

Closing open SDL-systems for model checking with DTSpin

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- con: state-space explosion

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- **assume-guarantee** paradigm

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- **push the button...**

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Embedding Chaos [Sidorova and Steffen, 2001]

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- the tool is **targeted towards** the verification of **SDL** components with **DTSpin**

SDL

(Specification and Description Language)

- standardized (in various versions)
- standard spec. language for telecom applications
- characteristics:
 - **control** structure:
communicating finite-state machines
 - **communication**:
asynchronous message passing
 - **data**: various basic and composed types
 - **timers** and **timeouts**
 - **bells and whistles**: graphical notation, structuring mechanisms, OO, ...

Model checking SDL systems

- three more specific **problems**
 1. **asynchronous** input queues: \Rightarrow **state explosion**
 2. infinite data domains
 3. chaotic **timer** behavior

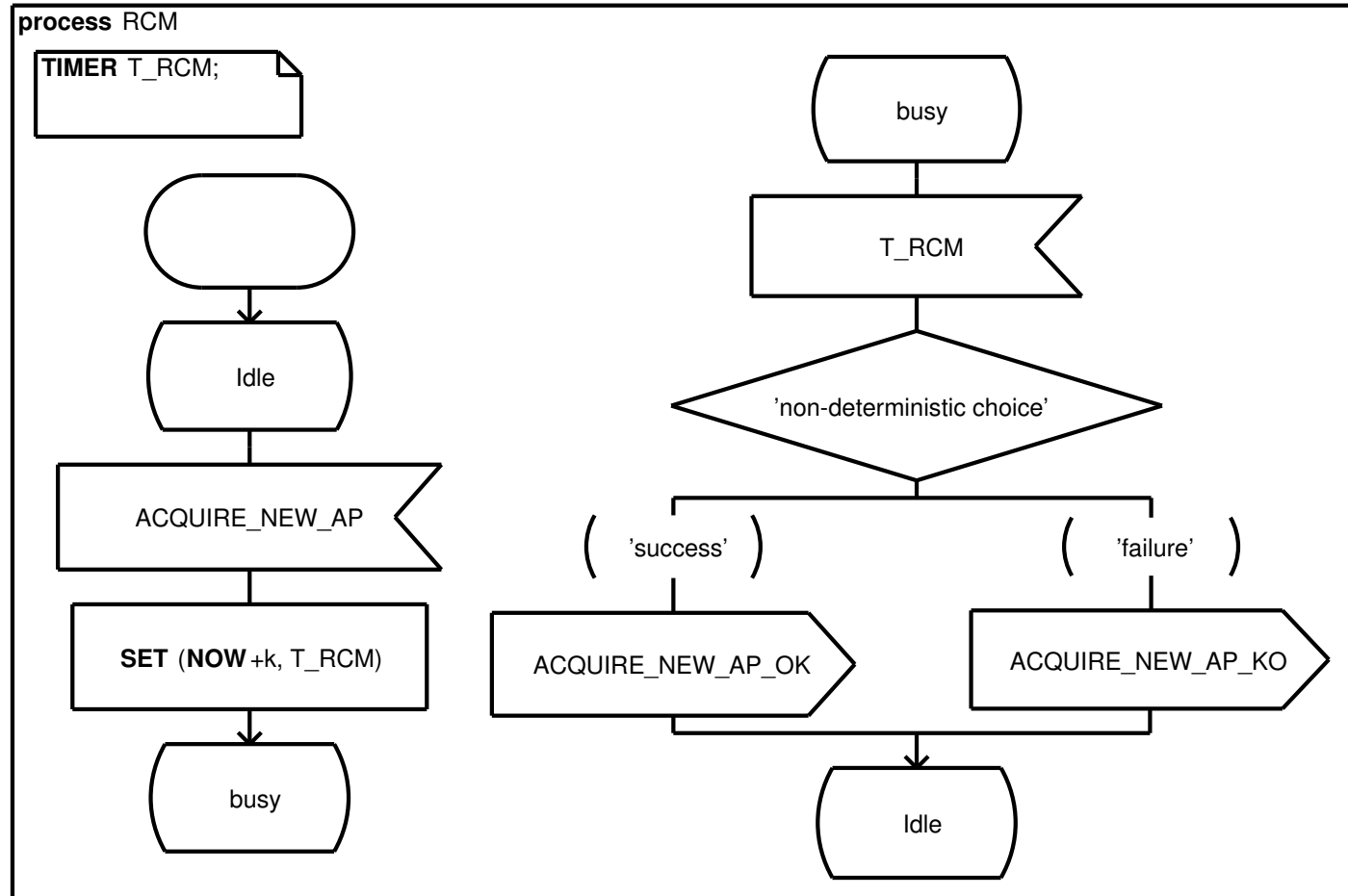
Model checking SDL systems

- three more specific **problems**
 1. **asynchronous** input queues: \Rightarrow **state explosion**
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- three specific solutions
 1. **embedding** environment into the system
 2. **one-valued** data abstraction $\hat{=}$ **no external data**
 3. three-valued **timer abstraction**

Roadmap

1. (sketch of) syntax
2. SO-semantic rules
3. eliminating external data via data-flow analysis
4. dealing with chaotic timers
5. eliminating communication with environment
6. tools overview
7. experimental results

Syntax: Example



Syntax

- labelled edges $l \longrightarrow_{\alpha} \hat{l}$ connecting locations

- actions α :

input $?s(x)$

output $g \triangleright P!s(e)$

assignment $g \triangleright x := e$

with guards g , signals s , processes P

Semantics (local)

- straightforward **operational** small-step semantics
 - **interleaving** semantics
 - **top-level** concurrency
 - **local** process **configuration**:
 1. **location/control** state
 2. **valuation** of variables
