

ENO and WENO schemes. Further topics and time Integration

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Outline

- 1 **Short review**
 - ENO/WENO
- 2 **Further topics**
 - Subcell resolution
 - Other building blocks
- 3 **Time Integration**
 - TVD Runge-Kutta methods
 - TVD multistep methods
 - Lax-Wendroff procedure

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Solving hyperbolic conservation laws, consider;

- Class of piecewise smooth functions, $v(x)$
- Fixed stencil, $S(i) = \{I_{i-r}, \dots, I_{i+s}\}$, approximation may lead to oscillations near the discontinuity
- Adaptive stencil; left shift r

ENO Procedure

- Compute the divided differences, using the cell averages.
 - For cell I_i start with the two-point stencil $\tilde{S}(i) = \{x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}\}$.
 - Add one of the two neighbouring points, using Newton divided difference measure.
 - Repeat previous step until a k -th order stencil is obtained.
 - Use reconstruction method to compute the approximation to $v(x)$
-
- In the stencil choosing process, k candidate stencils are considered covering $2k - 1$ cells, but only one stencil is used to reconstruct.

To improve the accuracy:

Assume a uniform grid, i.e. $\Delta x_i = \Delta x, i = 1, \dots, N$. Consider the k candidate stencils

$$S_r(i) = \{x_{i-r}, \dots, x_{i-r+k-1}\} \quad r = 0, \dots, k-1.$$

The reconstruction produces k different approximations to the value $v(x_{i+\frac{1}{2}})$:

$$v_{i+\frac{1}{2}}^{(r)} = \sum_{j=0}^{k-1} c_{rj} \bar{v}_{i-r+j} \quad r = 0, \dots, k-1 \quad (1.1)$$

- ▶ WENO takes a convex combination of the $v_{i+\frac{1}{2}}^{(r)}$'s.

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- Instead of using the reconstruction polynomial $P_i(x)$ in the shocked cell I_i , find the location of discontinuity inside I_i , say x_s
- Use neighbouring reconstructions $P_{i-1}(x)$ and $P_{i+1}(x)$
- Extend $P_{i-1}(x)$ and $P_{i+1}(x)$ into the cell I_i
- Require that the cell average \bar{v}_i is preserved:

$$\int_{x_{i-\frac{1}{2}}}^{x_s} P_{i-1}(x) dx + \int_{x_s}^{x_{i+\frac{1}{2}}} P_{i+1}(x) dx = \Delta x_i \bar{v}_i$$

Examples

- rational functions
- trigonometric polynomials
- exponential functions
- radial functions

idea

Find suitable smooth indicators similar to Newton divided difference for the polynomial case.

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Consider,
system of ODEs

$$u_t = L(u)$$

resulting from spatial approximation to PDE;

$$u_t = -f(u)_x$$

Construction

Assume: First order Euler forward time stepping

$$u^{n+1} = u^n + \Delta t L(u^n)$$

is stable in a certain norm

$$\|u^{n+1}\| \leq \|u^n\|$$

under a suitable restriction on Δt : $\Delta t \leq \Delta t_1$

- For higher order in time Runge-Kutta methods,

$$\Delta t < c \Delta t_1 \quad c: \text{CFL coefficient} \quad (3.1)$$

General Runge-Kutta method

$$u^{(i)} = \sum_{k=0}^{i-1} \left(\alpha_{ik} u^k + \Delta t \beta_{ik} L(u^{(k)}) \right), i = 1, \dots, m \quad (3.2)$$
$$u^{(0)} = u^n, u^{(m)} = u^{n+1}$$

For $\alpha_{ik} \geq 0, \beta_{ik} \geq 0 \Rightarrow$ convex combination of Euler forward operators

$$\Delta t \text{ replaced by } \frac{\alpha_{ik}}{\beta_{ik}} \Delta t$$

Consistency;

$$\sum_{k=0}^{i-1} \alpha_{ik} = 1.$$

Lemma

The Runge-Kutta method (3.2) is TVD under the CFL coefficient (3.1)

$$c = \min_{i,k} \frac{\alpha_{ik}}{\beta_{ik}}$$

provided; $\alpha_{ik} \geq 0$ and $\beta_{ik} \geq 0$.

