

Majorana Algebra for the Hoffman–Singleton Graph

Andries E. Brouwer and Alexander A. Ivanov^{1 2 3}

March 14, 2022

¹Imperial College London, London, UK, a.ivanov@ic.ac.uk

²Three Gorges Mathematical Research Center, Yichang, Hubei, China

³Institute for System Analysis ERC, CSC RAS, Moscow, Russia

Abstract

Majorana theory is an axiomatic tool for studying the Monster group M and its subgroups through the 196 884-dimensional Conway–Griess–Norton algebra. The theory was introduced by A. A. Ivanov in 2009 and since then it experienced a remarkable development including the classification of Majorana representations for small (and not so small) groups. The group $U_3(5)$ is (isomorphic to) the socle of the centralizer in M of a subgroup of order 25. The involutions of this $U_3(5)$ -subgroup are $2A$ -involutions in the Monster. Therefore, $U_3(5)$ possesses a Majorana representation (based on the embedding in the Monster). We prove that this is the unique Majorana representation of $U_3(5)$, calculate its dimension, which is 798, and obtain a description in terms of the Hoffman–Singleton graph of which the automorphism group has $U_3(5)$ as an index 2 subgroup.

1 The Monster and Majorana

The Monster group, which is the largest and most famous sporadic simple group, has its minimal complex representation of dimension 196 883. This number was noticed by J. McKay in the 1970's to be one less than the linear coefficient of the modular invariant $J(q)$, making the start of the Monstrous Moonshine. The underlying vector space, as shown by S. P. Norton in the early 1970's, carries invariant inner and algebra products. This algebra was more explicitly described by R. L. Griess [6] when constructing the Monster in 1980. Later the construction was reviewed and improved in various ways by J. H. Conway [3]. In particular Conway adjoined to the algebra an identity and defined $2A$ -axes associated with $2A$ -involutions in the Monster. The $2A$ -axis $a(t)$ associated with an involution t is an idempotent in the 2-dimensional space

$$C_{V_M}(C_M(t)), \text{ where } C_M(t) \cong 2 \cdot BM,$$

BM standing for the Baby Monster sporadic simple group. Among other idempotents in this 2-space the $2A$ -axis is characterized by having 1-eigenvector with multiplicity 1. The 196 884-dimensional algebra is called the Conway–Griess–Norton algebra or simply the Monster algebra and is denoted by V_M .

In [7] essential properties of $2A$ -axes in the Monster algebra were axiomatised in the following way.

Let V be a real vector space equipped with a bilinear form $(\ , \)$ and an algebra product \cdot .

- (M1) $(\ , \)$ is a symmetric positive-definite bilinear form on V that associates with \cdot in the sense that $(u, v \cdot w) = (u \cdot v, w)$ for all $u, v, w \in V$, and \cdot is a bilinear commutative non-associative algebra product on V ;
- (M2) the Norton inequality holds, so that $(u \cdot u, v \cdot v) \geq (u \cdot v, u \cdot v)$ for all $u, v \in V$.

A vector $a \in V$ is said to be a *Majorana axis* if it satisfies the following five conditions (M3) to (M7), where $\text{ad}(a) : v \mapsto a \cdot v$ is the adjoint operator of a on V .

- (M3) $(a, a) = 1$ and $a \cdot a = a$, so that a is an idempotent of length 1;
- (M4) $\text{ad}(a)$ is semi-simple with spectrum $Sp = \{1, 0, \frac{1}{4}, \frac{1}{32}\}$;

$$V = V_1^{(a)} \oplus V_0^{(a)} \oplus V_{\frac{1}{4}}^{(a)} \oplus V_{\frac{1}{32}}^{(a)},$$

where $V_\mu^{(a)} = \{v \mid v \in V, a \cdot v = \mu v\}$ is the set of μ -eigenvectors of $\text{ad}(a)$ on V ;

- (M5) $V_1^{(a)} = \{\lambda a \mid \lambda \in \mathbb{R}\}$;
- (M6) the linear transformation $\tau(a)$ of V defined via

$$\tau(a) : u \mapsto (-1)^{32\mu} u$$

for $u \in V_\mu^{(a)}$ with $\mu = 1, 0, \frac{1}{4}, \frac{1}{32}$, preserves the algebra product (i.e. $u^{\tau(a)} \cdot v^{\tau(a)} = (u \cdot v)^{\tau(a)}$ for all $u, v \in V$). The automorphism $\tau(a)$ is called the *Majorana involution* associated with the Majorana axis a ;

(M7) if $V_+^{(a)}$ is the centralizer of $\tau(a)$ in V , so that $V_+^{(a)} = V_1^{(a)} \oplus V_0^{(a)} \oplus V_{\frac{1}{4}}^{(a)}$, then the linear transformation $\sigma(a)$ of $V_+^{(a)}$ defined via

$$\sigma(a) : u \mapsto (-1)^{4\mu}u$$

for $u \in V_\mu^{(a)}$ with $\mu = 1, 0, \frac{1}{4}$ preserves the restriction of the algebra product to the subalgebra $V_+^{(a)}$.

The conditions (M1) to (M7) imply that the eigenspaces $V_\mu^{(a)}$ of the adjoint action of a satisfy the fusion rules described in the following table:

Sp	1	0	$\frac{1}{4}$	$\frac{1}{32}$
1	1	0	$\frac{1}{4}$	$\frac{1}{32}$
0	0	0	$\frac{1}{4}$	$\frac{1}{32}$
$\frac{1}{4}$	$\frac{1}{4}$	$\frac{1}{4}$	1, 0	$\frac{1}{32}$
$\frac{1}{32}$	$\frac{1}{32}$	$\frac{1}{32}$	$\frac{1}{32}$	1, 0, $\frac{1}{4}$

Table 1. Fusion Rules.

