

# Solutions final test Advanced Calculus (2DBN10) january 2019

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1. a) The equation is homogeneous and has characteristic equation  $\lambda^3 - \lambda^2 + 2 = 0$  with the three solutions  $\lambda_1 = -1$ ,  $\lambda_{2,3} = 1 \pm i$ , and therefore the general solution

$$y(t) = C_1 e^{-t} + e^t (C_2 \cos(t) + C_3 \sin(t)).$$

If  $C_1 \neq 0$  then  $|y(t)| \rightarrow \infty$  as  $t \rightarrow -\infty$ . On the other hand, all solutions of the form  $y(t) = e^t (C_2 \cos(t) + C_3 \sin(t))$  satisfy  $y(t) \rightarrow 0$  as  $t \rightarrow -\infty$ .

- b) Ansatz:  $u(t) = A \cos(t) + B \sin(t)$ . Filling this in yields  $A + 3B = 0$ ,  $3A - B = 1$ , so  $A = 3/10$ ,  $B = -1/10$ ,  $u(t) = \frac{3}{10} \cos(t) - \frac{1}{10} \sin(t)$ .
2. a) According to the properties of the Laplace transform,  $Y_1, Y_2$  are solutions to the linear system

$$\begin{pmatrix} s-1 & -1 \\ 1 & s-3 \end{pmatrix} \begin{pmatrix} Y_1(s) \\ Y_2(s) \end{pmatrix} = \begin{pmatrix} \frac{1}{s-2} \\ \frac{2}{s-2} \end{pmatrix}.$$

This system has the solution

$$Y_1(s) = \frac{s-1}{(s-2)^3}, \quad Y_2(s) = \frac{2s-3}{(s-2)^3}.$$

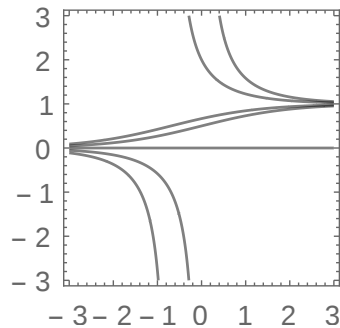
- b) Rewrite

$$Y_1(s) = \frac{1}{(s-2)^2} + \frac{1}{(s-2)^3}, \quad Y_2(s) = \frac{2}{(s-2)^2} + \frac{1}{(s-2)^3}.$$

So by inverse Laplace transform

$$y_1(t) = \left(t + \frac{t^2}{2}\right) e^{2t}, \quad y_2(t) = \left(2t + \frac{t^2}{2}\right) e^{2t}.$$

3. a) The level curves are given by  $f(x, y) = c$ , or equivalently  $y = ce^x / (1 + ce^x)$  for  $c \in \{-2, -1, 0, 1, 2\}$ .



**b)** We have  $f_x(0, 2) = 2$ ,  $f_y(0, 2) = 1$ , so the tangent plane is given by

$$z = -2 + 2x + (y - 2).$$

**c)** The tangent line should run through  $(0, 2)$  and be orthogonal to  $\nabla f(0, 2) = (2, 1)^\top$ , so an equation is

$$2x + (y - 2) = 0.$$

**d)** We can use the 1D Taylor expansions

$$\begin{aligned} e^{-x} &= 1 - x + \frac{x^2}{2} - \frac{x^3}{6} + O(x^4), \\ \frac{y}{1-y} &= y + y^2 + y^3 + O(y^4) \end{aligned}$$

to find the third order Taylor polynomial

$$p_3(x, y) = y - xy + y^2 + \frac{1}{2}x^2y - xy^2 + y^3.$$

Alternatively, the Taylor polynomial can be obtained from the standard formula.

**4.** From the given equations we find by the chain rule

$$\begin{aligned} \partial_1 f(1, 1) + \partial_2 f(1, 1) &= 1, \\ \partial_1 f(1, 1) + 2\partial_2 f(1, 1) &= 1/2. \end{aligned}$$

We solve this linear system to find  $\partial_1 f(1, 1) = 3/2$ ,  $\partial_2 f(1, 1) = -1/2$  and consequently

$$\frac{d}{dt} f(t, t^\alpha)|_{t=1} = \partial_1 f(1, 1) + \alpha \partial_2 f(1, 1) = (3 - \alpha)/2.$$

**5.** The critical points are the zeroes of the gradient given by

$$\nabla f(x, y) = 2 \begin{pmatrix} x(y^2 - x^2 + 1) \\ y(y^2 - x^2 - 1) \end{pmatrix} e^{-(x^2+y^2)}$$

From the first component we get that  $x = 0$  or  $y^2 - x^2 = -1$ . In the first case, the second equation implies  $y = 0$  or  $y = \pm 1$ . In the second case, the second equation implies  $y = 0$  and therefore  $x = \pm 1$ . Summarizing, there are five critical points:  $(0, 0)$ ,  $(0, \pm 1)$ , and  $(\pm 1, 0)$ .

