

## Oplossingen eindtoets Voortgezette Calculus (2DBN11) februari 2018

Aan deze oplossingen kunnen geen rechten worden ontleend.

1. a) According to the properties of the Laplace transform,  $Y_1, Y_2$  are solutions to the linear system

$$\begin{pmatrix} s-2 & 1 \\ -1 & s-2 \end{pmatrix} \begin{pmatrix} Y_1(s) \\ Y_2(s) \end{pmatrix} = \begin{pmatrix} 1 \\ \frac{1}{s} \end{pmatrix}.$$

This system has the solution

$$Y_1(s) = \frac{s^2 - 2s - 1}{s((s-2)^2 + 1)}, \quad Y_2(s) = \frac{2s - 2}{s((s-2)^2 + 1)}.$$

- b) Partial fraction decomposition and rewriting conveniently:

$$\begin{aligned} Y_1(s) &= \frac{1}{5} \left( -\frac{1}{s} + \frac{6s - 14}{(s-2)^2 + 1} \right) = \frac{1}{5} \left( -\frac{1}{s} + \frac{6(s-2) - 2}{(s-2)^2 + 1} \right), \\ Y_2(s) &= \frac{2}{5} \left( -\frac{1}{s} + \frac{s+1}{(s-2)^2 + 1} \right) = \frac{2}{5} \left( -\frac{1}{s} + \frac{(s-2) + 3}{(s-2)^2 + 1} \right). \end{aligned}$$

So by inverse Laplace transform

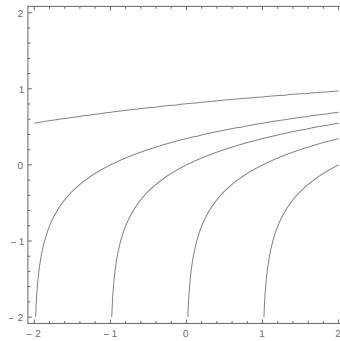
$$y_1(t) = \frac{1}{5} (-1 + 6e^{2t} \cos t - 2e^{2t} \sin t), \quad y_2(t) = \frac{2}{5} (-1 + e^{2t} \cos t + 3e^{2t} \sin t).$$

2. Because of

$$\partial_y \partial_x f(x, y) = x = \partial_x \partial_y f(x, y) = 2ax + by$$

we find  $a = \frac{1}{2}, b = 0$ .

3. a) The contour lines are given by  $x - e^{2y} = C$ , or equivalently  $y = \frac{1}{2} \ln(x - C)$ .



- b) The contour line through  $(0, 0)$  has equation  $y = \frac{1}{2} \ln(x+1)$ , so the tangent has equation  $y = \frac{x}{2}$ .
- c) Observe that

$$x - e^{2y} = (x-1) - (e^{2y} - 1) = (x-1) - 2y - 2y^2 + O(y^3),$$

so

$$\begin{aligned} f(x, y) &= 1 + (x-1) - 2y - 2y^2 + ((x-1) - 2y - 2y^2)^2 + O(((x-1)^2 + y^2)^{3/2}) \\ &= 1 + (x-1) - 2y + (x-1)^2 - 4(x-1)y + 2y^2 + O((x-1)^2 + y^2)^{3/2}. \end{aligned}$$

The second order Taylor polynomial is given by the last expression without the higher order remainder term.

Alternatively, the Taylor polynomial can be found by using  $g(0) = 1, g'(0) = 1, g''(0) = 2$  and the chain rule to calculate all partial derivatives of  $f$  up to order 2 in  $(1, 0)$  and applying the standard formula.

4. Critical points  $(x, y)$  have to satisfy  $\cos x = \cos y = -\cos(x + y)$ , so if  $(x, y) \in D$  it follows that  $x = y$  and further  $\cos x + \cos(2x) = \cos x + 2\cos^2 x - 1 = 0$ , so  $\cos x = 1/2$  or  $\cos x = -1$  where the second possibility is in contradiction with  $x \in [0, \pi/2]$ . So  $x = \pi/3$ , and the only critical point of  $f$  in  $D$  is  $(\pi/3, \pi/3)$  with function value  $f(\pi/3, \pi/3) = \frac{3}{2}\sqrt{3}$ .

Due to the symmetry in  $x$  and  $y$ , it is sufficient to discuss the boundary components  $\{(x, 0) \mid x \in [0, \pi/2]\}$  and  $\{(x, \pi/2) \mid x \in [0, \pi/2]\}$ . We find

$$f(x, 0) = 2 \sin x \leq 2 < \frac{3}{2}\sqrt{3},$$

$$f(x, \pi/2) = \sin x + 1 + \cos x \leq \sqrt{2} + 1 < \frac{3}{2}\sqrt{3}.$$

So the global maximum value on  $D$  is  $\frac{3}{2}\sqrt{3}$ .

5. The Lagrange equations are

$$\begin{pmatrix} \frac{1}{z} \\ \frac{1}{z} \\ -\frac{x+y}{z^2} \end{pmatrix} = \lambda \begin{pmatrix} 2x \\ 2y \\ 2(z-2) \end{pmatrix}.$$

This implies  $x = y \neq 0$  and  $\lambda = 1/(2xz)$ . With this we get further  $-2x^2 = z(z-2)$  and from the restriction

$$-z(z-2) + (z-2)^2 = 1,$$

so  $z = 3/2$ ,  $x = y = \pm\sqrt{3/8}$ . The maximal value is taken in  $(\sqrt{3/8}, \sqrt{3/8}, 3/2)$  and is  $\sqrt{2/3}$ .

6. Let  $F : \mathbb{R}^4 \rightarrow \mathbb{R}^2$  be defined by

$$F(x, y, u, v) = \begin{pmatrix} x^2 + y^2 + u^2 + v^2 - 4 \\ x + y^2 + u^3 + v^4 - 4 \end{pmatrix}$$

By the Implicit Function theorem, as  $F$  is continuously differentiable,  $F(1, 1, 1, 1) = 0$ , and

$$D_{(x,y)}F(1, 1, 1, 1) = \begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix}$$

is regular, the system  $F(x, y, u, v) = (0, 0)^\top$  is locally solvable in the form  $x = \phi(u, v)$ ,  $y = \psi(u, v)$  near  $(1, 1, 1, 1)$ . Further

$$\begin{aligned} \begin{pmatrix} \partial_u \phi & \partial_v \phi \\ \partial_u \psi & \partial_v \psi \end{pmatrix} (1, 1) &= D_{(u,v)} \begin{pmatrix} \phi \\ \psi \end{pmatrix} (1, 1) = -D_{(x,y)}F(1, 1, 1, 1)^{-1} D_{(u,v)}F(1, 1, 1, 1) \\ &= -\begin{pmatrix} 1 & -1 \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ -2 & -3 \end{pmatrix} \end{aligned}$$

- 7.

$$\iiint_K x \, dV = \int_0^1 \int_0^{1-z} \int_0^{1-z} x \, dx \, dy \, dz = \frac{1}{8}.$$

8. Cylindrical coordinates:

$$\iiint_K z e^{-(x^2 + y^2 + z^2)} \, dV = \int_0^{2\pi} \int_0^\infty \int_0^1 r e^{-r^2} z e^{-z^2} \, dV = \frac{\pi}{2}(1 - e^{-1}).$$