The meaning of the fusion rules is the inclusion

$$V_\lambda^{(a)} \cdot V_\mu^{(a)} \subseteq \bigoplus_{\nu \in Sp(\lambda, \mu)} V_\nu^{(a)}$$

where $\lambda, \mu \in Sp$ and $Sp(\mu, \lambda)$ is the (λ, μ) -entry in Table 1.

Definition 1. Let $(V, (,), \cdot)$ be a triple satisfying (M1) and (M2), let A be a set of Majorana axes in V satisfying (M3) to (M7), and let G be the subgroup of the automorphism group of $(V, (,), \cdot)$ generated by the Majorana involutions associated with the axes in A . Then the triple $(V, (,), \cdot)$ is called a Majorana algebra, and the quintuple $(V, (,), \cdot, A, G)$ is called a Majorana representation of G .

If $(V_M, (,), *)$ is the full name of the Monster algebra and $2A$ denotes the set of $2A$ -axes in this algebra, then $(V_M, (,), *, 2A, M)$ is a Majorana representation of the Monster. There is a 1-1 correspondence between $2A$ -involutions t in the monster M and $2A$ -axes a in $2A$ such that if $\phi: M \rightarrow GL(V_M)$ is the given representation of M on V_M , then $\phi(t) = \tau(a)$. It follows that any subgroup G of M generated by a set of $2A$ -involutions possesses at least one Majorana representation.

The above definitions were motivated by a theorem proved by S. Sakuma in [18] making use of earlier results by M. Miyamoto. In Majorana terms this theorem as stated and proved in [11] sounds as follows.

Theorem 2. (Sakuma) *Let $(V, (\ , \), \cdot)$ be a Majorana algebra, let $A = \{a_0, a_1\}$ for $a_0 \neq a_1$ be Majorana axes, and let G be the dihedral subgroup D_{2n} generated by $\tau(a_0)$ and $\tau(a_1)$, where n is the order of the product of the generators. Then $n \leq 6$ and there are at most eight possibilities for the isomorphism type of the subalgebra generated by A in the Majorana representation $(V, (\ , \), \cdot, A, G)$ of G .*

Type	Basis	Products and angles
2A	a_0, a_1, a_ρ	$a_0 \cdot a_1 = \frac{1}{2^3}(a_0 + a_1 - a_\rho), a_0 \cdot a_\rho = \frac{1}{2^3}(a_0 + a_\rho - a_1)$ $(a_0, a_1) = (a_0, a_\rho) = (a_1, a_\rho) = \frac{1}{2^3}$
2B	a_0, a_1	$a_0 \cdot a_1 = 0, (a_0, a_1) = 0$
3A	$a_{-1}, a_0, a_1,$ u_ρ	$a_0 \cdot a_1 = \frac{1}{2^5}(2a_0 + 2a_1 + a_{-1}) - \frac{3^3 \cdot 5}{2^{11}}u_\rho$ $a_0 \cdot u_\rho = \frac{1}{3^2}(2a_0 - a_1 - a_{-1}) + \frac{5}{2^5}u_\rho$ $u_\rho \cdot u_\rho = u_\rho$ $(a_0, a_1) = \frac{13}{2^8}, (a_0, u_\rho) = \frac{1}{2^2}, (u_\rho, u_\rho) = \frac{2^3}{5}$
3C	a_{-1}, a_0, a_1	$a_0 \cdot a_1 = \frac{1}{2^6}(a_0 + a_1 - a_{-1}), (a_0, a_1) = \frac{1}{2^6}$
4A	$a_{-1}, a_0, a_1,$ a_2, v_ρ	$a_0 \cdot a_1 = \frac{1}{2^6}(3a_0 + 3a_1 + a_2 + a_{-1} - 3v_\rho)$ $a_0 \cdot v_\rho = \frac{1}{2^4}(5a_0 - 2a_1 - a_2 - 2a_{-1} + 3v_\rho)$ $v_\rho \cdot v_\rho = v_\rho, a_0 \cdot a_2 = 0$ $(a_0, a_1) = \frac{1}{2^5}, (a_0, a_2) = 0, (a_0, v_\rho) = \frac{3}{2^3}, (v_\rho, v_\rho) = 2$
4B	$a_{-1}, a_0, a_1,$ a_2, a_{ρ^2}	$a_0 \cdot a_1 = \frac{1}{2^6}(a_0 + a_1 - a_{-1} - a_2 + a_{\rho^2})$ $a_0 \cdot a_2 = \frac{1}{2^3}(a_0 + a_2 - a_{\rho^2})$ $(a_0, a_1) = \frac{1}{2^6}, (a_0, a_2) = (a_0, a_{\rho^2}) = \frac{1}{2^3}$
5A	$a_{-2}, a_{-1}, a_0,$ a_1, a_2, w_ρ	$a_0 \cdot a_1 = \frac{1}{2^7}(3a_0 + 3a_1 - a_2 - a_{-1} - a_{-2}) + w_\rho$ $a_0 \cdot a_2 = \frac{1}{2^7}(3a_0 + 3a_2 - a_1 - a_{-1} - a_{-2}) - w_\rho$ $a_0 \cdot w_\rho = \frac{7}{2^{12}}(a_1 + a_{-1} - a_2 - a_{-2}) + \frac{7}{2^5}w_\rho$ $w_\rho \cdot w_\rho = \frac{5^2 \cdot 7}{2^{19}}(a_{-2} + a_{-1} + a_0 + a_1 + a_2)$ $(a_0, a_1) = \frac{3}{2^7}, (a_0, w_\rho) = 0, (w_\rho, w_\rho) = \frac{5^3 \cdot 7}{2^{19}}$
6A	$a_{-2}, a_{-1}, a_0,$ a_1, a_2, a_3 a_{ρ^3}, u_{ρ^2}	$a_0 \cdot a_1 = \frac{1}{2^6}(a_0 + a_1 - a_{-2} - a_{-1} - a_2 - a_3 + a_{\rho^3}) + \frac{3^2 \cdot 5}{2^{11}}u_{\rho^2}$ $a_0 \cdot a_2 = \frac{1}{2^5}(2a_0 + 2a_2 + a_{-2}) - \frac{3^3 \cdot 5}{2^{11}}u_{\rho^2}$ $a_0 \cdot u_{\rho^2} = \frac{1}{3^2}(2a_0 - a_2 - a_{-2}) + \frac{5}{2^5}u_{\rho^2}$ $a_0 \cdot a_3 = \frac{1}{2^3}(a_0 + a_3 - a_{\rho^3}), a_{\rho^3} \cdot u_{\rho^2} = 0, (a_{\rho^3}, u_{\rho^2}) = 0$ $(a_0, a_1) = \frac{5}{2^8}, (a_0, a_2) = \frac{13}{2^8}, (a_0, a_3) = \frac{1}{2^3}$

