

Chapter 13: Bit Level Arithmetic Architectures

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- A W -bit fixed point two's complement number A is represented as :

$$A = a_{W-1} \cdot a_{W-2} \dots a_1 \cdot a_0$$

where the bits a_i , $0 \leq i \leq W-1$, are either 0 or 1, and the msb is the sign bit.

- The value of this number is in the range of $[-1, 1 - 2^{-W+1}]$ and is given by :

$$A = -a_{W-1} + \sum a_{W-1-i} 2^{-i}$$

- For bit-serial implementations, constant word length multipliers are considered. For a $W \times W$ bit multiplication the W most-significant bits of the $(2W-1)$ -bit product are retained.

- Parallel Multipliers :

$$A = a_{W-1} \cdot a_{W-2} \dots a_1 \cdot a_0 = -a_{W-1} + \sum_{i=1}^{W-1} a_{W-1-i} 2^{-i}$$

$$B = b_{W-1} \cdot b_{W-2} \dots b_1 \cdot b_0 = -b_{W-1} + \sum_{i=1}^{W-1} b_{W-1-i} 2^{-i}$$

Their product is given by :

$$P = -p_{2W-2} + \sum_{i=1}^{2W-2} p_{2W-2-i} 2^{-i}$$

In constant word length multiplication, $W - 1$ lower order bits in the product P are ignored and the Product is denoted as $X \leftarrow P = A \times B$, where

$$X = -x_{W-1} + \sum_{i=1}^{W-1} x_{W-1-i} 2^{-i}$$

- Parallel Multiplication with Sign Extension :

Using Horner's rule, multiplication of A and B can be written as

$$\begin{aligned}
 P &= A \times (-b_{W-1} + \sum b_{W-1-i} 2^{-i}) \\
 &= -A \cdot b_{W-1} + [A \cdot b_{W-2} + [A \cdot b_{W-3} + [\dots + \\
 &\quad [A \cdot b_1 + A b_0 2^{-1}] 2^{-1}] \dots] 2^{-1}] 2^{-1}
 \end{aligned}$$

where 2^{-1} denotes scaling operation.

- In 2's complement, negating a number is equivalent to taking its 1's complement and adding 1 to lsb as shown below:

$$\begin{aligned}
 -A &= a_{w-1} - \sum_{i=1}^{W-1} a_{w-1-i} 2^{-i} \\
 &= a_{w-1} + \sum_{i=1}^{W-1} (1 - a_{w-1-i}) 2^{-i} - \sum_{i=1}^{W-1} 2^{-i} \\
 &= a_{w-1} + \sum_{i=1}^{W-1} (1 - a_{w-1-i}) 2^{-i} - 1 + 2^{-W+1} \\
 &= -(1 - a_{w-1}) + \sum_{i=1}^{W-1} (1 - a_{w-1-i}) 2^{-i} + 2^{-W+1}
 \end{aligned}$$

			a_3	a_2	a_1	a_0	
			b_3	b_2	b_1	b_0	
			$-a_3b_0$	a_2b_0	a_1b_0	a_0b_0	
		$-a_3b_1$	a_2b_1	a_1b_1	a_0b_1		
	$-a_3b_2$	a_2b_2	a_1b_2	a_0b_2			
$-a_3b_3$	a_2b_3	a_1b_3	a_0b_3				
	p_6	p_5	p_4	p_3	p_2	p_1	p_0

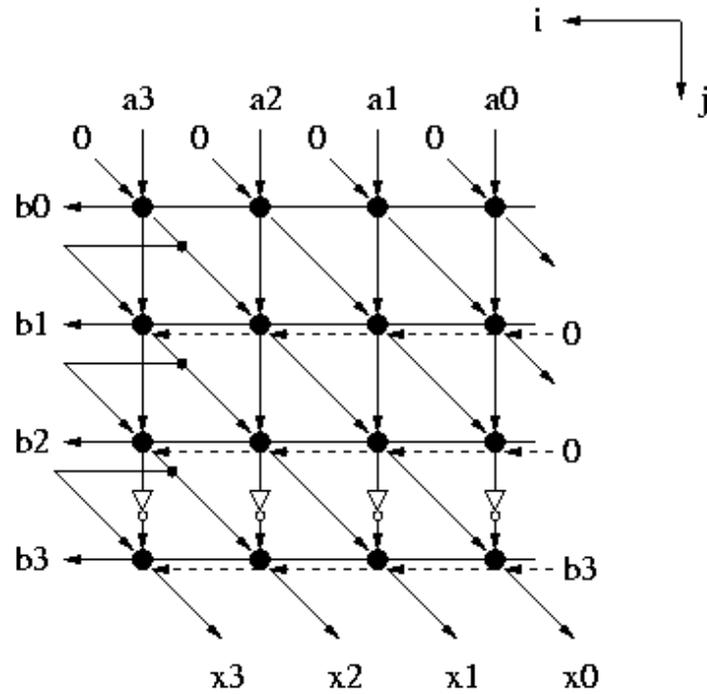
Tabular form of bit-level array multiplication

- The additions cannot be carried out directly due to terms having negative weight. Sign extension is used to solve this problem. For example,

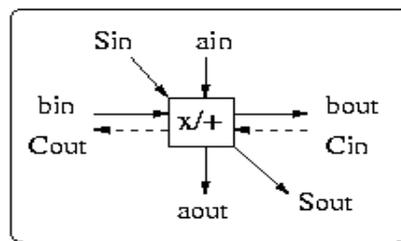
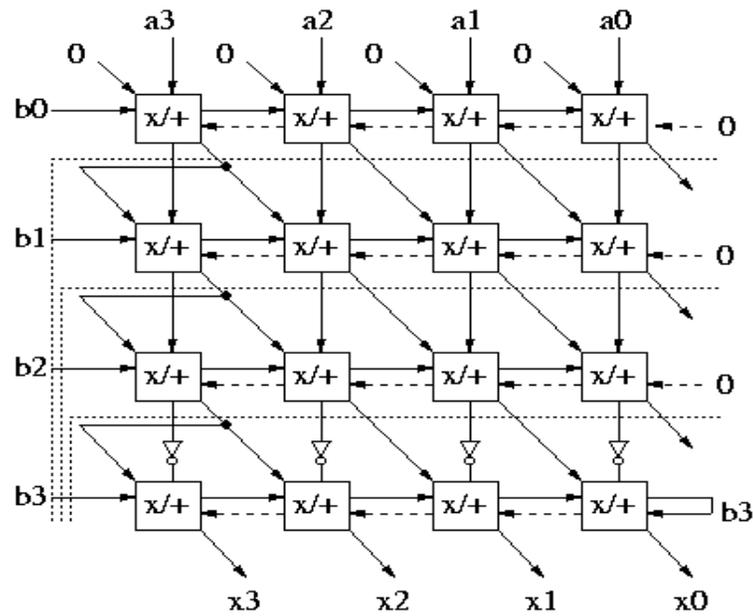
$$\begin{aligned}
 A &= a_3 + a_22^{-1} + a_12^{-2} + a_02^{-3} \\
 &= -a_32 + a_3 + a_22^{-1} + a_12^{-2} + a_02^{-3} \\
 &= -a_32^2 + a_32 + a_3 + a_22^{-1} + a_12^{-2} + a_02^{-3}
 \end{aligned}$$

describes sign extension of A by 1 and 2 bits.

