

2IF55 Semantics and computational models

Recursion—transition systems and higher-order definitions

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J.W. de Bakker & E.P. de Vink, *Control Flow Semantics*
The MIT Press 1996

- Chapter 1: Recursion and Iterations
Section 1.1: Recursion
- Chapter 2: Nondeterminacy
- Chapter 4: Uniform Parallelism
- Chapter 11: Branching Domains at Work

§1.1.3 Denotational semantics

- *program construct denote values*
- *the meaning of a whole
is composed from the meaning of constituents*
- *infinite computation is dealt with by fixed points*

an operator for sequential composition

denotational domain $\mathbb{P}_D = \text{Act}^\infty \setminus \{\epsilon\}$

$;\colon \mathbb{P}_D \times \mathbb{P}_D \xrightarrow{1} \mathbb{P}_D$ unique non-expansive function such that

$$\begin{aligned} ;(a, p) &= a \cdot p \\ ;(a \cdot p', p) &= a \cdot (;(p', p)) \end{aligned}$$

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put $\text{Op} = \mathbb{P}_D \times \mathbb{P}_D \xrightarrow{1} \mathbb{P}_D$ and $\Omega_{;}\colon \text{Op} \rightarrow \text{Op}$

$$\begin{aligned} \Omega_{;}(a, p) &= a \cdot p \\ \Omega_{;}(a \cdot p', p) &= a \cdot (\Omega_{;}(p', p)) \end{aligned}$$

lemma 1.37 $\Omega;$ is $\frac{1}{2}$ -contractive

lemma 1.38 $(p_1; p_2); p_3 = p_1; (p_2; p_3)$

lemma 1.41 $d(p_1; p_2, \bar{p}_1; \bar{p}_2) \leq \max\{ d(p_1, \bar{p}_1), \frac{1}{2}d(p_2, \bar{p}_2) \}$

denotational mapping

put $\text{Sem}_D = \mathcal{L}_{\text{rec}} \rightarrow \mathbb{P}_D$ and $\Psi: \text{Sem}_D \rightarrow \text{Sem}_D$

$$\begin{aligned}\Psi(S)(D|a) &= a \\ \Psi(S)(D|x) &= \Psi(S)(D|D(x)) \\ \Psi(S)(D|s_1; s_2) &= \Psi(S)(D|s_1); S(D|s_2)\end{aligned}$$

lemma 1.42 Ψ is $\frac{1}{2}$ -contractive

denotational semantics $\mathcal{D} = \text{fix}(\Psi)$

lemma 1.43

- $\mathcal{D}(D|(s_1; s_2); s_3) = \mathcal{D}(D|s_1; (s_2; s_3))$
- $\mathcal{D}(D|x) = a^\omega$ if $D(x) = a; x$