

## Solutions final test Advanced Calculus (2DBN10) November 2023

No rights can be derived from these solutions.

1. a) The eigenvalues of the coefficient matrix are  $\lambda_1 = -1$ ,  $\lambda_2 = 3$  with corresponding eigenvectors  $(1, 1)^\top$  and  $(3, 2)^\top$ . So all (real) solution are given by

$$y(t) = C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t} + C_2 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{3t}, \quad C_{1,2} \in \mathbb{R}.$$

These solutions go to 0 for  $t \rightarrow \infty$  if and only if  $C_2 = 0$ . In this case we have

$$y(0) = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix},$$

i.e.  $z_1 = z_2$ .

- b) Ansatz via variation of parameters:

$$y_p(t) = C_1(t) \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t} + C_2(t) \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{3t}.$$

This leads to the linear system

$$\begin{pmatrix} 1 & 3 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} e^{-t} \dot{C}_1(t) \\ e^{3t} \dot{C}_2(t) \end{pmatrix} = \begin{pmatrix} e^t \\ 1 \end{pmatrix}$$

with solution

$$\begin{aligned} \dot{C}_1(t) &= -2e^{2t} + 3e^t, \\ \dot{C}_2(t) &= e^{-2t} - e^{-3t} \end{aligned}$$

and after integration

$$\begin{aligned} C_1(t) &= -e^{2t} + 3e^t, \\ C_2(t) &= -\frac{1}{2}e^{-2t} + \frac{1}{3}e^{-3t} \end{aligned}$$

(with integration constants set to 0 as we seek a particular solution only). So

$$y_p(t) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} (-e^t + 3) + \begin{pmatrix} 3 \\ 2 \end{pmatrix} \left(-\frac{1}{2}e^t + \frac{1}{3}\right) = \begin{pmatrix} -\frac{5}{2}e^t + 4 \\ -2e^t + \frac{11}{3} \end{pmatrix}$$

2. a) Rewrite

$$F(s) = \underbrace{\frac{1}{(s+1)^2 + 2}}_{F_1(s)} - \underbrace{\frac{e^{-s/2}}{(s+1)^2 + 2}}_{F_2(s)}.$$

The calculation rules yield

$$f_1(t) := \mathcal{L}^{-1}[F_1](t) = \frac{e^{-t}}{\sqrt{2}} \sin(\sqrt{2}t),$$

$$f_2(t) := \mathcal{L}^{-1}[F_2](t) = \begin{cases} 0 & \text{if } t < 1/2, \\ \frac{e^{-(t-1/2)}}{\sqrt{2}} \sin(\sqrt{2}(t-1/2)) & \text{if } t \geq 1/2, \end{cases}$$

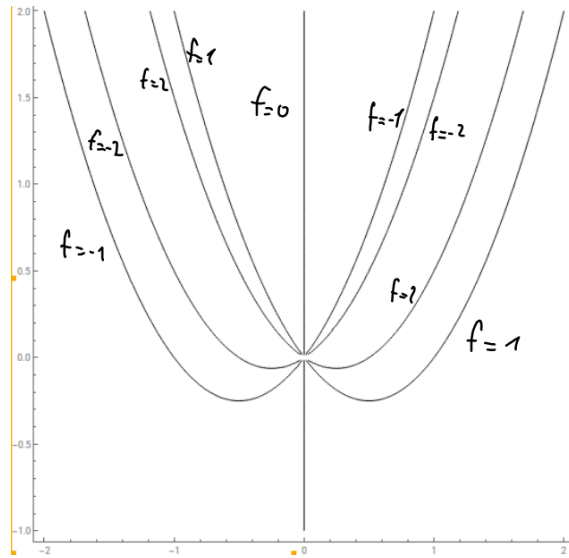
so

$$\mathcal{L}^{-1}[F_2](t) = f_1(t) - f_2(t) = \begin{cases} \frac{e^{-t}}{\sqrt{2}} \sin(\sqrt{2}t) & \text{if } t < 1/2, \\ \frac{e^{-t}}{\sqrt{2}} (\sin(\sqrt{2}t) - e^{1/2} \sin(\sqrt{2}(t-1/2))) & \text{if } t \geq 1/2. \end{cases}$$

- b) As  $f'$  is a bounded continuous function, its Laplace transform converges to 0 as  $s \rightarrow \infty$ . Hence

$$sF(s) = \mathcal{L}[f'](s) + f(0) \xrightarrow{s \rightarrow \infty} f(0).$$

3. a)



b)  $z = \frac{2}{3} - \frac{5}{9}(x-2) + \frac{2}{9}(y-1)$

c)  $-\frac{5}{9}(x-2) + \frac{2}{9}(y-1) = 0$ , or  $5x - 2y = 8$ .

4. Let  $z = x \cos y - 1$ . Then, by standard expansions,

$$\begin{aligned} z &= (1 + (x-1))(1 - y^2/2 + O(y^4)) - 1 = (x-1) - y^2/2 + O(|(x-1, y)|^3), \\ z^2 &= (x-1)^2 + O(|(x-1, y)|^3), \\ z^3 &= O(|(x-1, y)|^3), \\ f(x, y) &= 1/(1-z) = 1 + z + z^2 + O(z^3) = 1 + (x-1) - y^2/2 + (x-1)^2 \\ &\quad + O(|(x-1, y)|^3), \end{aligned}$$

and the Taylor polynomial is given by

$$T(x, y) = 1 + (x-1) - y^2/2 + (x-1)^2.$$

This result can alternatively be obtained by calculating the partial derivatives at  $(1, 1)$  and using the standard formula.