- Parallel Carry-Ripple Array Multipliers :

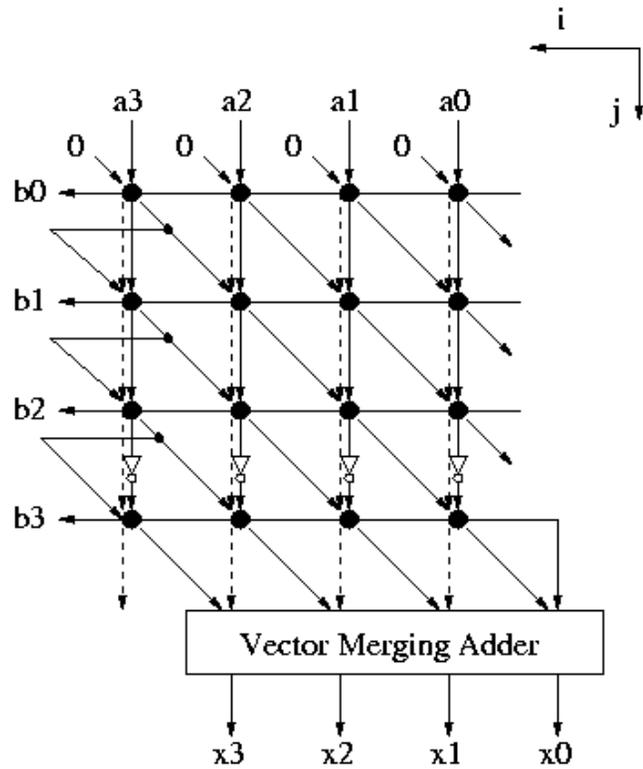


Bit level dependence Graph

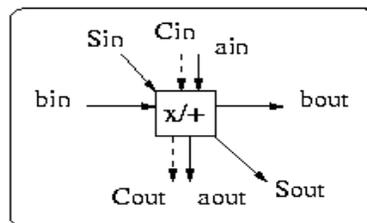
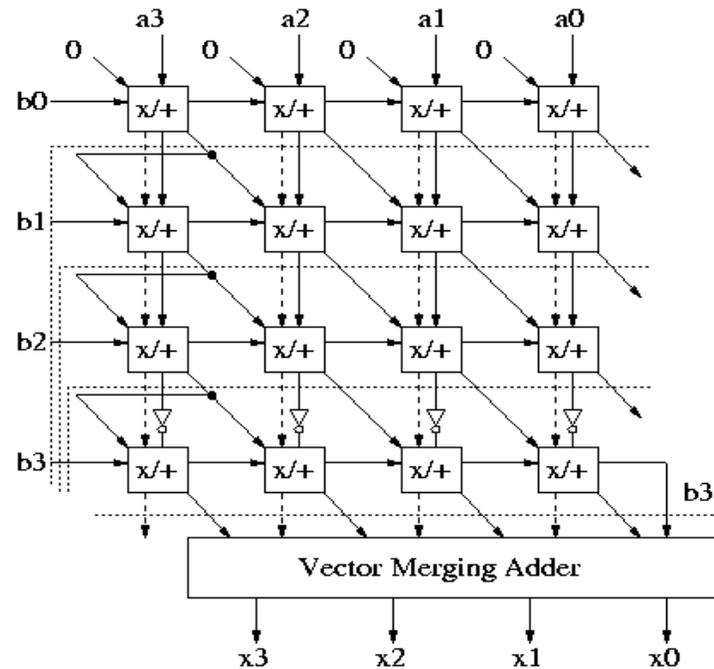


- Broadcast signals:
 $b_{out} = b_{in}; a_{out} = a_{in}$
- Single-bit Full-Adder:
 $2 C_{out} + S_{out} = a_{in} * b_{in} + S_{in} + C_{in}$

Parallel Carry Ripple Multiplier



DG for 4x4-bit carry save array multiplication



- Broadcast signals:
b_{out}=b_{in}; a_{out}=a_{in}
- Single-bit Full-Adder:
 $2 \text{Cout} + \text{Sout} = \text{ain} * \text{bin} + \text{Sin} + \text{Cin}$

Parallel carry-save array multiplier

- Baugh-Wooley Multipliers:
 - Handles the sign bits of the multiplicand and multiplier efficiently.

$$\begin{array}{rcccc}
 & & & \mathbf{a}_3 & \mathbf{a}_2 & \mathbf{a}_1 & \mathbf{a}_0 \\
 & & & \mathbf{b}_3 & \mathbf{b}_2 & \mathbf{b}_1 & \mathbf{b}_0 \\
 \hline
 & & & \overline{\mathbf{a}_3 \mathbf{b}_0} & \mathbf{a}_2 \mathbf{b}_0 & \mathbf{a}_1 \mathbf{b}_0 & \mathbf{a}_0 \mathbf{b}_0 \\
 & & & \mathbf{a}_2 \mathbf{b}_1 & \overline{\mathbf{a}_1 \mathbf{b}_1} & \mathbf{a}_0 \mathbf{b}_1 & \\
 & & & \overline{\mathbf{a}_3 \mathbf{b}_1} & \mathbf{a}_1 \mathbf{b}_2 & \mathbf{a}_0 \mathbf{b}_2 & \\
 & & & \mathbf{a}_2 \mathbf{b}_2 & \overline{\mathbf{a}_1 \mathbf{b}_2} & & \\
 & & & \overline{\mathbf{a}_3 \mathbf{b}_2} & \mathbf{a}_0 \mathbf{b}_3 & & \\
 & & & \mathbf{a}_1 \mathbf{b}_3 & & & \\
 & & \mathbf{a}_3 \mathbf{b}_3 & \overline{\mathbf{a}_2 \mathbf{b}_3} & & & \\
 \hline
 & & & \mathbf{x}_3 & \mathbf{x}_2 & \mathbf{x}_1 & \mathbf{x}_0
 \end{array}$$

Tabular form of bit-level Baugh-Wooley multiplication

- Parallel Multipliers with Modified Booth Recoding :
 - Reduces the number of partial products to accelerate the multiplication process.
 - The algorithm is based on the fact that fewer partial products need to be generated for groups of consecutive zeros and ones. For a group of “m” consecutive ones in the multiplier, i.e.,

$$\begin{aligned} \dots 0\{11\dots 1\}0\dots &= \dots 1\{00\dots \underline{0}\}0\dots - \dots 0\{00\dots 1\}0\dots \\ &= \dots 1\{00\dots 1\}0\dots \end{aligned}$$
 instead of “m” partial products, only 2 partial products need to be generated if signed digit representation is used.
 - Hence, in this multiplication scheme, the multiplier bits are first recoded into signed-digit representation with fewer number of nonzero digits; the partial products are then generated using the recoded multiplier digits and accumulated.

b_{2i+1}	b_{2i}	b_{2i-1}	b'_i	Operation	Comments
0	0	0	0	+0	string of 0's
0	0	1	1	+A	end of 1's
0	1	0	1	+A	a single 1
0	1	1	2	+2A	end of 1's
1	0	0	-2	-2A	beginning of 1's
1	0	1	-1	-A	A single 0
1	1	0	-1	-A	beginning of 1's
1	1	1	0	-0	string of 1's

Radix-4 Modified Booth Recoding Algorithm

Recoding operation can be described as:

$$b'_i = -2b_{2i+1} + b_{2i} + b_{2i-1}$$

Interleaved Floor-Plan and Bit-Plane-Based Digital Filters

- A constant coefficient FIR filter is given by:

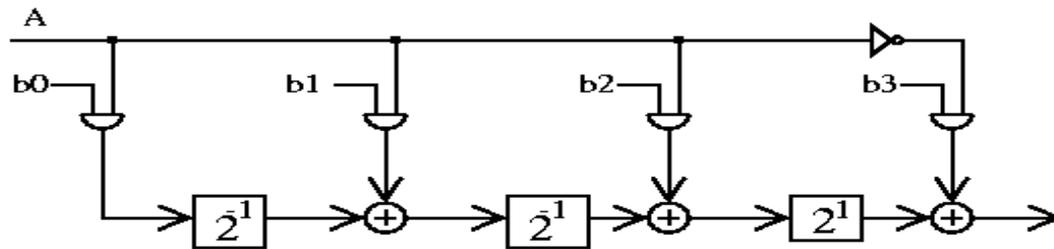
$$y(n) = x(n) + f \cdot x(n-1) + g \cdot x(n-2)$$

where, $x(n)$ is the input signal, and f and g are filter coefficients.

