

Stability and evolution of gravity-driven porous media flows



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Introduction

Upflowing salty groundwater, evaporating completely at the ground surface, leads to the buildup of a **saline boundary layer** below the surface. This boundary layer, if stable, may grow to a finite thickness at equilibrium.

Thus we have a fluid layer that **differs in density** from the fluid below, and the question of the **gravitational stability** of this boundary layer arises. From numerical and Hele-Shaw cell experiments, it appears that the saline boundary layer may be unstable to perturbations, resulting in so called **“salt-fingers”**.

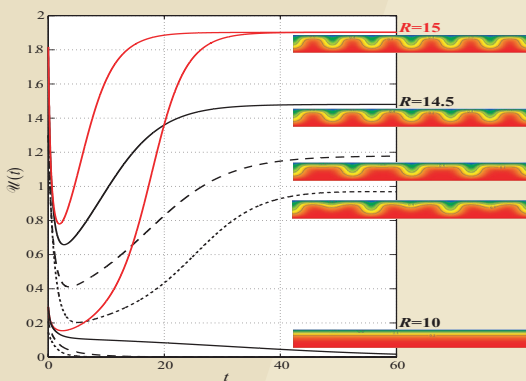
Dimensionless model equations

- Transport equation $\frac{\partial S}{\partial t} + \text{div}(R \mathbf{U} S - \text{grad } S) = 0$,
- Darcy law $\mathbf{U} + \text{grad } P - S \mathbf{e}_z = 0$,
- Fluid incompressibility $\text{div } \mathbf{U} = 0$,

subject to suitable boundary- and initial conditions. The bifurcation parameter R is usually referred to as the system **Rayleigh number**. The **ground state** solution is characterized by the uniform (constant) flow \mathbf{U}_0 and the equilibrium one-dimensional boundary layer $S_0(z)$.

Questions: Under what conditions is the ground state stable/unstable, and what happens when it becomes unstable ?

Growing instabilities and pattern formation



FEM simulations of the full model. Above a certain critical Rayleigh number the system bifurcates to a convective regime. The shape and number of fingers depend on the initial conditions.

Reduction to a lower-order dynamical system

Claim: dynamics of the fully nonlinear problem can be captured by a lower-order model. Idea:

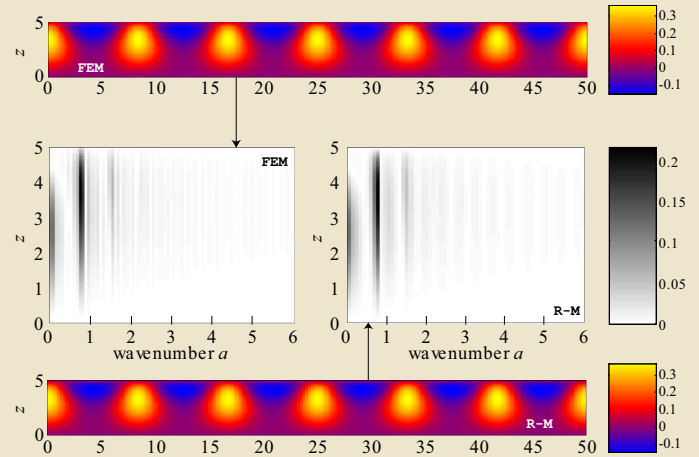
- prescribe the patterns (e.g. rolls, hexagons, ...) in the (x, y) -plane via planform functions having certain (dynamically active) wavenumbers;
- use eigenfunctions of the linearised problem for the expansion in the z -direction;
- Galerkin-Eckhaus method: project the fully nonlinear model onto this pattern expansion.

This gives the system of nonlinear ODE's:

$$a_j \frac{dA_j(t)}{dt} = \sum_{k=1}^N b_{jk} A_k(t) + \sum_{k=1}^N \sum_{l=1}^N c_{jkl} A_k(t) A_l(t),$$

where A_j denotes the amplitude of the j -th mode in the pattern expansion. This equation is sometimes called the **Landau equation** or amplitude equation.

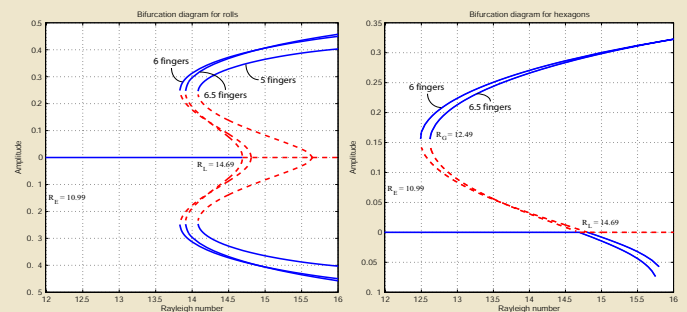
The dynamically active eigenmodes are not *a priori* known. However, using Fourier analysis one obtains detailed information about these active modes.



(Top figure) 2D FEM numerical simulation of a perturbation pattern. The three active wavenumbers in the FEM simulations are used for the order reduction. As to be expected, only these three horizontal modes plus five eigenfunctions in z -direction represent the complete pattern (bottom figure). The system Rayleigh number for both cases is given by $R = 14.5$.

Benefit reduced model: Bifurcation analysis with the reduced model is from a numerical point of view cheaper (3D patterns !) and gives more information about the stability of the steady-states:

- Roll patterns
- Hexagonal patterns



Blue depicts stable branches, the dashed red ones unstable. The rolls bifurcate subcritically while the hexagonal patterns bifurcate transcritically. Pattern interaction will probably lead to a combination of both bifurcation diagrams.

Future developments

- Branch following for larger Rayleigh numbers
- Pattern interaction: rolls with hexagons, squares etc.
- Stochastic determination of the attraction basins

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