

One-phase Stefan problems

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Outline

- 1 MBP
 - The Stefan Problem
- 2 Strategies for solving MBP
 - Tentative list of methods
 - Self-similar solutions
- 3 Global heat balance
 - Dirichlet problem
 - Neumann problem
- 4 Classical solution
 - Maximum principle
 - Existence theorem

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MBP: The Stefan Problem

describes the melting of ice and the freezing of water.

Definition

$Q_T = \Omega \times (0, T) = \{(x, t) \in \mathbb{R}^2 \mid 0 < x < s(t), 0 < t < T\}$,

find (s, u) such that

$s \in C[0, T] \cap C^1(0, T)$, $u \in C^{2,1}(Q_T) \cap C(\overline{Q_T})$,

$u_x(x, t)$ - continuous,

$$u_{xx} - u_t = 0, \text{ in } Q_T,$$

$s(0) = b > 0$,

$u(x, 0) = h(x), 0 < x < s(0)$,

$u(0, t) = f(t), 0 < t < T$, $|$ $u_x(0, t) = g(t), 0 < t < T$,

$u(s(t), t) = 0, 0 < t < T$,

$u_x(s(t), t) = -\dot{s}(t), 0 < t < T$.

Sign restrictions: $h \geq 0, f \geq 0$ or $g \leq 0$.

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Solving MBP strategies

- Integral equation methods;
- Mapping methods;
- Fixed-domain methods;
- Alternative approaches (for example, self-similar solutions, etc.).

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Self-similar solutions

Heating problem within a fixed-domain

1 $f(\xi), \gamma(t)$, such that $u(x, t) = f(\gamma(t)x)$ satisfies $u_{xx} = u_t$.

2 $\gamma^2 f'' = \dot{\gamma} x f' \Rightarrow \frac{f''}{\xi f'} = \frac{\dot{\gamma}}{\gamma^3} = \lambda^2$, with $\lambda \in \mathbb{R}$.

3 $\frac{\dot{\gamma}}{\gamma^3} = \lambda^2 \Rightarrow \gamma(t) = \lambda^{-1} [2(t - t_0)]^{-\frac{1}{2}}, t > t_0$.

4 $\frac{f''}{\xi f'} = \lambda^2 \Rightarrow f(\xi) = A(\operatorname{erf}(\frac{\lambda \xi}{\sqrt{2}}) - \operatorname{erf}(\frac{\lambda \xi_0}{\sqrt{2}}))$, where
 $\operatorname{erf}(z) := \frac{2}{\sqrt{\pi}} \int_0^z e^{-y^2} dy$.

5 We can define the desired class of self-similar solutions:

$$u(x, t) = A(\operatorname{erf}(\frac{x}{2\sqrt{(t - t_0)}}) - \operatorname{erf}(z_0)),$$

depending on three parameters A, t_0, z_0 .

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Self-similar solutions

Heating problem within a fixed-domain

$$u(x, t) = A \left(\operatorname{erf} \left(\frac{x}{2\sqrt{(t-t_0)}} \right) - \operatorname{erf}(z_0) \right).$$

The Stefan problem

- 1 We set $t_0 = 0$.
- 2 $u(s(t), t) = A \left(\operatorname{erf} \left(\frac{s(t)}{2\sqrt{t}} \right) - \operatorname{erf}(z_0) \right) = 0 \Rightarrow s(t) = 2\alpha\sqrt{t}$.
- 3 $\frac{\partial u}{\partial x} = A \frac{1}{\sqrt{\pi t}} e^{-\frac{x^2}{4t}} = -\dot{s}(t) = -\frac{\alpha}{\sqrt{t}} \Rightarrow A = -\sqrt{\pi}\alpha e^{\alpha^2}$.
- 4 One-parameter family of self-similar solutions:

$$u(x, t) = \sqrt{\pi}\alpha e^{\alpha^2} \left(\operatorname{erf}(\alpha) - \operatorname{erf} \left(\frac{x}{2\sqrt{t}} \right) \right), \quad s(t) = 2\alpha\sqrt{t}.$$

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Global heat balance: Dirichlet problem