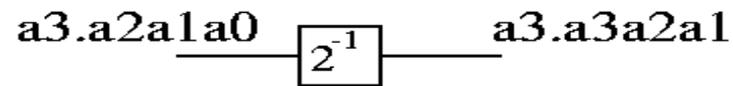
- The main idea behind the interleaved approach is to perform the computation and accumulation of partial products associated with f and g simultaneously thus increasing the speed.
- This increases the accuracy as truncation is done at the final step.
- If the coefficients are interleaved in such a way that their partial products are computed in different rows, the resulting architecture is called bit-plane architecture.

Bit-Serial Multipliers

- Lyon's Bit-Serial Multiplier using Horner's Rule :

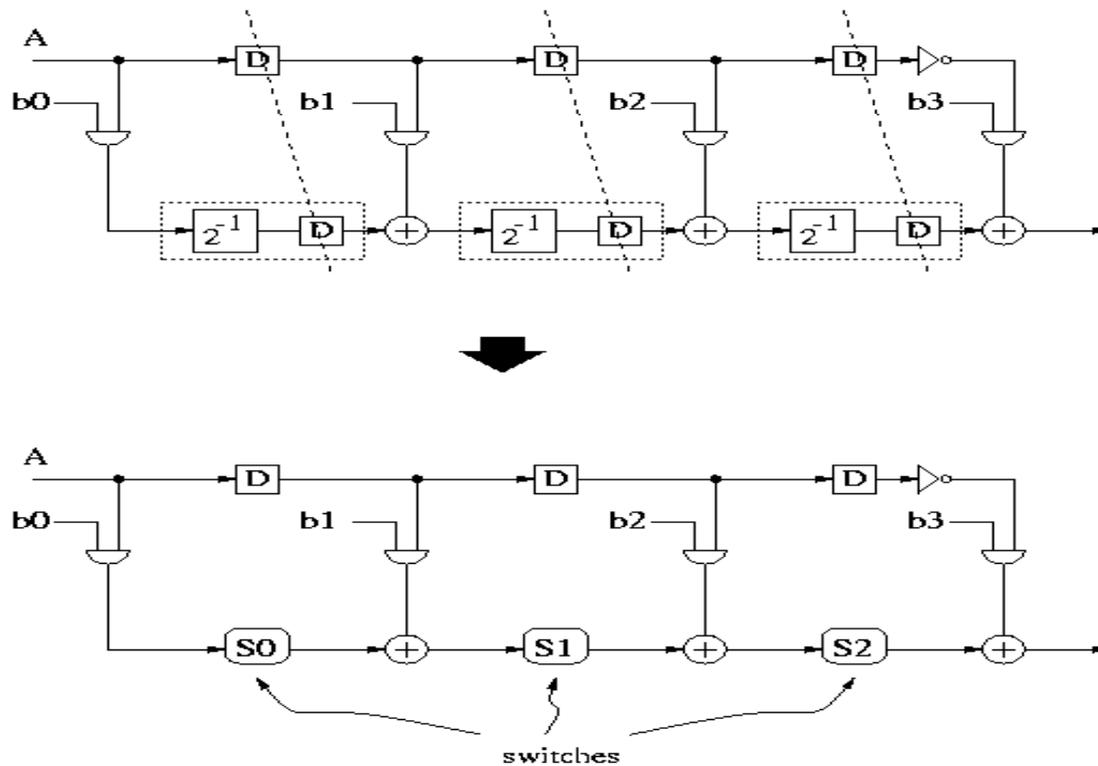


(a)

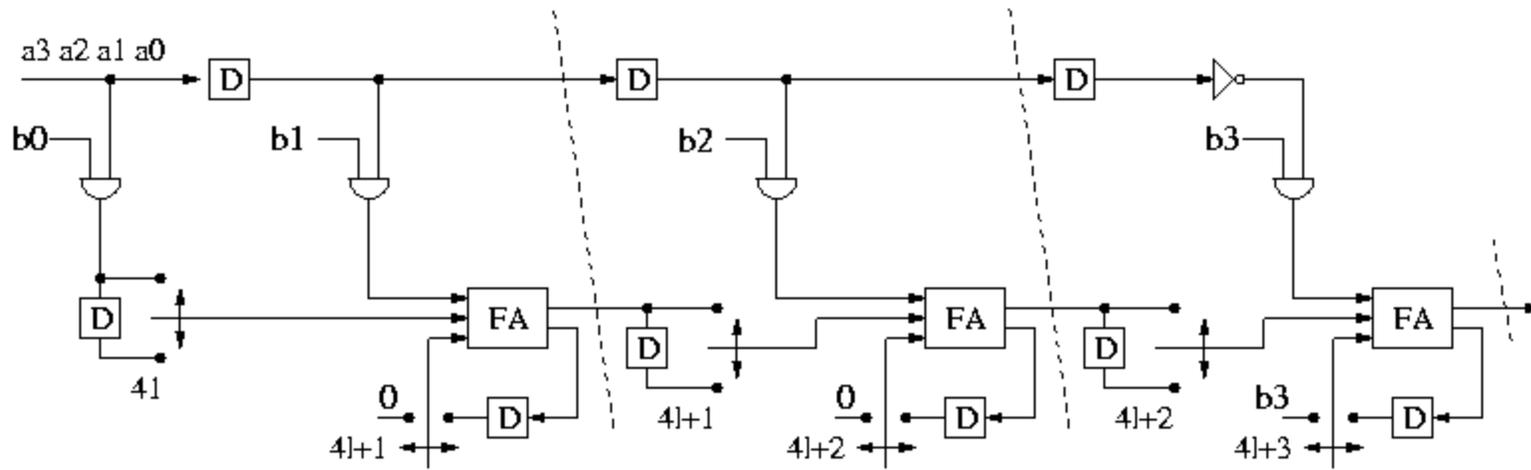


(b)

- For the scaling operator, the first output bit a_1 should be generated at the same time instance when the first input a_1 enters the operator. Since input a_1 has not entered the system yet, the scaling operator is non-causal and cannot be implemented in hardware.



Derivation of implementable bit-serial 2's complement multiplier



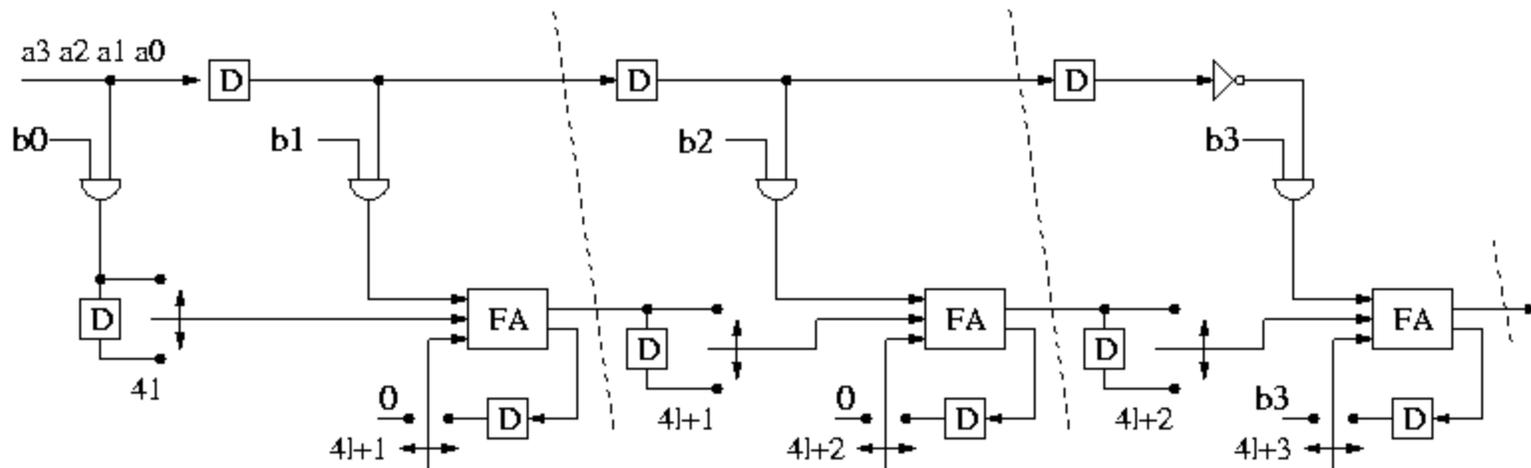
Lyon's bit-serial 2's complement multiplier