Table 2. Norton–Sakuma Algebras.

Each of the eight algebras in Sakuma’s theorem are subalgebras in the Monster algebra, their explicit forms were computed by S. P. Norton in [16] and given in Table 2 with respect

to the Majorana scaling. The name of the algebra generated by a_0 and a_1 is the conjugacy class of the Monster containing the product $\tau(a_0)\tau(a_1)$.

Therefore, Sakuma's theorem provides the classification of Majorana representations of the dihedral groups. On progress in classifying Majorana representations of further groups we refer the reader to surveys [9], [10].

Our main result is the following.

Theorem 1. *The group $U_3(5)$ has a unique Majorana representation satisfying (M8) below. This representation has dimension 798, it is 2-closed, is spanned by Majorana and 3A-axes and is based on an embedding into the Monster.*

Here the *dimension* of a Majorana representation $(V, (\cdot, \cdot), \cdot, A, G)$ is the vector space dimension of the subalgebra $\langle\langle A \rangle\rangle$ of V generated by A . The representation is called *i-closed*, when $\langle\langle A \rangle\rangle$ is spanned by products of at most i elements of A .

A *3A-axis* is a vector with the role of u_ρ in a type 3A subalgebra (an idempotent of squared length $\frac{8}{5}$, expressed in the Majorana axes a_{-1}, a_0, a_1 by the first equation in the 3A part of Table 2). Similarly, 4A-axes and 5A-axes are vectors with the role of v_ρ and w_ρ , respectively, in type 4A (5A) subalgebras.

Condition (M8) is

- (M8) The vectors a_ρ, a_{ρ^2} and a_{ρ^3} in type 2A, 4B and 6A algebras, respectively, are Majorana axes. The vectors u_ρ, v_ρ, w_ρ in algebras of type 3A, 4A and 5A depend solely on the group element $\rho = \tau(a_0)\tau(a_1)$ (rather than on the whole dihedral group $\langle \tau(a_0), \tau(a_1) \rangle$).

Condition (M8) is satisfied by $(V_M, (\cdot, \cdot), *, 2A, M)$ by [16]. In our $U_3(5)$ setting this condition will allow us to identify 3A-axes with subgroups of order 3. Note that condition (M8) implies conditions (2A) and (3A) in [11].

2 On the $U_3(5)$ group

In this section we summarise the required properties of the group $U_3(5)$. They can be deduced from the information in the relevant section of the ATLAS [2] and the properties of the Hoffman–Singleton graph found in [1], §10.19.

- (P1) $U_3(5)$ is a simple group of order $126\,000 = 2^4 \cdot 3^2 \cdot 5^3 \cdot 7$ with a unique class of involutions. Its Schur multiplier is of order 3 and the outer automorphism group is isomorphic to S_3 .
- (P2) $U_3(5)$ contains three classes of subgroups isomorphic to A_7 , which are maximal and the classes are transitively permuted by the outer automorphisms.
- (P3) The action of $U_3(5)$ on the cosets of a subgroup A_7 preserves a structure of the Hoffman–Singleton graph, which is the unique strongly regular graph with parameters $v = 50, k = 7, \lambda = 0, \mu = 1$. The action of $U_3(5)$ on this graph has rank 3.
- (P4) The action of an A_7 -subgroup on the cosets of an A_7 subgroup from a different class has two orbits with lengths 15 and 35 and stabilizers $L_3(2)$ and $(S_3 \times S_4)^+$, the latter being the normalizer of a subgroup of order 3 in both A_7 's.

- (P5) If t is an involution in $U_3(5)$, then the fixed vertices of t on the Hoffman–Singleton graph form a Petersen subgraph on which the centralizer $C(t)$ of t in $U_3(5)$ induces an action of S_5 with kernel $\langle t \rangle$. The whole $C(t)$ is a non-split extension of $\langle t \rangle$ by S_5 in which a transposition of S_5 lifts to an involution. $C(t)$ is the unique index 2 subgroup of $GL_2(5)$ with the class of 20 non-central involutions. $C(t)$ is maximal in $U_3(5)$.
- (P6) The action of $U_3(5)$ on its 525 involutions has rank 8, with suborbits of sizes 1, 20, 120, 120, 48, 48, 48, corresponding to product orders 1, 2, 3, 4, 6, 5, 5, 5, respectively. The action of $U_3(5).S_3$ has rank 6, the three suborbits of size 48 fuse into a single suborbit of size 144.
- (P7) The Monster group contains a maximal 5-local subgroup

$$N(5A^2) \cong (5^2 : 4 \cdot 2^2 \times U_3(5)) : S_3$$

where

$$N(5A) \cong (D_{10} \times HN) \cdot 2$$

(see [19]).