 3. an input **queue**
- ⇒ **labelled** steps between configurations, e.g.

$$\frac{l \longrightarrow_{?s(x)} \hat{l} \in Edg}{(l, \eta, s(v)::q) \longrightarrow_{?s(x)} (\hat{l}, \eta[x \mapsto v], q)} \text{INPUT}$$

Modelling SDL Timers

- discrete-time semantics
- ⇒ time evolves by ticking down (active) timer variables
- timer: active or deactivated
- timeout possible: if active timer has reached 0
- modelled by timeout guards

Syntax for timers

- guarded actions involving timers

set $g \triangleright \text{set } t := e$ (re-)activate timer t
for a period given by
 e

reset $g \triangleright \text{reset } t$ deactivate t

timeout $g_t \triangleright \text{reset } t$ perform a timeout,
thereby deactivate t

- note: timeout is guarded by “timer-guard” g_t :
 $t = 0$

Parallel composition

- standard **product** construction
- **message passing** using the **labelled** steps
- note: **tick** step = counting down active timers:
 - is taken only when **no other** move is possible

$$\sigma \rightarrow_{tick} \sigma[t \mapsto (t-1)] \quad \text{iff} \quad \textit{blocked}(\sigma)$$

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Side-condition

- verification with *DTSpin* model checker:
 - there are no abstract data
 - we cannot re-implement tick
- keep it simple

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eliminating external data

1. **data-flow** analysis: mark all variable instances potentially influenced by chaos
2. **transform** the program, using that marking

Data-flow analysis

- **control-flow** given by SDL-automata
- propagate \top through control-flow graph, via **abstract effect** per action = **node**, e.g.:

$$f(?s(x)\eta^\alpha) = \begin{cases} \eta^\alpha[x \mapsto \top] & s \in \text{Sig}_{ex} \\ \eta^\alpha[x \mapsto \bigvee \{[e]_{\eta^\alpha} \mid \alpha_{n'} = g \triangleright P!s(e)\}] & \text{else} \end{cases}$$

- **constraint solving**: minimal solution for

$$\eta_{post}^\alpha(n) \geq f_n(\eta_{pre}^\alpha(n))$$

$$\eta_{pre}^\alpha(n) \geq \bigvee \{ \eta_{post}^\alpha(n') \mid (n', n) \text{ in flow relation} \}$$

Worklist algo (pseudo-code)

input : the flow-graph of the program

output : $\eta_{pre}^\alpha, \eta_{post}^\alpha$;

$\eta^\alpha(n) = \eta_{init}^\alpha(n)$;