Design of Bit-Serial Multipliers Using Systolic Mappings

- Design of Lyon's bit-serial multiplier by systolic mapping Using DG of ripple carry multiplication.

Here, $d^T = [1 \ 0]$, $s^T = [1 \ 1]$ and $p^T = [0 \ 1]$

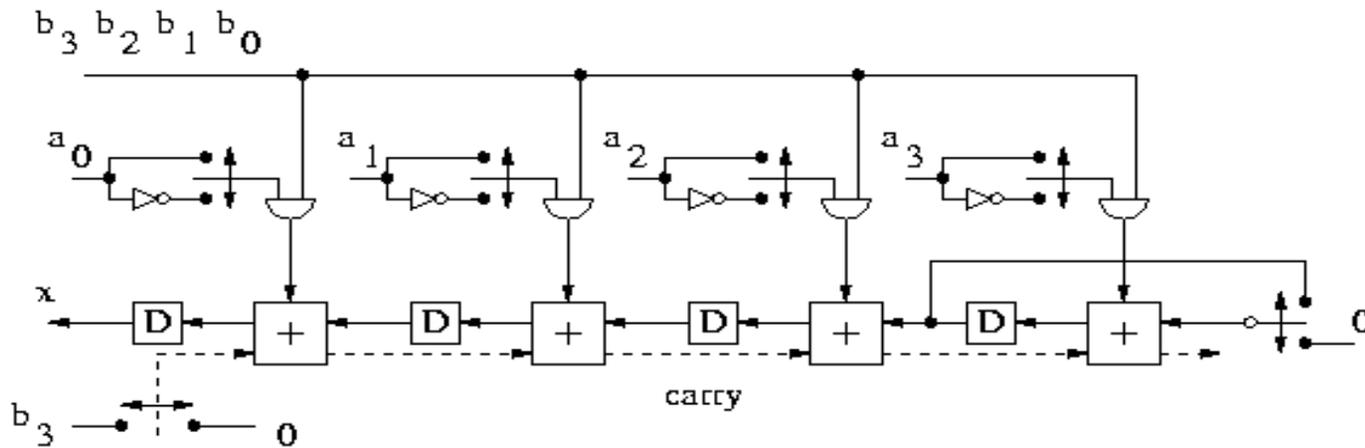
e	$p^T e$	$s^T e$
$a(0,1)$	1	1
$b(1,0)$	0	1
carry(1,0)	0	1



- Design of bit-serial multiplier by systolic mapping using DG of ripple carry multiplication and the following :

$$d^T = [0 \ 1], \quad s^T = [0 \ 1] \quad \text{and} \quad p^T = [1 \ 0]$$

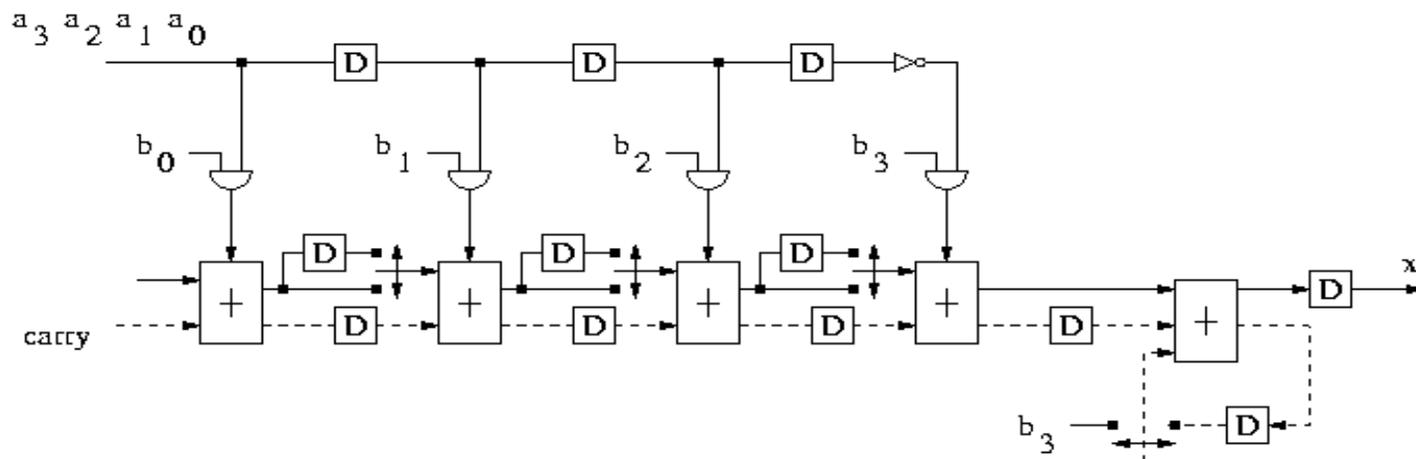
e	$p^T e$	$s^T e$
$a(0,1)$	0	1
$b(1,0)$	1	0
carry(1,0)	1	0
$x(-1,1)$	-1	1

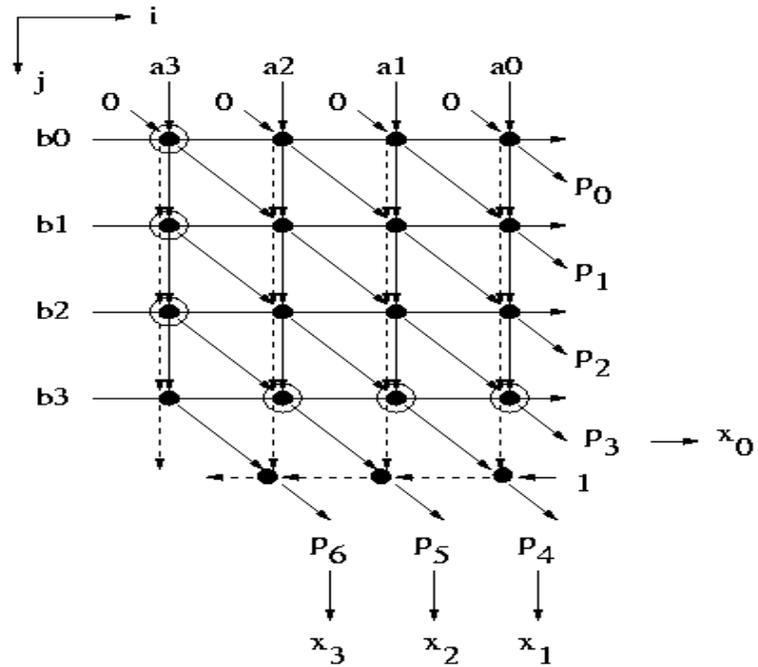


- Design of bit-serial multiplier by systolic mapping using DG for carry-save array multiplication and the following :