- (P8) The involutions in the $U_3(5)$ -subgroup in $N(5A^2)$ are $2A$ -involutions in the Monster by Table 5 in [17].

3 An upper bound

Property (P8) implies that $U_3(5)$ possesses a Majorana representation based on embedding into the Monster. It would be very hard to deduce any exact information on this representation, like the dimension, by pre-Majorana methods. The characterization [5] of the Majorana representation of the Harada–Norton group is not explicit enough either. What one can do is to get an upper bound on the dimension of this particular representation. The procedure is rather standard.

Lemma 3. *The following assertions hold:*

- (i) $N_M(U_3(5))/U_3(5) \cong 5^2 : (SL_2(3) * Z_4)$;
- (ii) $C_M(U_3(5)) \cong 5^2 : (Q_8 * Z_4)$.

Proof. Part (i) follows from (P7), and (ii) is immediate from (i). □

It is clear that the Majorana subalgebra of $U_3(5)$ in the Monster algebra is contained in

$$C_{V_M}(C_M(U_3(5))).$$

If b is the dimension of the above centralizer, then the dimension of the Majorana representation of $U_3(5)$ in V_M is at most b . On the other hand, b can be calculated by restricting the character of M on V_M to $C_M(U_3(5))$ and counting the number of trivial components.

The character table of $C_M(U_3(5))$ was found on the internet by William Giuliano to whom we are very thankful. The fusion of classes was recovered via the embedding

$$C_M(U_3(5)) \leq C_M(A_5) \cong A_{12}.$$

A_{12}	M	A_{12}	M	A_{12}	M	A_{12}	M
(1^{12})	1A	$(4, 2)$	4B	$(6, 2)$	6C	$(4, 3, 2)$	12C
(2^2)	2A	$(4, 2^3)$	4B	(7)	7A	$(4, 3^2, 2)$	12C
(2^6)	2A	(5)	5A	$(8, 2)$	8B	(6, 4)	12C
(2^4)	2B	(5^2)	5A	$(8, 4)$	8B	$(7, 2^2)$	14A
(3)	3A	$(3, 2^2)$	6A	(9)	9A	(5, 3)	15A
(3^2)	3A	$(3^2, 2^2)$	6A	$(9, 3)$	9A	$(5, 3^2)$	15A
(3^4)	3A	$(6, 2^3)$	6A	$(5, 2^2)$	10A	$(5, 4, 2)$	20B
(3^3)	3B	(6^2)	6A	$(10, 2)$	10A	(7, 3)	21A
(4^2)	4A	$(6, 3, 2)$	6B	(11)	11A	$(5, 3, 2^2)$	30B
$(4^2, 2^2)$	4A	$(3, 2^4)$	6C	$(4^2, 3)$	12A	(7, 5)	35A

Table 3. Fusion of A_{12} -classes into the Monster.

The fusion of A_{12} -classes into the Monster is well known, appeared for instance in [14] and we present it here in Table 3 for future reference.

Since 5^2 is a Sylow 5-subgroup of A_{12} and $N_{A_{12}}(5^2)$ is the intersection with A_{12} of $N_{S_{12}}(5^2) \cong (F_{20} \wr 2) \times S_2$ and $C_M(U_3(5))$ as in Lemma 3(ii) is rather visible inside this normalizer, we obtain the final result of these calculations.

Lemma 4.

$$\dim C_{V_M}(C_M(U_3(5))) = 990.$$

□

4 Subrepresentations and relations

We start this section by presenting the list of eigenvectors of a Majorana axis a_0 inside Norton–Sakuma algebras. This list is well known [11] and can be deduced from the product rules. In order to save space, we write $e_1 := a_1 - a_{-1}$ and $e_2 := a_2 - a_{-2}$.

Type	0	$\frac{1}{4}$	$\frac{1}{32}$
2A	$a_1 + a_\rho - \frac{1}{2^2}a_0$	$a_1 - a_\rho$	
2B	a_1		
3A	$u_\rho - \frac{2 \cdot 5}{3^3}a_0 + \frac{2^5}{3^3}(a_1 + a_{-1})$	$u_\rho - \frac{2^3}{3^2 \cdot 5}a_0 - \frac{2^5}{3^2 \cdot 5}(a_1 + a_{-1})$	e_1
3C	$a_1 + a_{-1} - \frac{1}{2^5}a_0$		e_1
4A	$v_\rho - \frac{1}{2}a_0 + 2(a_1 + a_{-1}) + a_2, \quad a_2$	$v_\rho - \frac{1}{3}a_0 - \frac{2}{3}(a_1 + a_{-1}) - \frac{1}{3}a_2$	e_1
4B	$a_1 + a_{-1} - \frac{1}{2^5}a_0 - \frac{1}{2^3}(a_{\rho^2} - a_2),$ $a_2 + a_{\rho^2} - \frac{1}{2^2}a_0$	$a_2 - a_{\rho^2}$	e_1
5A	$w_\rho + \frac{3}{2^9}a_0 - \frac{3 \cdot 5}{2^7}(a_1 + a_{-1}) - \frac{1}{2^7}(a_2 + a_{-2}),$ $w_\rho - \frac{3}{2^9}a_0 + \frac{1}{2^7}(a_1 + a_{-1}) + \frac{3 \cdot 5}{2^7}(a_2 + a_{-2})$	$w_\rho + \frac{1}{2^7}(a_1 + a_{-1} - a_2 - a_{-2})$	$e_1,$ e_2
6A	$u_{\rho^2} + \frac{2}{3^2 \cdot 5}a_0 - \frac{2^4}{3^2 \cdot 5}(a_1 + a_{-1}) -$ $\frac{2^3}{3^2 \cdot 5}(a_2 + a_{-2} + a_3 - a_{\rho^3}),$ $a_3 + a_{\rho^3} - \frac{1}{2^2}a_0, u_{\rho^2} - \frac{2 \cdot 5}{3^3}a_0 + \frac{2^5}{3^3}(a_2 + a_{-2})$	$u_{\rho^2} - \frac{2^3}{3^2 \cdot 5}a_0 -$ $\frac{2^3}{3^2 \cdot 5}(a_2 + a_{-2} + a_3 - a_{\rho^3}),$ $a_3 - a_{\rho^3}$	$e_1,$ e_2