5. a) Critical points of  $f$  satisfy

$$\nabla f(x, y) = \begin{pmatrix} 4x^3 - 8y \\ 4y^3 - 8x \end{pmatrix} = 0,$$

hence  $x^3 = 2y$  and  $y^3 = 2x$ . So  $x^9 = 8y^3 = 16x$ , and hence either  $x = 0$  or  $x^8 = 16$ , i.e.  $x = \pm\sqrt[4]{2}$ .

If  $x = 0$  then  $y = 0$ , and indeed  $\nabla f(0, 0) = 0$ . If  $x = \pm\sqrt[4]{2}$  then  $y = \pm\sqrt[4]{2}$ , and indeed  $\nabla f(\pm(\sqrt[4]{2}, \sqrt[4]{2})) = 0$ . For the Hessian we get

$$D^2 f(x, y) = \begin{pmatrix} 12x^2 & -8 \\ -8 & 12y^2 \end{pmatrix}, \quad D^2 f(0, 0) = \begin{pmatrix} 0 & -8 \\ -8 & 0 \end{pmatrix}, \quad D^2 f(\pm(\sqrt[4]{2}, \sqrt[4]{2})) = \begin{pmatrix} 24 & -8 \\ -8 & 24 \end{pmatrix},$$

and the second derivative test yields that  $(0, 0)$  is a saddle point and  $\pm(\sqrt[4]{2}, \sqrt[4]{2})$  are places of (strict) local minima.

b) As e.g.  $f(x, 0) = x^4$  gets arbitrarily large for  $x$  large,  $f$  has no upper bounds and therefore no global maximum.

Alternative: As  $\mathbb{R}^2$  has no boundary points, a global (hence also local) maximum would be taken at a critical point. However, we have already seen that there is no critical point at which the function takes a local maximum.

6. Let  $g : \mathbb{R}^2 \rightarrow \mathbb{R}$  be given by

$$g(x, y) = (x + 2)^2 + y^2 - 4.$$

The Lagrange equations are

$$\nabla f(x, y) = e^x \begin{pmatrix} x^2 - y^2 + 2x \\ -2y \end{pmatrix} = \lambda \nabla g(x, y) = \lambda \begin{pmatrix} 2(x + 2) \\ 2y \end{pmatrix}, \quad g(x, y) = 0.$$

We distinguish the cases  $y = 0$  and  $y \neq 0$ .

1. If  $y = 0$  then  $x = 0$  or  $x = -4$  because of  $g(x, 0) = 0$ .

1.1. If  $x = 0$  then  $\lambda = 0$ , and  $(x, y, \lambda) = (0, 0, 0)$  indeed solves the Lagrange equations. The corresponding function value is  $f(0, 0) = 0$ .

1.2. If  $x = -4$  then  $\lambda = -2e^{-4}$ , and  $(x, y, \lambda) = (-4, 0, -2e^{-4})$  indeed solves the Lagrange equations. The corresponding function value is  $f(-4, 0) = 16e^{-4}$ .

2. If  $y \neq 0$  then  $\lambda = -e^x \neq 0$ , and hence  $x^2 - y^2 + 2x = -2(x + 2)$ , i.e.  $(x + 2)^2 = y^2$ . Together with  $g(x, y) = 0$  this implies  $(x + 2)^2 = y^2 = 2$ . This yields the four solutions

$$\begin{aligned} (x, y, \lambda) &= (-2 - \sqrt{2}, \pm\sqrt{2}, -e^{-(2-\sqrt{2})}), \\ (x, y, \lambda) &= (-2 + \sqrt{2}, \pm\sqrt{2}, -e^{-(2+\sqrt{2})}), \end{aligned}$$

with corresponding function values

$$\begin{aligned} f(-2 - \sqrt{2}, \pm\sqrt{2}) &= 4e^{-2-\sqrt{2}}(1 + \sqrt{2}), \\ f(-2 + \sqrt{2}, \pm\sqrt{2}) &= 4e^{-2+\sqrt{2}}(1 - \sqrt{2}). \end{aligned}$$

Comparison of the function values yields that the global maximum is  $4e^{-2-\sqrt{2}}(1 + \sqrt{2})$  and the global minimum is  $4e^{-2+\sqrt{2}}(1 - \sqrt{2})$ .

7. Using the change of variables theorem, we get

$$\text{Area}(\Phi(D)) = \iint_{\Phi(D)} 1 \, dA = \iint_D |\det D\Phi| \, dA = 2 \iint_D (x^2 + y^2) \, dA = 2 \int_0^1 \int_0^{1-x} (x^2 + y^2) \, dA = 1/3.$$

8. “adapted” cylindrical coordinates  $((x, y, z) = (x, r \cos \theta, r \sin \theta))$ :

$$\iiint_K x \, dV = \int_0^{2\pi} \int_1^2 x \int_0^{\sqrt{4-x^2}} r \, dr \, dx \, d\theta \quad \text{or} \quad \iiint_K x \, dV = \int_0^{2\pi} \int_0^{\sqrt{3}} r \int_1^{\sqrt{4-r^2}} x \, dx \, dr \, d\theta = 9\pi/4.$$