$$d^T = [1 \ 0], \quad s^T = [1 \ 1] \quad \text{and} \quad p^T = [0 \ 1]$$

e	$p^T e$	$s^T e$
$a(0,1)$	1	1
$b(1,0)$	1	1
carry(1,0)	0	1
$x(-1,1)$	1	0





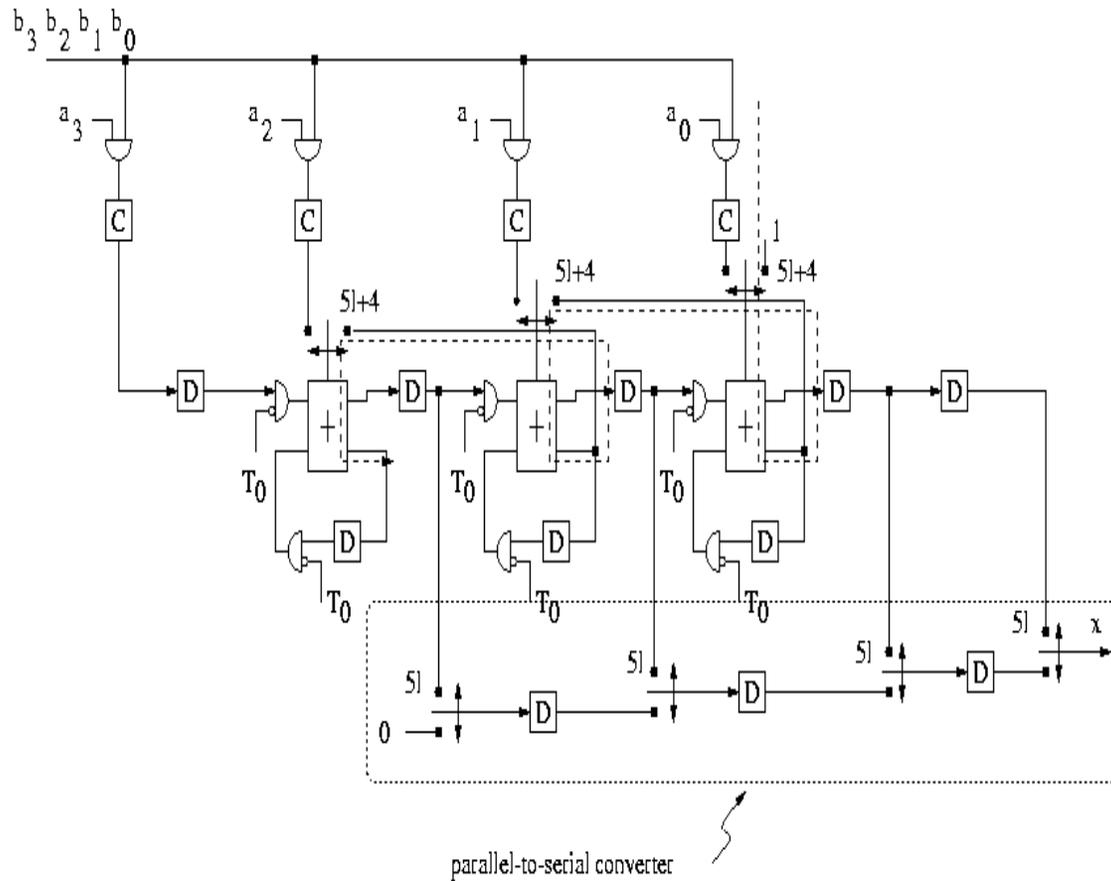
Dependence graph for carry save Baugh-Wooley multiplication with carry ripple vector merging

- Design of bit-serial Baugh-Wooley multiplier by systolic mapping using DG for Baugh-Wooley multiplication and the following :

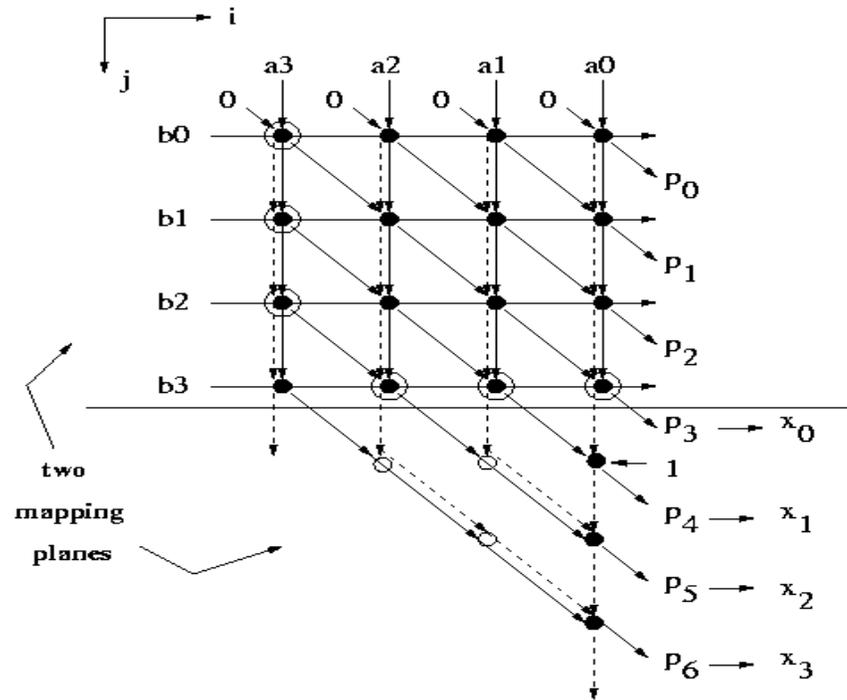
$$d^T = [0 \ 1], s^T = [0 \ 1] \text{ and } p^T = [1 \ 0]$$

e	$p^T e$	$s^T e$
$a(0,1)$	0	1
carry(0,1)	0	1
$b(1,0)$	1	0
$x(1,1)$	1	1
carry-vm(-1,0)	-1	0