Global heat balance

$$\int_0^{s(t)} xu(x, t) dx = \int_0^b xh(x) dx + \int_0^t f(\tau) d\tau - \frac{1}{2}(s^2(t) - b^2).$$

● $u_{xx} - u_t = 0 \Rightarrow$

$$\int_{Q_t} x(u_{xx} - u_t) dx d\tau = 0.$$

● $xu_{xx} = (xu_x - u)_x \Rightarrow$

$$\int_{Q_t} [(xu_x - u)_x - (xu)_\tau] dx d\tau = 0.$$

● Green's Theorem \Rightarrow

$$\oint_{\partial Q_t} [(xu_x - u) d\tau + x u dx] = 0.$$

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Global heat balance: Dirichlet problem

$$\int_{(0,0)}^{(0,t)} \left[\underbrace{x}_{=0} u_x - \underbrace{u}_{=f(\tau)} \right] d\tau + xu \underbrace{dx}_{=0} = - \int_0^t f(\tau) d\tau. \quad (1)$$

$$\int_{(0,t)}^{(s(t),t)} \left[(xu_x - u) \underbrace{d\tau}_{=0} + xudx \right] = \int_0^{s(t)} xu(x, t) dx. \quad (2)$$

$$\int_{(s(t),t)}^{(b,0)} \left[\underbrace{x}_{=s(\tau)} \underbrace{u_x}_{=-\dot{s}(\tau)} - \underbrace{u}_{=0} \right] d\tau + x \underbrace{u}_{=0} dx = \int_0^t [s(\tau)\dot{s}(\tau)] d\tau = \frac{1}{2}(s^2(t) - b^2). \quad (3)$$

$$\int_{(b,0)}^{(0,0)} \left[(xu_x - u) \underbrace{d\tau}_{=0} + x \underbrace{u}_{=h(x)} dx \right] = - \int_0^b xh(x) dx. \quad (4)$$

Global heat balance: Neumann problem

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$$\int_0^{s(t)} u(x, t) dx = \int_0^b h(x) dx - \int_0^t g(\tau) d\tau - (s(t) - b).$$

- $u_{xx} - u_t = 0 \Rightarrow$

$$\int_{Q_t} (u_{xx} - u_t) dx d\tau = 0.$$

- Green's Theorem \Rightarrow

$$\oint_{\partial Q_t} [u_x d\tau + u dx] = 0.$$

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$$\int_{(0,0)}^{(0,t)} \left[\underbrace{u_x}_{g(\tau)} d\tau + \underbrace{u}_{=0} dx \right] = \int_0^t g(\tau) d\tau. \quad (5)$$

$$\int_{(0,t)}^{(s(t),t)} \left[\underbrace{u_x}_{=0} d\tau + u dx \right] = \int_0^{s(t)} u(x, t) dx. \quad (6)$$

$$\int_{(s(t),t)}^{(b,0)} \left[\underbrace{u_x}_{=-\dot{s}(\tau)} d\tau + \underbrace{u}_{=0} dx \right] = \int_0^t \dot{s}(\tau) d\tau = s(t) - b. \quad (7)$$

$$\int_{(b,0)}^{(0,0)} \left[\underbrace{u_x}_{=0} d\tau + \underbrace{u}_{=h(x)} dx \right] = - \int_0^b h(x) dx. \quad (8)$$

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Let $u \in C^{2,1}(Q_T) \cap C(\overline{Q_T})$ be a solution of $u_{xx} - u_t = 0$ in Q_T .

- **Strong version:** if u has its maximum [minimum] on $\{\overline{Q_T} \setminus \partial_P Q_T\}$, then u is constant in $\overline{Q_T}$.

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Positivity of the temperature and the interface velocity

Proposition

For any solution of **our** one-phase Stefan problem

- 1 $u \geq 0$;
- 2 $\dot{s} \geq 0$.