$WL = \{n \mid \alpha_n = ?s(x), s \in Sig_{ext}\}$;

repeat

 pick $n \in WL$;

 let $S = \{n' \in succ(n) \mid f_n(\eta^\alpha(n)) \not\leq \eta^\alpha(n')\}$

 in

 for all $n' \in S: \eta^\alpha(n') := f(\eta^\alpha(n))$;

 if $n = g \triangleright P!s(e)$

 then let $S' = \{n' \in P \mid n' = ?s(x), \eta^\alpha(n)(e) \not\leq \eta^\alpha(n')(x)\}$

$WL := WL \setminus n \cup S \cup S'$;

until $WL = \emptyset$;

$\eta_{pre}^\alpha(n) = \eta^\alpha(n)$;

$\eta_{post}^\alpha(n) = f_n(\eta^\alpha(n))$

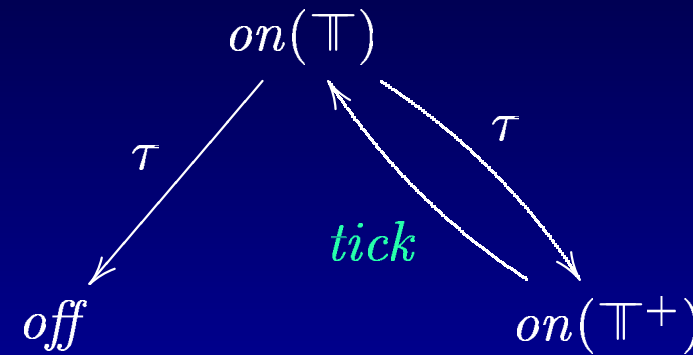
What about time?

- so far: we ignored **timers**
- timers can be **influenced** by external data
- chaotic timeout for an **active** timer:
 1. it can happen **now**, or
 2. **eventually** in the future
- remember: **time steps** (ticks) have **least priority!**

Timer abstraction

Three abstract values:

1. *off*: deactivated
2. *on*(\top): arbitrarily active
3. *on*(\top^+): active, but not 0 (no time-out possible)



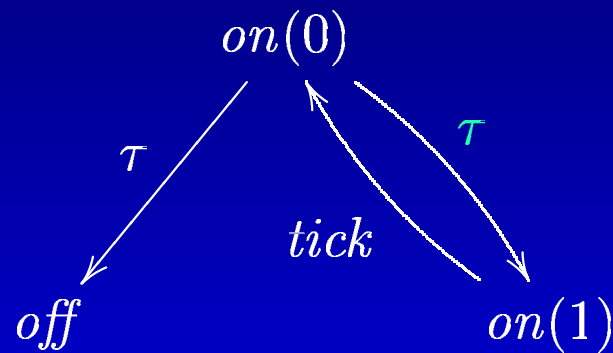
- arbitrary expiration time \Rightarrow non-deterministic setting from *on*(\top) to *on*(\top^+)

Implementation: *off*, *on*(0), *on*(1)

Transformation rules

- using result of the **flow analysis**
- inference rule(s) for each syntax construct, e.g.,

$$\frac{\llbracket t \rrbracket_{\eta_l^\alpha} = \top}{l \xrightarrow{gt} \triangleright \text{reset } t \xrightarrow{\text{set } t:=1} l \in \text{Edg}^\#} \text{T-NoTIMEOUT}$$



- **transformation** yields a **safe abstraction**

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- **No data** involved in the communication with the environment
- But: the system is still **open**

Embedding chaos

- Environment sends signals arbitrarily
- ⇒ Inputs from the environment are always potentially enabled
- ⇒ Replace them by ?*none* inputs ???