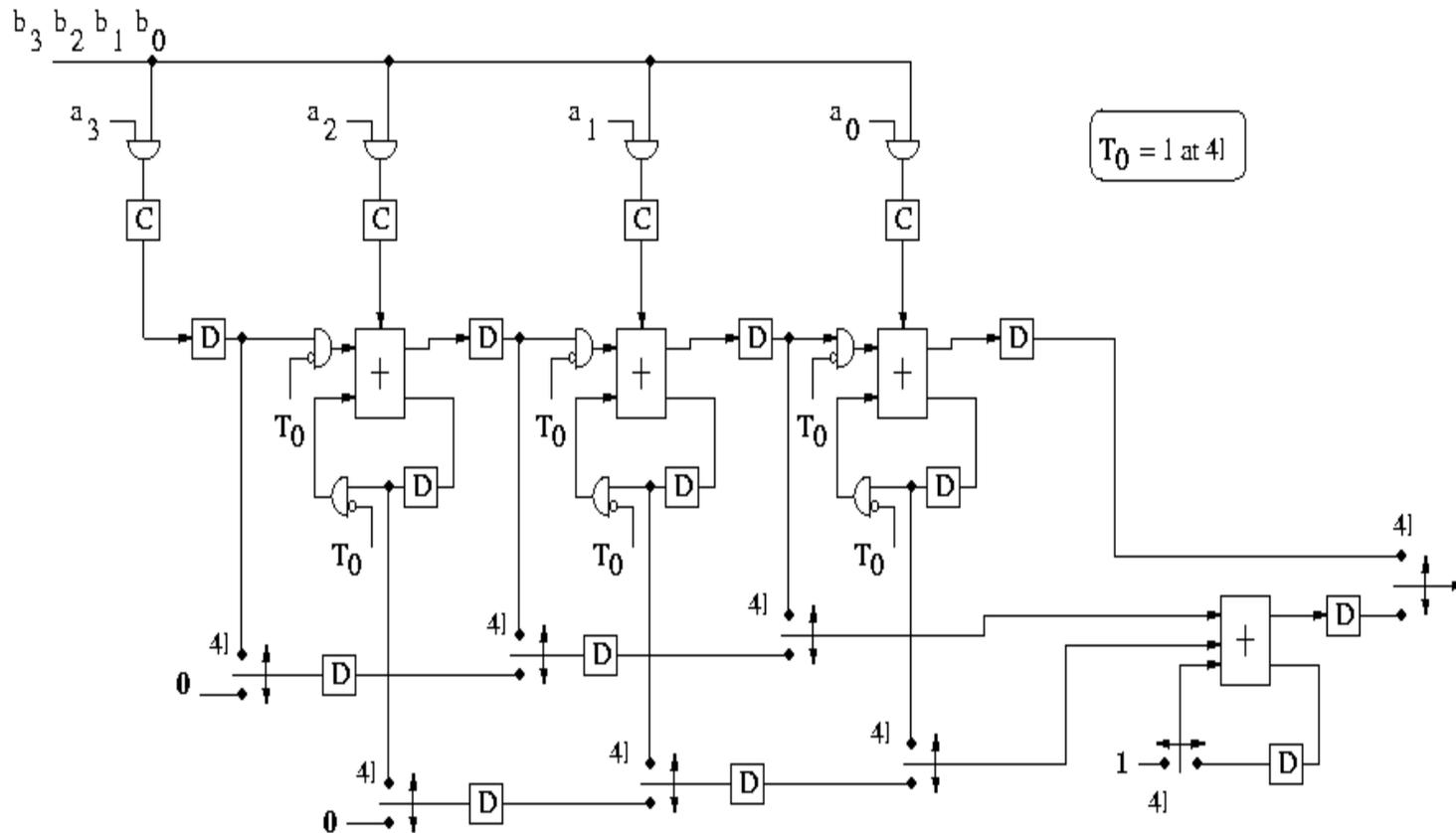
Here, carry-vm denotes the carry outputs in the vector merging portion.



Bit-Serial Baugh-Wooley Multiplier

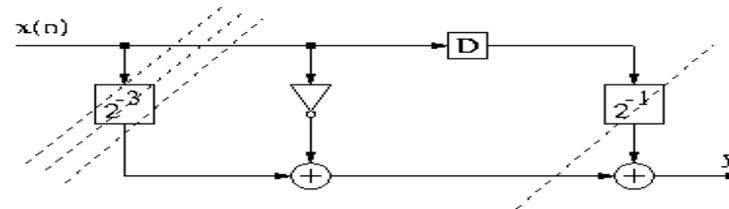


DG bit-serial Baugh-Wooley multiplier
with carry-save array and vector merging
portion treated as two separate planes

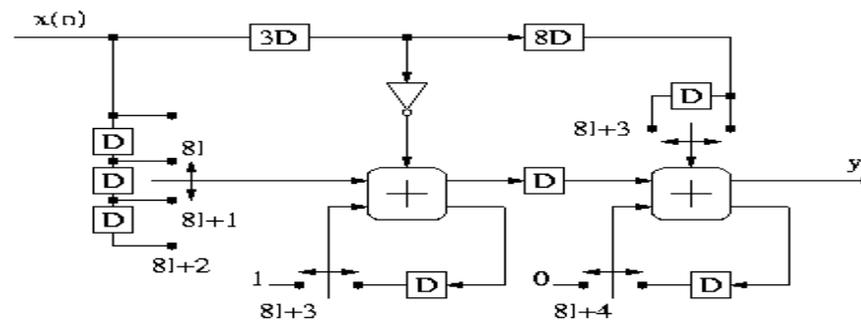


Bit-serial Baugh-Wooley multiplier
 using the DG having two separate planes
 for carry-save array and the vector merging portion

Bit-Serial FIR Filter



(a)



(b)

Bit-level pipelined bit-serial FIR filter, $y(n) = (-7/8)x(n) + (1/2)x(n-1)$, where constant coefficient multiplications are implemented as shifts and adds as $y(n) = -x(n) + x(n)2^{-3} + x(n-1)2^{-1}$.

- (a) Filter architecture with scaling operators;
- (b) feasible bit-level pipelined architecture

Bit-Serial IIR Filter

- Consider implementation of the IIR filter

$$Y(n) = (-7/8)y(n-1) + (1/2)y(n-2) + x(n)$$

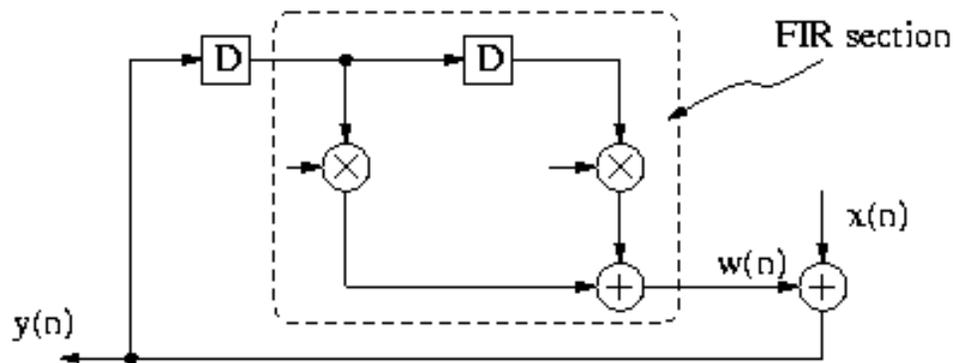
where, signal word-length is assumed to be 8.

- The filter equation can be re-written as follows:

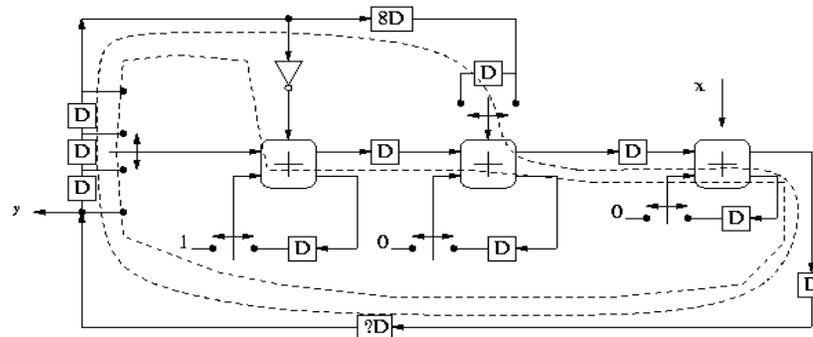
$$w(n) = (-7/8)y(n-1) + (1/2)y(n-2)$$

$$Y(n) = w(n) + x(n)$$

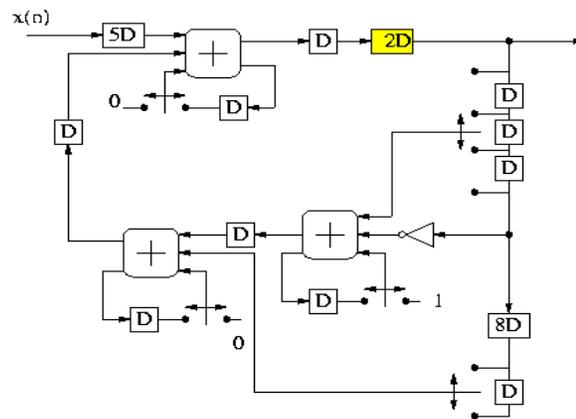
which can be implemented as an FIR section from $y(n-1)$ with an addition and a feedback loop as shown below:



- Steps for deriving a bit-serial IIR filter architecture:
 - A bit-level pipelined bit-serial implementation of the FIR section needs to be derived.
 - The input signal $x(n)$ is added to the output of the bit-serial FIR section $w(n)$.
 - The resulting signal $y(n)$ is connected to the signal $y(n-1)$.
 - The number of delay elements in the edge marked D needs to be determined.(see figure in next page)
- For, systems containing loop, the total number of delay elements in the loops should be consistent with the original SFG, in order to maintain synchronization and correct functionality.
- **Loop delay synchronization** involves matching the number of word-level loop delay elements and that in the bit-serial architecture. The number of bit-level delay elements in the bit-serial loops should be $W \times N_D$, where W is signal word-length and N_D denotes the number of delay elements in the word-level SFG.