Table 4. Eigenvectors of Norton–Sakuma algebras.

Next we formulate and prove an important special case of the *resurrection principle* [11]. In what follows $\langle\langle X \rangle\rangle$ denotes the subalgebra generated by a set X . We shall write ab instead of $a \cdot b$.

Lemma 5. *Let $(V, (,), \cdot, A, G)$ be a Majorana representation of a group G . Suppose that b_0, b_1, b_2 are Majorana axes such that*

$$B_1 := \langle\langle b_0, b_1 \rangle\rangle \text{ and } B_2 := \langle\langle b_0, b_2 \rangle\rangle$$

are 3A-algebras with 3A-axes u_1 and u_2 , respectively. Then the product $u_1 u_2$ is explicitly expressible in terms of products of Majorana axes and products of Majorana axes with a 3A-axis, and similarly for the inner product (u_1, u_2) .

Proof. Let α_1 be the 0-eigenvector of $\text{ad}(b_0)$ in B_1 , α_2 and β_2 the 0- and $\frac{1}{4}$ -eigenvectors of that operator in B_2 normalized as in Table 4. Then by the fusion rule $\alpha_1 \alpha_2$ is a 0-eigenvector, while $\alpha_1 \beta_2$ is a $\frac{1}{4}$ -eigenvector of $\text{ad}(b_0)$. These eigenvectors have $u_1 u_2$ as the leading terms and the remaining terms are products of two Majorana axes and of a Majorana axis with u_1 or u_2 . Now $u_1 u_2$ can be found from

$$b_0(\alpha_1 \alpha_2 - \alpha_1 \beta_2) = -\frac{1}{4} \alpha_1 \beta_2 = -\frac{1}{4} u_1 u_2 + \dots$$

For the inner product we just apply $0 = (\alpha_1, \beta_2) = (u_1, u_2) + \dots$ □

Lemma 6. *Let G be the semidirect product of an elementary abelian group of order 9 generated by elements x and y , and a group of order 2 generated by t which inverts both x and y . Then G possesses a unique Majorana representation satisfying (M8) such that any two Majorana axes generate a 3A subalgebra. Furthermore, if b_1, \dots, b_9 and u_1, \dots, u_4 are the Majorana and 3A-axes in this representation, then*

$$45 \sum_{i=1}^4 u_i - 32 \sum_{j=1}^9 b_j = 0$$

The relations in Lemma 6 were called in [8] *Pasechnik relations* and this terminology became standard, although the referee of [8] pointed out that these relations were known for a long time in the theory of Vertex Operator Algebras.

The Majorana representation of A_7 based on the embedding into the Monster was characterised in [8].

Lemma 7. *The group A_7 possesses a unique Majorana representation satisfying (M8). This representation has dimension 196. It is spanned by 105 Majorana axes, which are linearly independent and 140 3A-axes associated with order 3 elements of cyclic type 3^2 . The latter are subject to 49 linearly independent relations of which 35 are Pasechnik relations and 14 are Faradzev relations. All the 5A-axes in the representation are linear combinations of the Majorana and 3A-axes.* □

An explicit form of Faradzev relation was obtained by Clara Franchi and Mario Mainardis [4] as an alternating sum of some 48 3A-axes. This form played a crucial role in some early stages of our project.

The information in the following lemma was obtained by J. McInroy by the expansion algorithm for Majorana algebra described in [15]. We are extremely thankful to Justin for his sharing this information with us.

Lemma 8. *The group $C = 2 \cdot S_5$, which is the centralizer of an involution in $U_3(5)$, possesses a unique Majorana representation. This representation has dimension 31, and is spanned by twenty-one Majorana and ten 3A-axes. Furthermore, if ρ is an element of order 3 in C , then*

- (i) *for an involution t in C which generates with ρ a $GL_2(3)$ -subgroup, we have $(u_\rho, a_t) = \frac{1}{36}$;*
- (ii) *for an element σ of order 3 in C which generates with ρ an $SL_2(3)$ -subgroup, we have $(u_\rho, u_\sigma) = \frac{8}{81}$;*
- (iii) *for an element π of order 3 in C , which generates with ρ an $SL_2(5)$ -subgroup, we have $(u_\rho, u_\pi) = \frac{16}{405}$;*

□

5 Shape and 1-closure

We start our construction of a Majorana representation of $G = U_3(5)$ by setting a vector space with a set A of 525 vectors a_t indexed by the involutions $t \in T$, where T is the class of involutions in G . In order to proceed we need to find the *shape* of the representation we are aiming at, which is a map sh from the set of dihedral subgroups in G into the set of Norton–Sakuma algebras such that

$$\langle\langle a_t, a_s \rangle\rangle \cong sh(\langle t, s \rangle_G).$$

Lemma 9. *The shape sh of a representation of $G \cong U_3(5)$ is uniquely determined and the set of images of sh is*

$$\{2A, 3A, 4B, 5A, 6A\}$$

Proof. There is only one algebra for D_{12} and one for D_{10} . By (P6) every subgroup D_6 is contained in a D_{12} -subgroup. Since a 6A algebra contains 3A- but not 3C-subalgebras, the image of a D_6 -subgroup is 3A. Similarly, since 6A contains 2A- but not 2B-subalgebras, the image of a D_4 -subgroup is 2A. Finally 4A contains a 2B-subalgebra, which we do not have, therefore, the image of D_8 is 4B. □

Lemma 9 enables us to determine the form on the linear span of A .