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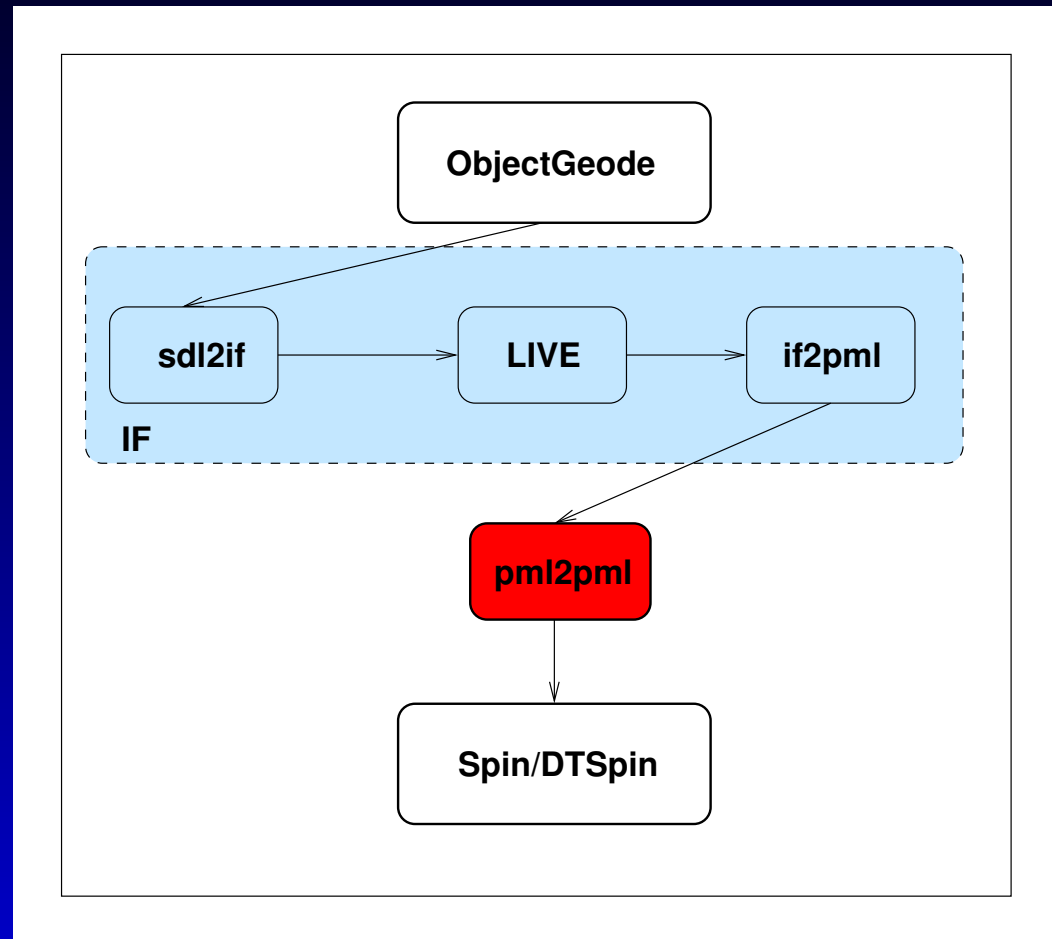
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$$\frac{l \xrightarrow{?s(x)} \hat{l} \in Edg^{\top} \quad s \in Sig_{ext}}{l \xrightarrow{gt_P} \triangleright reset\ t_P \longrightarrow set\ t_P:=0 \hat{l} \in Edg^{\#}} \text{T-INPUT}$$

$$\frac{}{l \xrightarrow{gt_P} \triangleright reset\ t_P \longrightarrow set\ t_P:=1 \ l \in Edg^{\#}} \text{T-NOINPUT}$$

Extending Vires toolset



Experimental results

Steady State Control of Mascara* closed with embedded chaos and model checked with *DTSpin*

	System with ext. chaos	System with embedded chaos
States	2.68938e+07	467555
Transitions	1.04753e+08	2.30307e+06
Memory	944.440	14.499
Time	1:59:39.76	2:12.91

*[Guoping and Graf],[Sidorova and Steffen, 2001b], [Bošnački et al., 2000]

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 - a closed model
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- experiments on Mascara confirm the usefulness of the embedding chaos approach

Related work

- software testing
- VERISOFT, C, untimed [Colby et al., 1998]
- filtering [Dwyer and Pasareanu, 1998]
[Pasareanu, 2000]
- module checking:
 - checking open systems
 - e.g. MOCHA [Alur et al., 1998]

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- extension of **pml2pml** implementing **synchronous closing** [Sidorova and Steffen, 2002]

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