(a)



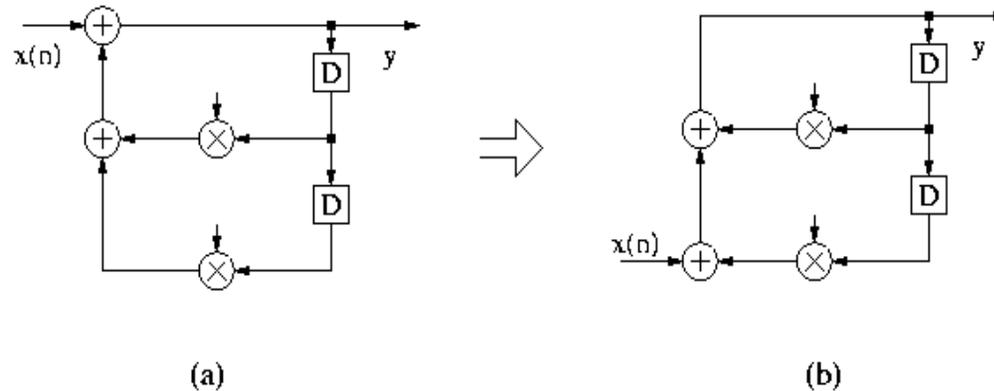
(b)

- Bit-level pipelined bit-serial architecture, without synchronization delay elements. (b) Bit-serial IIR filter. Note that this implementation requires a minimum feasible word-length of 6.

Note:

- To compute the total number of delays in the bit-level architecture, the paths with the **largest number of delay elements** in the switching elements should be counted.
- Input synchronizing delays (also referred as **shimming** delays or **skewing** delays).
- It is also possible that the loops in the intermediate bit-level pipelined architecture may contain more than $W \times N_D$ number of bit-level delay elements, in which case the word-length needs to be increased.
- The architecture without the two loop synchronizing delays can function correctly with a signal word-length of 6, which is the minimum word-length for the bit-level pipelined bit-serial architecture.

- **Associativity transformation** :



Loop iteration bound of IIR filter can be reduced from one-multiply-two-add to one-multiply-add by associative transformation

Canonic Signed Digit Arithmetic

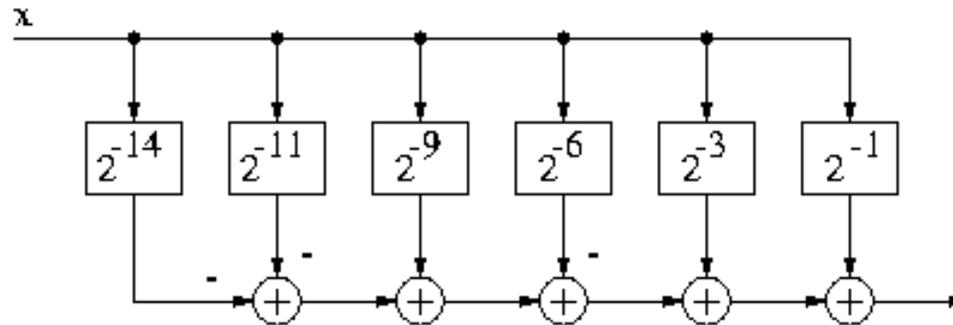
- Encoding a binary number such that it contains the fewest number of non-zero bits is called **canonic signed digit**(CSD).
- The following are the properties of CSD numbers:
 - No 2 consecutive bits in a CSD number are non-zero.
 - The CSD representation of a number contains the minimum possible number of non-zero bits, thus the name canonic.
 - The CSD representation of a number is unique.
 - CSD numbers cover the range $(-4/3, 4/3)$, out of which the values in the range $[-1, 1)$ are of greatest interest.
 - Among the W -bit CSD numbers in the range $[-1, 1)$, the average number of non-zero bits is $W/3 + 1/9 + O(2^{-W})$. Hence, on average, CSD numbers contains about 33% fewer non-zero bits than two's complement numbers.

- Conversion of W -bit number to CSD format:
 - $A = a'_{W-1} \cdot a'_{W-2} \dots a'_1 \cdot a'_0 = 2$'s complement number
 - Its CSD representation is $a_{W-1} \cdot a_{W-2} \dots a_1 \cdot a_0$
- Algorithm to obtain CSD representation:
 - $a'_{-1} = 0;$
 - $\gamma_{-1} = 0;$
 - $a'_W = a'_{W-1};$
 - for ($i = 0$ to $W-1$)
 - {
 - $\theta_i = a'_i \oplus a'_{i-1};$
 - $\gamma_i = \overline{\gamma_{i-1}} \theta_i;$
 - $a_i = (1 - 2a'_{i+1})\gamma_i;$
 - }

i	W	$W-1$								0	-1
a'_i	1	1	0	1	1	1	0	0	1	1	
θ_i		1	1	0	0	1	0	1	0	1	
γ_i		0	1	0	0	1	0	1	0	1	
$1 - 2a'_{i+1}$		-1	-1	1	-1	-1	-1	1	1	-1	
a_i		0	-1	0	0	-1	0	1	0	-1	

Table showing the computation of the CSD representation for the number 1.01110011.

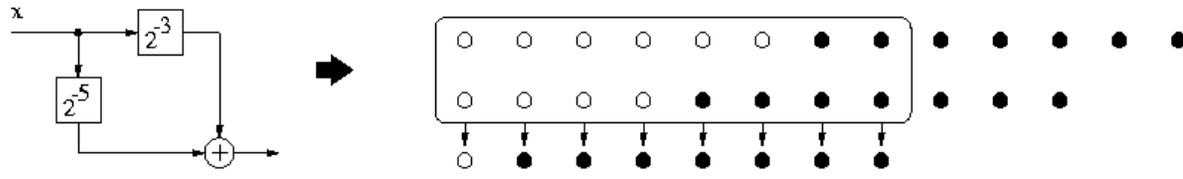
CSD Multiplication



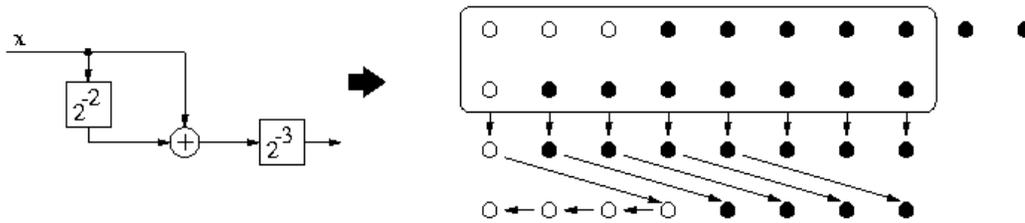
A CSD multiplier using linear arrangement of adders to compute $x \times 0.10100100101001$

- Horner's rule for precision improvement : This involves delaying the scaling operations common to the 2 partial products thus increasing accuracy.
- For example, $x \cdot 2^{-5} + x \cdot 2^{-3}$ can be implemented as $(x \cdot 2^{-2} + x)2^{-3}$ to increase the accuracy.