Optimal schemes

- Second order TVD Runge-Kutta

$$u^{(1)} = u^n + \Delta t L(u^n)$$

$$u^{n+1} = \frac{1}{2}u^n + \frac{1}{2}u^{(1)} + \frac{1}{2}\Delta t L(u^{(1)})$$

with CFL $c = 1$.

- Third order TVD R-K

$$u^{(1)} = u^n + \Delta t L(u^n)$$

$$u^{(2)} = \frac{3}{4}u^n + \frac{1}{4}u^{(1)} + \frac{1}{4}\Delta t L(u^{(1)})$$

$$u^{n+1} = \frac{1}{3}u^n + \frac{2}{3}u^{(2)} + \frac{2}{3}\Delta t L(u^{(2)})$$

- Fourth order TVD Runge-Kutta method does not exist with for positive α_{ik} and β_{ik}

Consider

$\alpha_{ik} \geq 0$ and β_{ik} negative

- introduce an adjoint operator \tilde{L}
 - it approximates the same spatial derivatives as L
 - TVD for first order Euler, backward in time:

$$u^{n+1} = u^n - \Delta t \tilde{L} u^n$$

Lemma

The Runge-Kutta method (3.2) is TVD under the CFL coefficient (3.1)

$$c = \min_{i,k} \frac{\alpha_{ik}}{|\beta_{ik}|}$$

provided; $\alpha_{ik} \geq 0$ and L replaced by \tilde{L}

Fourth order TVD R-K

$$u^{(1)} = u^n + \frac{1}{2} \Delta t L(u^n)$$

$$u^{(2)} = \frac{649}{1600} u^{(0)} - \frac{10890423}{25193600} \Delta t \tilde{L}(u^n) + \frac{951}{1600} u^{(1)} + \frac{5000}{7873} \Delta t L u^{(1)}$$

$$u^{(3)} = \frac{53989}{2500000} u^n - \frac{102261}{5000000} \Delta t \tilde{L}(u^n) + \frac{4806213}{20000000} u^{(1)} - \frac{5121}{20000} \Delta t \tilde{L}(u^{(1)}) \\ + \frac{23619}{32000} u^{(2)} + \frac{7873}{10000} \Delta t L(u^{(2)})$$

$$u^{n+1} = \frac{1}{5} u^n + \frac{1}{10} \Delta t L(u^n) + \frac{6127}{30000} u^{(1)} + \frac{1}{6} \Delta t L(u^{(1)}) + \frac{7873}{30000} u^{(2)} \\ + \frac{1}{3} u^{(3)} + \frac{1}{6} \Delta t L(u^{(3)})$$

Example

- Burgers' equation

$$u_t + \left(\frac{1}{2} u^2 \right)_x = 0$$

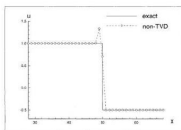
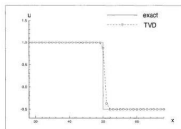
- with Riemann initial data

$$u(x, 0) = \begin{cases} 1, & x \leq 0 \\ -0.5, & x > 0 \end{cases}$$

- Spatial discretization : 2nd order ENO Scheme
- Monotone flux h: Godunov flux
- Time discretization
 - TVD R-K method :Optimal 2nd order
 - Non-TVD R-K

$$u^{(1)} = u^n - 20\Delta t L(u^n)$$

$$u^{n+1} = u^n + \frac{41}{40} u^{(1)} - \frac{1}{40} \Delta t L(u^{(1)})$$



conclusion

It is much safer to use TVD Runge-Kutta Method for solving hyperbolic problem.