Corollary 10. *The inner product (a_t, a_s) is equal to 1, $\frac{1}{8}$, $\frac{13}{256}$, $\frac{1}{64}$, $\frac{3}{128}$ and $\frac{5}{256}$ when $a(st)$ is equal to 1, 2, 3, 4, 5 and 6, respectively.* □

Computationally we obtain the following.

Lemma 11. *The 525×525 Gram matrix $\Gamma(A) = \|(a_t, a_s)\|$ has full rank.* □

Thus the 1-closure, which is the subspace spanned by the Majorana generators of a representation of $U_3(5)$, is 525-dimensional with uniquely determined inner product on it.

6 2-closure

Next we consider the 2-closure, which is the space generated by the Majorana generators together with their pairwise products. By Lemma 9 the 2-closure is spanned by the Majorana generators together with 3A- and 5A-axes. The following lemma takes care of the 5A-axes.

Lemma 12. *Every 5A-axis of a Majorana representation of $U_3(5)$ is a linear combination of the Majorana generators and 3A-axes in the 2-closure.*

Proof. The result follows from Lemma 7 since there are three $U_3(5)$ -orbits on D_{10} -subgroups by (P6) and three orbits on the A_7 -subgroups by (P2) with respective inclusion. \square

Lemma 13. *The 2-closure of a Majorana representation of $U_3(5)$ is spanned by the 525 Majorana generators and 1750 3A-axes indexed by the subgroups of order 3 in $U_3(5)$.*

Proof. By Lemmas 9 and 12 we should only consider 3A-axes. By (P6) there are

$$525 \cdot 120/6 = 10500$$

dihedral groups of order 6 in $U_3(5)$, six for every subgroup of order 3. Comparing the orders of normalizers we conclude that the normalizer of a 3-subgroup is contained in some A_7 -subgroup. So the glueing of 3A-subalgebras already takes place in A_7 -subrepresentations (cf. Lemma 7). \square

We denote by

$$U = \{u_\rho \mid \rho \in U_3(5), \rho^3 = 1\}$$

the set of 3A-axes in the representation, understanding that $u_\rho = u_{\rho^{-1}}$.

Next we are aiming to determine the Gram matrix of the set $A \cup U$ and by calculating its rank decide on the dimension of the 2-closure. The following result was obtained computationally.

Lemma 14. *The pairs of Majorana 2A- and 3A-axes in a representation of $U_3(5)$ are as described in Table 5, where T_H is the number of involutions generating a group H of a given isomorphism type together with a fixed order 3-subgroup generated by ρ .* \square

$ T_H $	$(t\rho)^M$	$H = \langle t, \rho \rangle$	(a_t, u_ρ)
3	6A	C_6	0
18	2A	S_3	$\frac{1}{4}$
36	3A	A_4	$\frac{1}{9}$
108	4B	S_4	$\frac{1}{36}$
36	8C	$GL_2(3)$	$\frac{1}{36}$
108	5A	A_5	$\frac{1}{18}$
216	7A	$L_2(7)$	$\frac{1}{24}$
525			

Table 5. (2A, 3A)-pairs in $U_3(5)$

Notice that all (2A, 3A)-pairs inside the Monster were classified by Simon Norton and are presented in Table 3 of [16] (in a scaling different from ours). We do not have a Majorana

version of this classification and can only compare the results and be happy when they are consistent, which is the case here. The entries in the second column showing the class of $(t\rho)$ in the Monster are taken from Norton's table. The inner products can be calculated inside A_7 -subrepresentations as in Lemma 7 for all pairs except those generating $GL_2(3)$, where we apply Lemma 8.

The inner products between $3A$ -axes were also determined computationally.

Lemma 15. *Let ρ be a subgroup of order 3 in $U_3(5)$. Then all the order 3 subgroups σ in $U_3(5)$ are classified by the isomorphism type of the subgroup $H = \langle \rho, \sigma \rangle$ generated by ρ and σ as indicated in Table 6.*

$ U_H $	$ H $	$H = \langle \rho, \sigma \rangle$	(u_ρ, u_σ)
1	3	C_3	$\frac{8}{5}$
12	9	$C_3 \times C_3$	0
36	12	A_4	$\frac{136}{405}$
144	21	F_7^3	$\frac{4}{27}$
18	24	$SL_2(3)$	$\frac{8}{81}$
72	36	$C_3 \times A_4$	$\frac{64}{405}$
54	60	A_5	$\frac{16}{405}$
9	120	$SL_2(5)$	$\frac{16}{405}$
108	168	$L_2(7)$	$\frac{32}{405}$
216	168	$L_2(7)$	$\frac{4}{81}$
216	360	A_6	$\frac{32}{405}$
216	2520	A_7	$\frac{8}{81}$
216	2520	A_7	$\frac{32}{405}$
432	126000	$U_3(5)$	x
1750			

Table 6. Inner products of $3A$ -axes in $U_3(5)$.