$x \rightarrow$ ○ ● ● ● ● ● ● ●

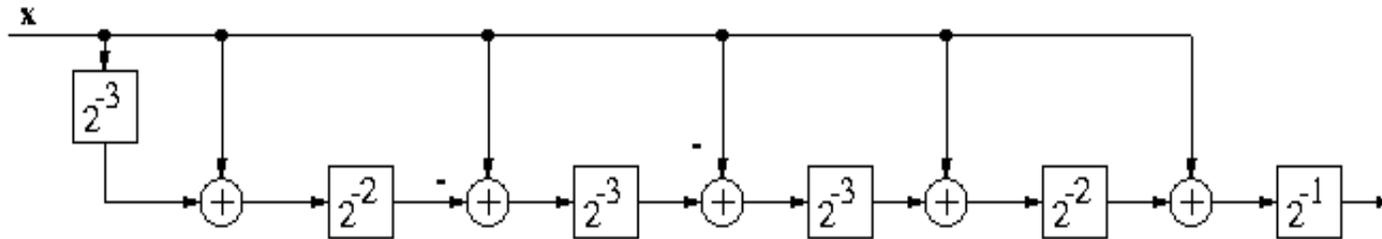


(a)



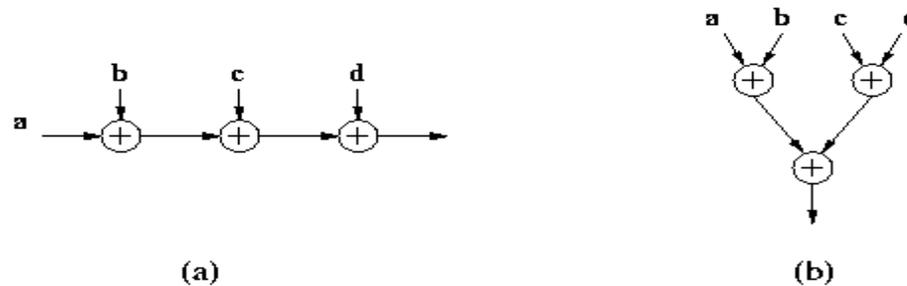
(b)

Using Horner's rule for partial product accumulation to reduce the truncation error.

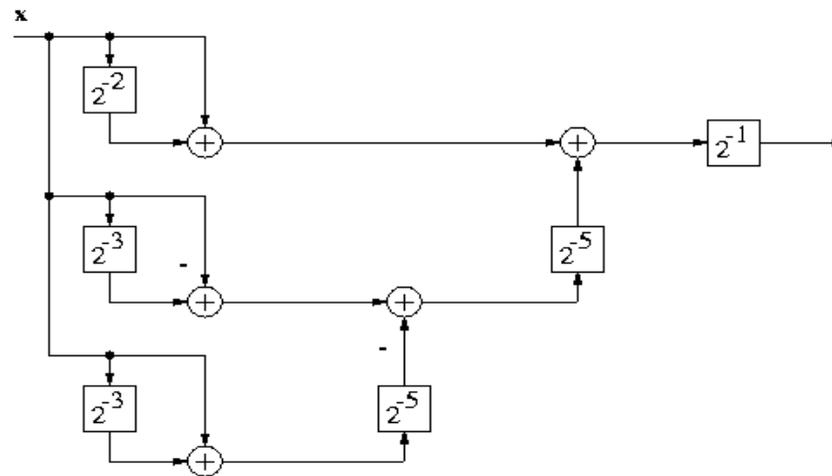


Rearrangement of the CSD multiplication of $x \times 0.10100100101001$ using Horner's rule for partial product accumulation to reduce the truncation error.

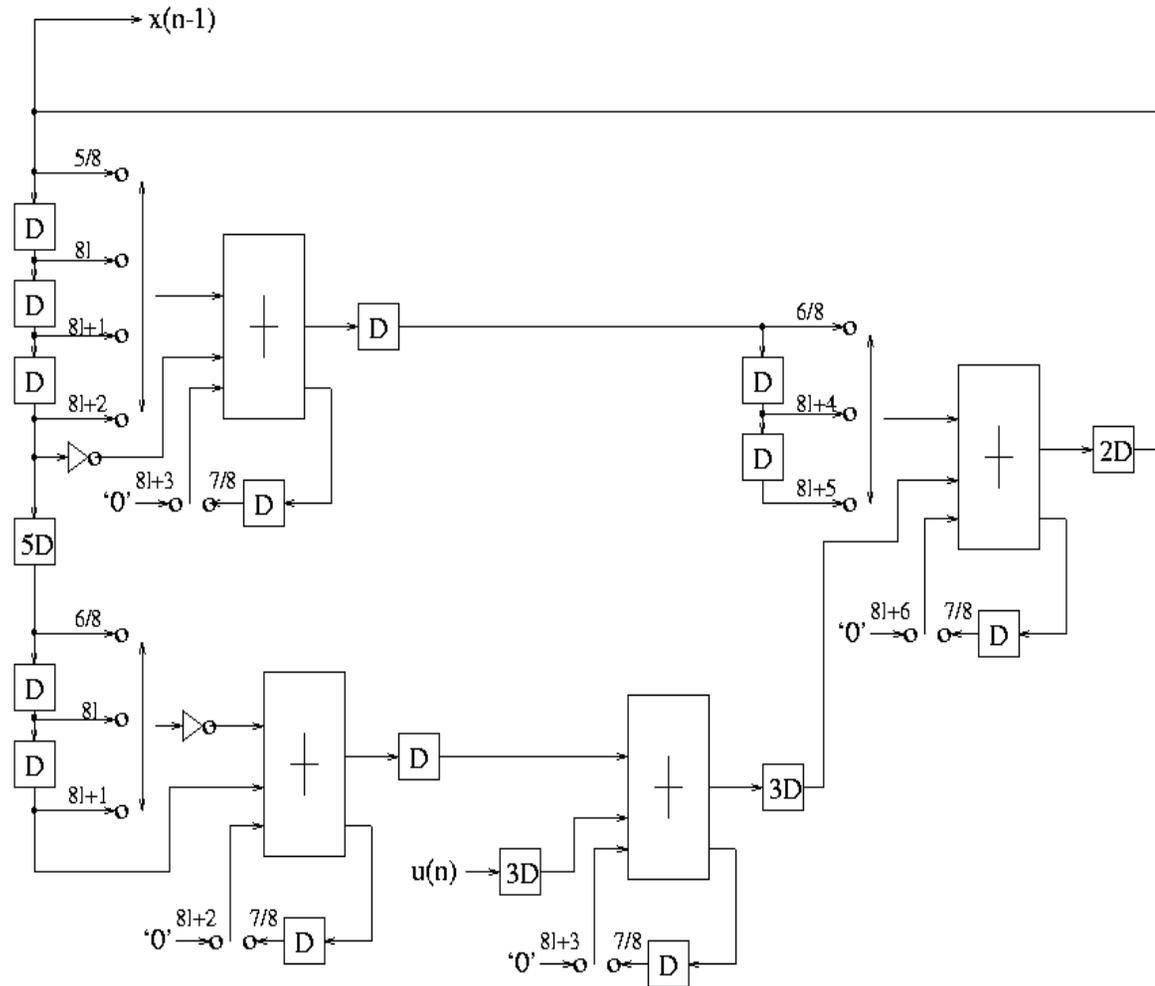
Use of Tree-Height Reduction for Latency Reduction



(a) linear arrangement (b) tree arrangement



Combination of tree-type arrangement and Horner's rule for the accumulation of partial products in CSD multiplication



Bit serial architecture using CSD. In this case the coefficients $-7/32 = -1/4 + 1/32$ is encoded as $0.0\bar{1}001$ and $3/4 = 1 - 1/4$ is encoded as $1.0\bar{1}$.