Construction

Similar to Runge-kutta Methods

General Form

$$u^{n+1} = \sum_{k=0}^{m-1} (\alpha_k u^{n-k} + \Delta t \beta_k L(u^{n-k})) \quad (3.3)$$

For $\alpha_k \geq 0, \beta_k \geq 0 \Rightarrow$ convex combination of Euler Forward operators

Δt replaced by $\frac{\beta_k}{\alpha_k} \Delta t$

Consistency;

$$\sum_{k=0}^m \alpha_k = 1.$$

Lemma

The multi-step method (3.3) is TVD under the CFL coefficient (3.1)

$$c = \min_k \frac{\alpha_k}{\beta_k}$$

provided; $\alpha_k \geq 0$ and $\beta_k \geq 0$

Examples

- (m=2) three step , second order scheme, TVD with c=0.5

$$u^{n+1} = \frac{3}{4}u^n + \frac{3}{2}\Delta tL(u^n) + \frac{1}{4}u^{n-2} \quad (3.4)$$

- (m=4) five step, third order scheme, TVD with c=0.5

$$u^{n+1} = \frac{25}{32}u^n + \frac{25}{16}\Delta tL(u^n) + \frac{7}{32}u^{n-4} + \frac{5}{16}\Delta tL(u^{n-4})$$

There are no multi-step schemes of order four or higher satisfying positive α_k and β_k

Lemma

The multi-step method (3.3) is TVD under the CFL coefficient (3.1)

$$c = \min_k \frac{\alpha_k}{|\beta_k|}$$

provided; $\alpha_k \geq 0$ and , L is replaced by \tilde{L} for β_k negative.

- one residue evaluation is needed per time step
- storage requirement is much bigger than Runge-Kutta methods

Idea

Taylor series expansion in time:

$$u(x, t + \Delta t) = u(x, t) + u_t(x, t)\Delta t + u_{tt}(x, t)\frac{\Delta t^2}{2} + \dots \quad (3.5)$$

Illustration

$$u_t = -f(u)_x$$

- second order Taylor series expansion
- Replace time derivatives by the spatial derivatives

$$\begin{aligned}
 u_t(x, t) &= -f(u(x, t))_x = -f'(u(x, t))u_x(x, t) \\
 u_{tt}(x, t) &= 2f'(u(x, t))f''(u(x, t))(u_x(x, t))^2 + (f'(u(x, t)))^2 u_{xx}(x, t)
 \end{aligned}
 \tag{3.6}$$

- Substituting (3.6) into (3.5)
- Discretize the spatial derivatives of $u(x, t)$ by ENO/WENO
- Integrate the pde

$$u_t(x, t) + f_x(u(x, t)) = 0$$

over the region $[x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}] \times [t^n, t^{n+1}]$ to obtain

$$\bar{u}_i^{n+1} = \bar{u}_i^n - \frac{1}{\Delta x_i} \left(\int_{t^n}^{t^{n+1}} f(u(x_{i+\frac{1}{2}}, t)) dt - \int_{t^n}^{t^{n+1}} f(u(x_{i-\frac{1}{2}}, t)) dt \right)
 \tag{3.7}$$

- Discretize time using suitable Gaussian quadrature

$$\frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f(u(x_{i+\frac{1}{2}}, t)) dt \approx \sum_{\alpha} \omega_{\alpha} f(u(x_{i+\frac{1}{2}}, t^n + \beta_{\alpha} \Delta t))$$

- replacing $f(u(x_{i+\frac{1}{2}}, t^n + \beta_\alpha \Delta t))$ by a monotone flux

$$f(u(x_{i+\frac{1}{2}}, t^n + \beta_\alpha \Delta t)) \approx h(u(x_{i+\frac{1}{2}}^\pm, t^n + \beta_\alpha \Delta t))$$

- use the Lax-Wendroff procedure to convert

$$u(x_{i+\frac{1}{2}}^\pm, t^n + \beta_\alpha \Delta t) \tag{3.8}$$

to $u(x_{i+\frac{1}{2}}^\pm, t^n)$ and its spacial derivatives at t^n .

limitations

- Algebra is very complicated for multi dimensional systems
- difficult to prove stability properties for higher order methods

