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## Motivation

Performance analysis of
two coupled $M / M / 1$ queues (in parallel), where the coupling occurs due to simultaneous abandonments


We transform the state space description

$$
n=\min \left\{q_{1}, q_{2}\right\} \text { and } m=q_{1}-q_{2}
$$




Objective: determine the steady-state distribution $\pi(n, m)$

## TU/e

## Background

Exact analysis techniques for random walks

- Boundary value method approach
[1] Cohen, J.W. and Boxma, O.J. (1983). Boundary Value Problems in Queueing System Analysis.
[2] Fayolle, G., Iasnogorodski, R. and Malyshev, V. (1999). Random Walks in the Quarter Plane.
- Matrix geometric approach

$$
A_{1}+R A_{0}+R^{2} A_{-1}=0
$$

- Compensation approach [3] Adan, I.J.B.F. (1991). A Compensation Approach for Queueing Problems.

- Successive lumping
[4] Smit, L.C. (2016). Steady State Analysis of Large-Scale Systems.

The above techniques have been developed separately and although there exists a set of models for which all aforementioned techniques are appropriate they haven't been connected!

## Main results

We consider the class of nearest neighbour random walks (NNRW) and we connect

- Boundary value method approach
- Matrix geometric approach
- Compensation approach


Theorem 1 $m$
We consider the chass of NNRW and we calculate the eigenvalues and eigenvectors of $R$ recursively.

Theorem 2

 "diagonalizable" and we can numerically approximate $R$ using spectral truncation;


Theorem 3
We obtain the eigenvalues of the rate matrix for the original model.


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Nearest neighbour random walk
We consider the class of nearest neighbour random walks (NNRW):

- 1 st quadrant
- Homogeneous nearest neighbour
- No transitions to N, NE and E


$$
\pi(n, m) \sim c \alpha^{n} \beta^{m} \text { as } n, m \rightarrow \infty
$$

More concretely,

$$
\pi(n, m)=\sum_{i} c_{i} \alpha_{i}^{n} \beta_{i}^{m}, n, m>0
$$

The limitations above are sufficient
[3] Adan, I.J.B.F. (1991). A Compensation Approach for Queueing Problems.
and necessary
[5] Chen, Y. (2015). Random Walks in the Quarter-Plane: invariant Measures and Performance Bounds.

## TU/e

## Boundary value method approach

First, introduce

$$
\Pi(x, y)=\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \pi(n, m) x^{n} y^{m}
$$

then

$$
K(x, y) \Pi(x, y)=A(x, y) \Pi(x, 0)+B(x, y) \Pi(0, y)+C(x, y) \Pi(0,0)
$$

where $K(x, y), A(x, y), B(x, y), C(x, y)$ are known quadratic functions.
Choose $y=f(x)$, e.g. $y=\bar{x}$, and set $K(x, f(x))=0$

$$
0=A(x, f(x)) \Pi(x, 0)+B(x, f(x)) \Pi(0, f(x))+C(x, f(x)) \Pi(0,0)
$$

The above equation can be solved as a Riemann (Hilbert) boundary value problem.


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## Compensation approach

Aims at solving directly the balance equations of a random walk in the quadrant using a series (infinite or finite) of product-form solutions
Key idea:

- Guess a product-form solution

$$
\alpha^{n} \beta^{m}
$$

- Check if it satisfies the boundaries
- If not start compensating by adding new product-form terms

Solution


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## Matrix geometric approach

We know that

$$
\boldsymbol{\pi}_{n}=\boldsymbol{\pi}_{n-1} \boldsymbol{R}
$$

where $\boldsymbol{\pi}_{n}=(\pi(n, 0) \pi(n, 1) \ldots)$ and $\pi(n, m)=\sum_{i} c_{i} \alpha_{i}^{n} \beta_{i}^{m}, n, m>0$.
Then,

$$
\Pi(x, y)=\boldsymbol{\pi}_{0} \boldsymbol{y}^{\prime}+\boldsymbol{\pi}_{1}\left(x^{-1} \boldsymbol{I}-\boldsymbol{R}\right)^{-1} \boldsymbol{y}^{\prime}
$$

where $\boldsymbol{y}^{\prime}=\left(1 y y^{2} \ldots\right)$.
Substituting in the functional equation reveals

$$
\begin{gathered}
K(x, y) \Pi(x, y)=A(x, y) \Pi(x, 0)+B(x, y) \Pi(0, y)+C(x, y) \Pi(0,0) \Rightarrow \\
\boldsymbol{\pi}_{1}\left(x^{-1} \boldsymbol{I}-\boldsymbol{R}\right)^{-1}[K(x, y) \boldsymbol{y}+A(x, y) \boldsymbol{e}] \\
=-\boldsymbol{\pi}_{0}\left[(K(x, y)+B(x, y)) \boldsymbol{y}^{\prime}+(A(x, y)+C(x, y)) \boldsymbol{e}^{\prime}\right]
\end{gathered}
$$

So $x^{-1}=\alpha$ is an eigenvalue of matrix $\boldsymbol{R}$. The terms $y^{-1}=\beta$ are associated with the eigenvalues of $\boldsymbol{R}$.

$\underbrace{\alpha_{0} \longrightarrow}_{$|  initial  |
| :---: |
|  solution  |\(} \beta_{0} \longrightarrow \alpha_{1} \xrightarrow[\begin{array}{c}vertical <br>


compensation\end{array}]{\longrightarrow} \beta_{\)|  horizontal  |
| :---: |
|  compensation  |$}^{\longrightarrow}$

## TU/e

## Matrix geometric approach

Theorem 1
The terms $\left\{\alpha_{i}\right\}$ constitute the different eigenvalues of the matrix $\boldsymbol{R}$. For eigenvalue $\alpha_{i}$ the corresponding eigenvector of the matrix $\boldsymbol{R}$ is $\boldsymbol{h}_{\boldsymbol{i}}$ with $h_{i, m}=c_{i}\left(\beta_{i-1}^{m}+f_{i} \beta_{i}^{m}\right)$.

Theorem 2
Spectral decomposition

$$
R=H^{-1} D H
$$

Truncated spectral decomposition

$$
R_{N}=H_{N}^{-1} D_{N} H_{N}
$$

## Remark

The latter is equivalent to truncating

$$
\pi(n, m)=\sum_{i=0}^{N} c_{i} \alpha_{i}^{n} \beta_{i}^{m}, n, m>0
$$

## Main results

Theorem 3
We obtain the eigenvalues of the rate matrix for the original model.

$$
\begin{aligned}
K(x, y) \Pi(x, y)= & A(x, y) \Pi(x, 0)+B(x, y) \Pi(0, y)+C(x, y) \Pi(0,0) \\
& +D(x, y) \Pi(p+(1-p) x, y)
\end{aligned}
$$

By using a similar argument as previously we obtain


## Conclusions

- Calculation of eigenvalues and eigenvectors of rate matrix for NNRW
- Efficient numerical calculation of rate matrix using spectral truncation
- Our results show promise for "non-structured" $\boldsymbol{R}$ of random walks in the quadrant


## Extensions

- Probabilistic interpretation of the product-form terms
- Use the results for approximation, i.e. approximate the invariant measure by a series (finite or infinite) of product forms.
[6] Y. Chen, R.J. Boucherie, and J. Goseling, (2016). Invariant measures and error bounds for random walks in the quarter-plane based on sums of geometric terms, arXiv:1502.07218.


[^0]:    Where innovation starts

