as $\mathcal E$, i.e., the solution of a variable X does not depend on the parameters that have been identified as positively redundant.



Example

- ▶ $\nu X(b:Bool, n:Nat) = b \land X(b, n+1)$ has solution $f = \{(c, v) \in Bool \times Nat \mid c = true\}$
- ▶ $\nu X(b:Bool) = b \wedge X(b)$ has solution $g = \{c \in Bool \mid c = \text{true}\}$
- ▶ For all $c \in Bool$, $v \in Nat$, $(c, v) \in f$ iff $c \in g$.

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Consider the lossy channel system described by the following LPE:

$$C(b: Bool, m: M) = \sum_{k:M} b \longrightarrow r(k) \cdot C(\mathsf{false}, k) + \neg b \longrightarrow s(m) \cdot C(\mathsf{true}, m) + \neg b \longrightarrow l \cdot C(\mathsf{true}, m)$$

Action r stands for reading, s stands for sending and l stands for losing a message.

- 1. $\nu X.([\mathsf{true}]X \wedge (\mu Y.[I]Y \wedge \forall m:M.[r(m)]Y \wedge \langle \mathsf{true}\rangle \mathsf{true}))$
- 2. $\nu X.\mu Y.\nu Z.(\forall m:M.[s(m)]X) \wedge ((\forall m:M.[s(m)]false) \vee ([l]Y \wedge \forall m:M.[r(m)]Y)) \wedge [l]Z \wedge \forall m:M.[r(m)]Z$

Questions:

- ▶ Translate both formulae to PBESs given process $C(\text{true}, m_0)$
- ▶ Use instantiation to compute BESs when M = Bool, and solve the BES ($m_0 = true$)
- Can you remove redundant parameters? If so, remove these redundant parameters and try instantiation to compute a BES when $M = Nat \ (m_0 = 0)$