In Table 6 U_H is the set of subgroups σ generating with ρ a subgroup isomorphic to H with further subdivisions in the two cases $L_2(7)$ and A_7 . For $L_2(7)$ the inner product is $\frac{32}{405}$ when ρ and σ are normalized by a common involution in H , and $\frac{4}{81}$ otherwise. For A_7 the inner product is $\frac{8}{81}$ when the generating order 3 subgroups in A_7 are both of cycle type 3^2 , and $\frac{32}{405}$ when the generation is by a 3- and a 3^2 -element.

The inner products are calculated in A_7 via Lemma 7 with [8] and in $C(t) \cong 2 \cdot S_5$ as in Lemma 8. In this way, proceeding inductively, we cannot calculate the inner product in the case when ρ and σ generate the whole group G so we put x in the relevant position. The reason of having just one x is justified by the following result obtained computationally.

Lemma 16. *Let ρ be a subgroup of order 3 in $G = U_3(5)$ and let $\Gamma_-(\rho)$ denote the set of order 3 subgroups in $U_3(5)$ which generate with ρ the whole group G . Then*

- (i) $\Gamma_-(\rho)$ is a union of six regular orbits of $N := N_G(\langle \rho \rangle) \cong (S_3 \times S_4)^+$ of order 72;
- (ii) the orbits in (i) are transitively permuted by $N_{\text{Aut}(G)}(\langle \rho \rangle)/N \cong S_3$;

(iii) if $\sigma \in \Gamma_-(\rho)$, then there is no involution in G which normalizes both $\langle \rho \rangle$ and $\langle \sigma \rangle$.

The following lemma was obtained computationally. We sketch the setting.

Let $V^{(2)} := \langle A \cup U \rangle$, the linear span of $A \cup U$, be the 2-closure of the representation, and for a $3A$ -axis $u \in U$ corresponding to a subgroup ρ of order 3, let $V_+(u)$ be the subspace of $V^{(2)}$ spanned by all Majorana axes in A together with all the $3A$ -axes except those in the last row of Table 5 (that is, except for those corresponding to a subgroup σ of order 3 with $\langle \rho, \sigma \rangle = U_3(5)$). Notice that for every $v \in V_+(u)$ the product uv is contained in an A_7 - or $2.S_5$ subrepresentation, thus can be computed and is contained in $V^{(2)}$. Let $\Gamma_-(u)$ be the set of $3A$ -axes corresponding to the last row in Table 5, so that $|\Gamma_-(u)| = 432$. Let

$$\Gamma_-(u) = O_1 \cup O_2 \cup \cdots \cup O_6$$

be the decomposition of $\Gamma_-(u)$ into a disjoint union of $N_G(\langle \rho \rangle)$ -orbits. For $1 \leq i \leq 6$, let F_i be the function on $V^{(2)}$ which is 1 on O_i and 0 on the remaining O_j 's.

Lemma 17. *The following assertions hold:*

- (i) $x = \frac{4}{81}$;
- (ii) $\dim V^{(2)} = 798$;
- (iii) $\dim V_+(u) = 796$;
- (iv) *there is an orthogonal complement $V_-(u)$ of $V_+(u)$ in $V^{(2)}$ spanned by*

$$F_1 + F_2 - F_3 - F_4, \quad -F_1 - F_2 + F_5 + F_6, \quad F_3 + F_4 - F_5 - F_6$$

for some arrangement of the orbits O_i into pairs.

Proof. The left hand side of the relations from an A_7 -subrepresentation are vectors of length zero and they must be zero vectors since the form is positive-definite. In particular they have to be perpendicular to all other vectors, which enabled us to determine x , proving (i). The power space of $A \cup U$ factorized over the linear span of the relations in the three classes A_7 -subrepresentations turned out to be 796-dimensional positive-definite which gives (ii). The assertions (iii) and (iv) were also achieved computationally. \square

It is clear from the above lemma that in order to close the product on $V^{(2)}$ it suffices to show that for a triple of $3A$ -axes u_1, u_2, u_3 such that u_2 and u_3 are in the same regular orbit of $G(u_1)$ on $\Gamma_-(u_1)$, the product

$$u_1(u_2 + u_3)$$

belongs to $V^{(2)}$. This was achieved by a version of the resurrection principle.

Computationally the following was established.

Lemma 18. *Let $u_1 \in U$ correspond to an element ρ and $u_2 \in \Gamma_-(u_1)$ to an element σ . Then there exists an involution t in G , such that $\langle \rho, t \rangle \cong S_3$ and $\langle \sigma, t \rangle \cong S_4$.*

By the above lemma and the shape of the representation of G we have that the subalgebra A_1 generated by u_1 and $a(t)$ is the $3A$ -algebra and the subalgebra A_2 generated by u_2 and $a(t)$ is the 13-dimensional S_4 -algebra of shape $(2A, 3A)$ as described in [11].

We assume that in A_1 $a(t) = a_0$ and $u_1 = u_\rho$ while in A_2 $a(t) = a_{(ij)}$ and $u_2 = u_i$. Then u_j , which is the image of u_i under t is contained with u_i in the same $G(u_1)$ -orbit on $\Gamma_-(u_1)$, since $t \in G(u_1)$. The subgroups of the axes u_k and u_l and normalized by t and therefore, they are in $V_+(u_1)$. Then the product rule in A_2 on p. 2460 in [11] shows that

$$\begin{aligned} \alpha_1 := & u_i + u_j - \frac{1}{8}(u_k - \frac{8}{45}a_{(ij)} - \frac{32}{45}(a_{(il)} + a_{(jl)})) \\ & - \frac{1}{8}(u_l - \frac{8}{45}a_{(ij)} - \frac{32}{45}(a_{(ik)} + a_{(jk)})) \\ & - \frac{1}{18}a_{(ij)} - \frac{8}{45}(a_{(kl)} - a_{(ij)(kl)}) \end{aligned}$$

is a 0-eigenvector of $a_{(ij)}$. Notice that the expressions in first, second and third brackets are $\frac{1}{4}$ -eigenvectors of $a_{(ij)}$ in the algebras $\langle\langle a_{(ij)}, u_k \rangle\rangle$, $\langle\langle a_{(ij)}, u_l \rangle\rangle$ and $\langle\langle a_{(ij)}, a_{(kl)} \rangle\rangle$, respectively, where these algebras are of types $3A$, $3A$ and $2A$, respectively.