- 1
 - BC's, sign restrictions $\Rightarrow \min_{\partial_P Q_T} u = 0$.
 - Maximum principle (the strong version) \Rightarrow

$$\min_{\overline{Q_T}} u = \min_{\partial_P Q_T} u = 0 \Rightarrow u \geq 0 \text{ in } \overline{Q_T}.$$

- 2 $u \geq 0 \in \overline{Q_T}$ and $x < s(t) \Rightarrow$

$$s'(t) = - \lim_{x \rightarrow s(t)^-} \frac{u(x, t) - u(s(t), t)}{x - s(t)} = - \lim_{x \rightarrow s(t)^-} \frac{u(x, t)}{x - s(t)} \geq 0, \forall t.$$

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Existence theorem

We refer to the case

$$s(0) = b > 0 \quad (9)$$

and assume that $f(x)$, $h(x)$ are continuous and nonnegative, and

$$0 \leq h(x) \leq H(b - x) \quad (10)$$

for some constant $H \geq 0$.

Existence theorem

Under the assumptions (9), (10) **our** one-dimensional one-phase Stefan problem has at least one solution.

Proof of the existence theorem

$$\Sigma(A) = \{s \in C[0, T] \mid s(0) = b, 0 \leq \frac{s(t') - s(t'')}{t' - t''} \leq A, 0 \leq t' \leq t'' \leq T\}.$$

$$F : s \in \Sigma \rightarrow \sigma, \text{ where } \dot{\sigma} = -u_x(s(t), t), \sigma(0) = b.$$

Schauder's fixed point theorem

- Suppose Σ is non-empty, compact and convex;
- Suppose $F : \Sigma \rightarrow \Sigma$ is continuous.

Then F has a fixed point in Σ (i.e. $\exists s \in \Sigma : F(s) = s$).

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$$F : s \in \Sigma \rightarrow \sigma, \text{ where } \dot{\sigma} = -u_x(s(t), t), \sigma(0) = b.$$

Schauder's fixed point theorem

- Suppose Σ is non-empty, compact and convex;
- Suppose $F : \Sigma \rightarrow \Sigma$ is continuous.

Then F has a fixed point in Σ (i.e. $\exists s \in \Sigma : F(s) = s$).

The plan of the proof

- 1 Σ is compact and convex;
- 2 $F(\Sigma) \subset \Sigma$;
- 3 F is continuous.

$$0 \leq u(x, t) \leq A(s(t) - x), 0 \leq x \leq s(t).$$

$$A := \max\left(H, \frac{1}{b} \sup_{t \in (0, T)} (f(t))\right).$$

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Continuity of the mapping

F is continuous

$\|\sigma_1 - \sigma_2\| \leq C\|s_1 - s_2\|$, where $\|\cdot\|$ denotes to the sup in $(0, T)$.

- For $s_1, s_2 \in \Sigma(s_1 < s_2)$ we consider u_1, u_2 .
 $u_x(s(t), t) = -\dot{\sigma}(t)$.

- GHB:

$$\int_0^t s_i(\tau) \dot{\sigma}_i(\tau) d\tau - \int_0^{s_i(t)} u_i(x, t) dx + \int_0^b xh(x) dx - \int_0^t f(\tau) d\tau = 0, i = 1, 2.$$

- By subtraction we get

$$\int_0^t s_1(\tau) (\dot{\sigma}_1(\tau) - \dot{\sigma}_2(\tau)) d\tau + \int_0^{s_1(t)} (s_1(\tau) - s_2(\tau)) \dot{\sigma}_2(\tau) d\tau =$$

$$\int_0^{s_1(t)} (u_1(x, t) - u_2(x, t)) dx - \int_{s_1(t)}^{s_2(t)} u_2(x, t) dx.$$

- Integrate the first term by parts:

$$\int_0^{s_1(t)} (u_1(x, t) - u_2(x, t)) dx = s_1(t) (\dot{\sigma}_1(t) - \dot{\sigma}_2(t)) - \int_0^t s_1(\tau) (\dot{\sigma}_1(\tau) - \dot{\sigma}_2(\tau)) d\tau.$$

