# Exercises Algorithms for Model Checking

#### $1 \quad \text{CTL}^*$

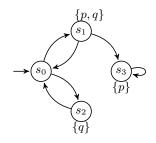


Figure 1:

- 1. For each of the CTL<sup>\*</sup> formulae below, indicate whether it is (syntactically) a formula in LTL and/or CTL. Determine for each formula in which states of the Kripke Structure of Fig. 1 it holds.
  - (a) p,
  - (b)  $\mathsf{E}[q \mathsf{R} p]$ ,
  - (c) E F G *p*,
  - (d) AGF p,
  - (e) A G E F p,
  - (f) A G F  $(p \land X q)$ ,
  - (g) A G  $(\neg q \lor \mathsf{F} p)$ ,
  - (h) A ((G p)  $\lor$  (F q))
- 2. For each pair of CTL<sup>\*</sup> formulae below, if possible, give a Kripke Structure in which both are valid, a Kripke Structure in which both are not valid, and a Kripke Structure in which only one of them is valid.
  - (a) p and A F p
  - (b)  ${\sf A} \; {\sf F} \; {\sf A} \; {\sf G} \; p$  and  ${\sf A} \; {\sf G} \; {\sf A} \; {\sf F} \; p$
  - (c) A F A X p and A F X p
  - (d) A X E X p and A X X p
  - (e) A X A X p and A X X p
  - (f) A [p U q] and A [ $\neg q$  R  $\neg p$ ]
- 3. Consider LTL, CTL and CTL<sup>\*</sup>. State for each of the claims below whether they hold or not. Motivate your answer by providing counterexamples or a formal justification.

- (a) Every CTL<sup>\*</sup> formula is equivalent to either an LTL formula or a CTL formula.
- (b) The language LTL is more expressive than CTL.
- (c) The language CTL is more expressive than LTL.
- (d) On deterministic Kripke Structures (i.e., Kripke Structures with a single initial state in which each state has exactly one successor), LTL and CTL are equally expressive; that is, every LTL formula has an equivalent CTL formula and vice versa.
- 4. Express that along all paths, proposition p holds infinitely often and  $\neg p$  holds infinitely often.
- 5. Express that along all paths, proposition p holds infinitely often and  $\neg p$  only holds finitely often.
- 6. Prove using the semantics of  $\mathsf{CTL}^*,$  or disprove using a Kripke Structure, the following equivalences:
  - (a) A  $[\phi \cup \psi] \equiv \neg (\mathsf{E} [\neg \psi \cup \neg (\phi \lor \psi)] \lor \mathsf{E} \mathsf{G} \neg \psi)$
  - (b) AGAF $p \equiv$ AGFp

### 2 Model Checking CTL and Fair CTL

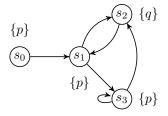


Figure 2:

- 1. For each of the CTL formulae below, draw a Kripke Structure in which the formula holds, a Kripke Structure in which it does not hold, but in which it does hold fairly with an appropriate fairness constraint. Also provide this fairness constraint.
  - (a) A G A F  $(\neg p \lor q)$
  - (b)  $q \wedge \mathsf{A} \mathsf{F} q \wedge \neg(\mathsf{E} [\neg q \mathsf{R} \neg p])$
  - (c)  $\neg AF \ p \lor E \ G \ (\neg p \lor q)$
  - (d)  $(p \lor \mathsf{A} \mathsf{F} p) \land \neg \mathsf{E} \mathsf{G} p$
- 2. Determine for each of the following CTL formulae in which states of the Kripke Structure of Fig. 1 it holds using the labelling algorithm. Repeat the exercise using the symbolic model checking algorithm for CTL, using explicit set notation to represent sets of states, rather than BDDs.
  - (a) p,
  - (b)  $\mathsf{E}[q \mathsf{R} p]$ ,
  - (c) A G E F p,
  - (d) A G  $p \lor \mathsf{A}$  F q
  - (e) A F q
  - (f) A [q R p]
- 3. Extend the Kripke Structure of Fig. 1 with the Fairness constraints  $F = \{ \{s_1\}, \{s_2\} \}$ . In which states do the formulae of exercise 2 *fairly* hold? Repeat the exercise using fairness constraint  $F = \{ \{s_3\} \}$ .
- 4. Answer Exercises 2 and 3 for the Kripke Structure in Fig. 2 instead of the Kripke Structure of Fig. 1.
- 5. Prove that  $A \in f = \mu Z.f \cup A \times Z.$

## 3 Counterexamples and Witnesses

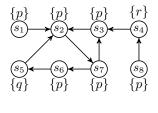


Figure 3:

- 1. Consider the Kripke Structure in Fig. 3.
  - (a) Fairness constraint:  $\neg r$  and q. Check that  $s_1 \models_F \mathsf{E} \mathsf{G} (p \lor q)$ .
  - (b) Construct a witness for  $s_1 \models_F \mathsf{E} \mathsf{G} (p \lor q)$ , using the techniques for symbolic model checking.

### 4 Equivalences and Pre-Orders

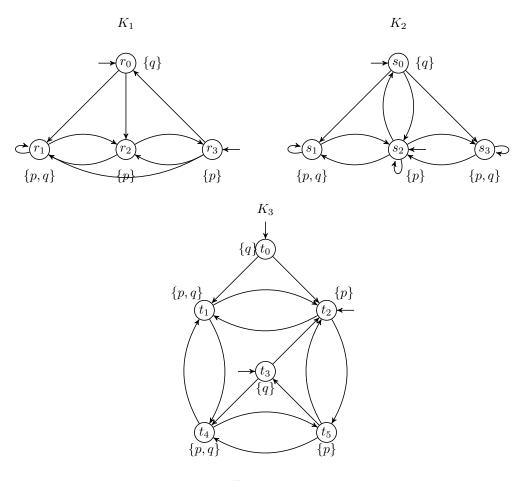


Figure 4:

- 1. Let  $K_1$  and  $K_2$  be arbitrary Kripke Structures. Let f be an arbitrary ACTL<sup>\*</sup> formula such that  $K_1 \models f$  and  $K_2 \not\models f$ . Prove that there must be a formula g in positive form such that  $K_1 \not\models g$  and  $K_2 \models g$ , and all path quantifiers in g are existential path quantifiers.
- 2. For each pair of Kripke Structures  $K_i, K_j$  in Fig. 4, prove or disprove  $K_i \sqsubseteq K_j$ , either by providing a simulation relation, or by providing a distinguishing ACTL-formula f (i.e.,  $K_i \models f$  and  $K_j \not\models f$ ).
- 3. For each pair of Kripke Structures  $K_i, K_j$  in Fig. 4, prove or disprove  $K_i \equiv K_j$ , either by computing a bisimulation relation, or by providing a distinguishing CTL-formula f (i.e.,  $K_i \models f \Leftrightarrow K_j \not\models f$ ).