To determine their type, we calculate the Hessian:

$$\nabla^2 f(x, y) = 2 \begin{pmatrix} -2x^2 - (2x^2 - 1)(y^2 - x^2 + 1) & 2xy(y^2 - x^2) \\ 2xy(y^2 - x^2) & 2y^2 - (2y^2 - 1)(y^2 - x^2 - 1) \end{pmatrix} e^{-(x^2+y^2)}.$$

At the critical points, this is

$$\nabla^2 f(0, 0) = \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix}, \quad \nabla^2 f(\pm 1, 0) = \begin{pmatrix} -4 & 0 \\ 0 & -4 \end{pmatrix} e^{-1}, \quad \nabla^2 f(0, \pm 1) = \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix} e^{-1}.$$

So the second derivative test yields that  $(0, 0)$  is a saddle point,  $(\pm 1, 0)$  are local maxima, and  $(0, \pm 1)$  are local minima.

**6. a)** The function  $f$  to be minimized is given by

$$f(x, y, z) = \sum [(x - a_i)^2 + (y - b_i)^2 + (z - c_i)^2].$$

Here and in the remaining part of a),  $\sum$  denotes summation over  $i = 1, 2$ . The Lagrange equations are

$$2 \begin{pmatrix} 2x - \sum a_i \\ 2y - \sum b_i \\ 2z - \sum c_i \end{pmatrix} = 2\lambda \begin{pmatrix} x \\ y \\ z \end{pmatrix},$$

or

$$(2 - \lambda) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \sum \begin{pmatrix} a_i \\ b_i \\ c_i \end{pmatrix}.$$

As  $a_1 + a_2 > 0$  we have  $\lambda \neq 2$  and therefore  $(x, y, z) \parallel \sum(a_i, b_i, c_i)$ . Consequently, the restriction implies

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \pm \frac{1}{\sqrt{(\sum a_i)^2 + (\sum b_i)^2 + (\sum c_i)^2}} \sum \begin{pmatrix} a_i \\ b_i \\ c_i \end{pmatrix}$$

(In the “+” case the minimum is taken, and in the “-”-case the maximum is taken. A proof of this is not demanded.)

- b)** The calculations for a) generalize immediately to  $n \geq 2$ , if all summations are taken from  $i = 1$  to  $n$ .

- 7. a)** Define  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  by

$$F(x, y, z) = \begin{pmatrix} x + y^2 + \sin(yz) - 2 \\ -x^2 + y + z \end{pmatrix}.$$

$F$  is differentiable,  $F(2, 0, 4) = 0$ , and

$$D_{(y,z)}F(x, y, z) = \begin{pmatrix} 2y + z \cos(yz) & y \cos(yz) \\ 1 & 1 \end{pmatrix},$$

in particular

$$D_{(y,z)}F(2, 0, 4) = \begin{pmatrix} 4 & 0 \\ 1 & 1 \end{pmatrix},$$

so  $D_{(y,z)}F(2, 0, 4)$  is regular.

Therefore the Implicit Function theorem can be applied and yields the statement.

- b)** Differentiating the given equations with respect to  $x$  and filling in  $x = 2$  yields the linear system

$$\begin{pmatrix} 4 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \phi'(2) \\ \psi'(2) \end{pmatrix} = \begin{pmatrix} -1 \\ 4 \end{pmatrix}$$

with solution  $\phi'(2) = -1/4$ ,  $\psi'(2) = 17/4$ . So the linearizations are

$$\phi(x) \approx -\frac{1}{4}(x - 2), \quad \psi(x) \approx 4 + \frac{17}{4}(x - 2).$$

- 8. Cylindrical coordinates:**

$$\iiint_K z \, dV = \int_0^{2\pi} \int_0^1 \int_0^{1+r \cos \theta} zr \, dz \, dr \, d\theta = \frac{5}{8}\pi.$$