Let α_2 and β_2 be 0- and $\frac{1}{4}$ -eigenvectors of $a(t) = a_0$ in the algebra $A_1 \cong 3A$ as in Table 4. Then by the fusion rule

$$\alpha_1\alpha_2 = u_1(u_i + u_j) + v_1$$

is a 0-eigenvector of $a(t)$ for some $v_1 \in V_+(u_1)$, while

$$\alpha_1\beta_2 = u_1(u_i + u_j) + v_2$$

is a $\frac{1}{4}$ -eigenvector of $a(t)$, where $v_2 \in V_+(u_1)$.

Now we apply the *resurrection principle*, Lemma 1.8 in [11], compare Lemma 5.

Consider

$$\alpha_1\alpha_2 - \alpha_1\beta_2 = v_3$$

where v_3 is in $V_+(u_1)$ so we can explicitly calculate

$$a_{(ij)}(\alpha_1\alpha_2 - \alpha_1\beta_2) = a_{(ij)}v_3,$$

although by the eigenvalue properties the above expression is equal to

$$0(\alpha_1\alpha_2) - \frac{1}{4}(\alpha_1\beta_2) = -\frac{1}{4}(u_1(u_i + u_j)) - \frac{1}{4}v_2,$$

which gives the required expression.

Now we know that the product is closed on $V^{(2)}$, so the latter is the whole Majorana algebra supporting the representation, which completes the proof of Theorem 1.

Since α_1 and β_2 are eigenvectors of $a(t)$ with different eigenvalues, they are perpendicular. If we expand the equality $(\alpha_1, \beta_2) = 0$ in terms of the above expressions and substitute the numerical values from Corollary 10, Lemma 14 and Lemma 15, we deduce that

$$(u_1, u_2) = (u_1, u_3) = \frac{4}{81},$$

thus obtaining an independent confirmation of Lemma 17 (i).

Acknowledgement

We are extremely thankful to our colleagues without whom the project could not be completed: William Giuliano for finding the character table of $C_M(U_3(5))$; to Clara Franchi and Mario Mainardis for deducing the explicit form of the Faradzev relations in the A_7 -algebra; to the three of them for most careful proofreading of the draft; and to Justin McInroy for sharing with us information on the representation of $2 \cdot S_5$.

References

- [1] A. E. Brouwer and H. Van Maldeghem, *Strongly Regular Graphs*, Cambridge Univ. Press, Cambridge, 2022.
- [2] J. H. Conway, R. T. Curtis, S. P. Norton, R. A. Parker and R. A. Wilson, *Atlas of Finite Groups*, Clarendon Press, Oxford, 1985.
- [3] J. H. Conway, A simple construction for the Fischer–Griess monster group, *Invent. Math.* **79** (1984), 513–540.
- [4] C. Franchi and M. Mainardis, Relations for A_7 , Note November 2021.
- [5] C. Franchi, A. A. Ivanov and M. Mainardis, The $2A$ -Majorana representation of the Harada-Norton group, *Ars Math. Contemp.* **11** (2016), 175–187.
- [6] R. Griess, The friendly giant, *Invent. Math.* **69** (1982), 1–102.
- [7] A. A. Ivanov, *The Monster Group and Majorana Involutions*, Cambridge Univ. Press, Cambridge, 2009.
- [8] A. A. Ivanov, On Majorana representations of A_6 and A_7 , *Comm. Math. Phys.* **306** (2011), 1–16.
- [9] A. A. Ivanov, The Future of Majorana Theory, pp. 107–118 in: *Group Theory and Computation*, Indian Statistical Institute Series, Springer, Singapore, 2018.
- [10] A. A. Ivanov, The Future of Majorana Theory II, Preprint, 2022.
- [11] A. A. Ivanov, D. V. Pasechnik, Á. Seress and S. Shpectorov, Majorana representations of the symmetric group of degree 4, *J. Algebra* **324** (2010), 2432–2463.
- [12] A. A. Ivanov and Á. Seress, Majorana representations of A_5 , *Math. Z.* **272** (2012), 269–295.
- [13] A. A. Ivanov and S. Shpectorov, Majorana representation of $L_3(2)$, *Adv. Geom.* **12** (2012), 717–738.
- [14] C. S. Lim, From the Monster to Majorana: A study of the $3A$ -axes, PhD thesis, Imperial College London, 2017.
- [15] J. McInroy and S. Shpectorov, An expansion algorithm for constructing axial algebras, *J. Algebra* **550** (2020), 379–409.

-
- [16] S. P. Norton, The Monster algebra: some new formulae, pp. 297–306 in: *Moonshine, the Monster and Related Topics*, Contemp. Math. **193**, AMS, Providence, RI, 1996.
- [17] S. P. Norton, Anatomy of the Monster I, pp. 198–214 in: *The Atlas of Finite Groups: Ten Years On*, LMS Lect. Notes Ser. 249, Cambridge Univ. Press, Cambridge, 1998.
- [18] S. Sakuma, 6-Transposition property of τ -involutions of Vertex Operator Algebras, *International Math. Research Notes* **2007** article rnm030, 19 pages.
- [19] R. A. Wilson, The odd-local subgroups of the Monster, *J. Austral. Math. Soc.* **44** (1988), 1–18.