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Continuity of the mapping

$$s_1(t)(\sigma_1(t) - \sigma_2(t)) = \int_0^t \dot{s}_1(\tau)(\sigma_1(\tau) - \sigma_2(\tau))d\tau - \int_0^t (s_1(\tau) - s_2(\tau))\dot{\sigma}_2(\tau)d\tau +$$

$$\int_0^{s_1(t)} (u_1(x, t) - u_2(x, t))dx - \int_{s_1(t)}^{s_2(t)} u_2(x, t)dx.$$

$$\int_0^t \dot{s}_1(\tau)(\sigma_1(\tau) - \sigma_2(\tau))d\tau \leq A \int_0^t |\sigma_1(\tau) - \sigma_2(\tau)|d\tau \quad (11)$$

$$- \int_0^t (s_1(\tau) - s_2(\tau))\dot{\sigma}_2(\tau)d\tau \leq A \int_0^t |s_1(\tau) - s_2(\tau)|d\tau \quad (12)$$

$$\int_0^{s_1(t)} (u_1(x, t) - u_2(x, t))dx \leq s_1(t) \|s_1 - s_2\| \quad (13)$$

$$- \int_{s_1(t)}^{s_2(t)} u_2(x, t)dx \leq \frac{1}{2} A |s_1^2(t) - s_2^2(t)| \quad (14)$$

Continuity of the mapping

$$s_1(t)(\sigma_1(t) - \sigma_2(t)) = \int_0^t \dot{s}_1(\tau)(\sigma_1(\tau) - \sigma_2(\tau))d\tau - \int_0^t (s_1(\tau) - s_2(\tau))\dot{\sigma}_2(\tau)d\tau + \int_0^{s_1(t)} (u_1(x, t) - u_2(x, t))dx - \int_{s_1(t)}^{s_2(t)} u_2(x, t)dx.$$

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$$A \int_0^t |\mathbf{s}_1(\tau) - \mathbf{s}_2(\tau)| d\tau + \mathbf{s}_1(t) \|\mathbf{s}_1 - \mathbf{s}_2\| + \frac{1}{2} A |\mathbf{s}_1^2(t) - \mathbf{s}_2^2(t)|$$

- $\mathbf{s}_1(t) \leq b + AT, \frac{1}{2}(\mathbf{s}_1(t) + \mathbf{s}_2(t)) \leq b + AT \Rightarrow$

$$|\sigma_1(t) - \sigma_2(t)| \leq \frac{A}{b} \int_0^t |\sigma_1(\tau) - \sigma_2(\tau)| d\tau + \frac{1}{b} [AT + b + AT + A(b + AT)] \|\mathbf{s}_1 - \mathbf{s}_2\|.$$

- Gronwall's inequality \Rightarrow continuity ($\|\sigma_1 - \sigma_2\| \leq C \|\mathbf{s}_1 - \mathbf{s}_2\|$).

Gronwall's inequality

If for $t_0 \leq t \leq t_1$, $\phi(t)$ and $\psi(t)$ are continuous functions such that $\psi(t) \geq 0$ and

$$\phi(t) \leq K + \int_{t_0}^t \psi(s)\phi(s)ds, t_0 \leq t \leq t_1, K - \text{const, then}$$

$$\phi(t) \leq K \exp\left(\int_{t_0}^t \psi(s)ds\right), \text{on } t_0 \leq t \leq t_1.$$

Continuity of the mapping

$$\begin{aligned} \mathbf{s}_1(t)(\sigma_1(t) - \sigma_2(t)) &\leq A \int_0^t |\sigma_1(\tau) - \sigma_2(\tau)| d\tau + \\ A \int_0^t |\mathbf{s}_1(\tau) - \mathbf{s}_2(\tau)| d\tau + \mathbf{s}_1(t) \|\mathbf{s}_1 - \mathbf{s}_2\| &+ \frac{1}{2} A |\mathbf{s}_1^2(t) - \mathbf{s}_2^2(t)| \end{aligned}$$

● $\mathbf{s}_1(t) \leq b + AT, \frac{1}{2}(\mathbf{s}_1(t) + \mathbf{s}_2(t)) \leq b + AT \Rightarrow$

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For further reading



A. Fasano

Mathematical model of some diffusive processes with free boundaries

2005.



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Weak and variational methods for moving boundary problems

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Questions?

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