

# Separator-based Pruned Dynamic Programming for Steiner Tree

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<https://www.aaai.org/Papers/AAAI/2019/AAAI-IwataY.4578.pdf>

# Steiner Tree Problem

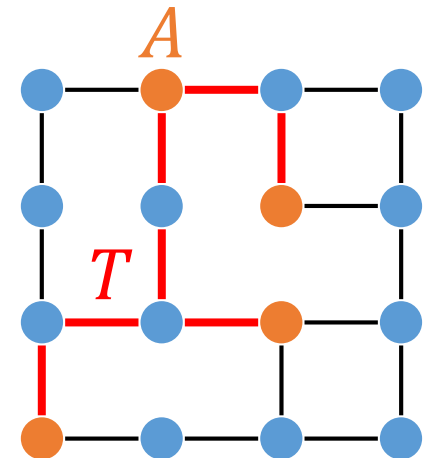
## Steiner tree problem

Input: graph  $G$ , terminals  $A \subseteq V(G)$

Output: minimum-weight tree connecting  $A$

Various applications:

- ✓ VLSI design
- ✓ fiber-optic network design
- ✓ team formulation in social networks



# PACE Challenge 2018

<https://pacechallenge.wordpress.com/pace-2018/>

## Track 1: small number of terminals ( $|A| \leq 136$ )

- ✓  $O\left(3^{|A|}n + 2^{|A|}(m + n \log n)\right)$  by DP [Erickson-Monma-Veinott 87]
- ✓ EMV +  $A^*$ -search [Hougardy-Silvanus-Vygen 17]

## Track 2: small tree-width ( $w \leq 47$ )

- ✓  $w^{O(w)}m$  by DP
- ✓  $2^{O(w)}m$  by a rank-based DP [Bodlaender-Cygan-Kratsch-Nederlof 15]

## Track 3: heuristic

# Results

<https://pacechallenge.org/files/PACE18-report.pdf>

## Track 1: small number of terminals

1. Our team solved 95/100 by *pruned DP*
2. Maziarz and Polak solved 94/100 by HSV
3. Koch and Rehfeldt solved 93/100 by ILP

## Track 2: small tree-width

1. Koch and Rehfeldt solved 92/100 by ILP
2. Our team solved 77/100 by *pruned DP* +  $w^w$ -DP
3. Tom van der Zanden solved 58/100 by rank-based DP

for public instances:

pruned DP alone solved 81/100

$w^w$ -DP alone solved 44/100

combined solved 84/100

# Outline

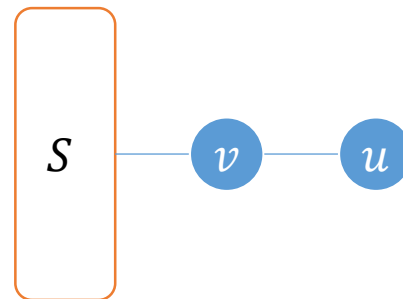
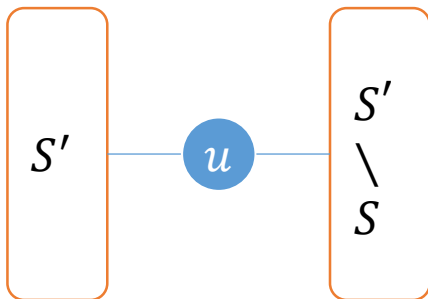


1. EMV Algorithm
2. Separator-based Pruning
3. Other techniques
4. Experiments

# Dynamic Programming [Dreyfus-Wagner 71]

For  $S \subseteq V$ , let  $\text{opt}(S) :=$  weight of min Steiner tree for terminals  $S$ .

$$\begin{aligned} & \text{opt}(S \cup \{u\}) \\ &= \min \begin{cases} \text{opt}(S' \cup \{u\}) + \text{opt}((S \setminus S') \cup \{u\}) & (S' \subseteq S) \\ \text{opt}(S \cup \{v\}) + w(vu) & (vu \in E(G)) \end{cases} \end{aligned}$$



# EMV Algorithm [Erickson-Monma-Veinott 87]

$d(S, u) = \infty$  for  $\forall S \subseteq A$  and  $\forall u \in V$

$d(\{a\}, a) = 0$  for  $\forall a \in A$

for  $S \subseteq A$  in ascending order of  $|S|$

    update  $d(S, u)$  for  $\forall u$  by Dijkstra

    for  $S' \subseteq A \setminus S$

        update  $d(S \cup S', u)$  for  $\forall u$

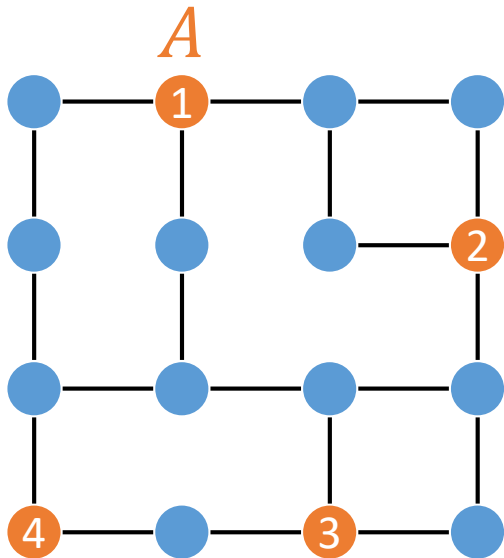
$O\left(3^{|A|}n + 2^{|A|}(m + n \log n)\right)$  time

Can we avoid computing all  $d(S, u)$ ?

→ Yes, for special instances. [EMV 87]

# Special Case [Erickson-Monma-Veinott 87]

If the graph is planar and all the terminals are on a single face, the running time is improved to  $O(|A|^3 n + |A|^2 n \log n)$ .

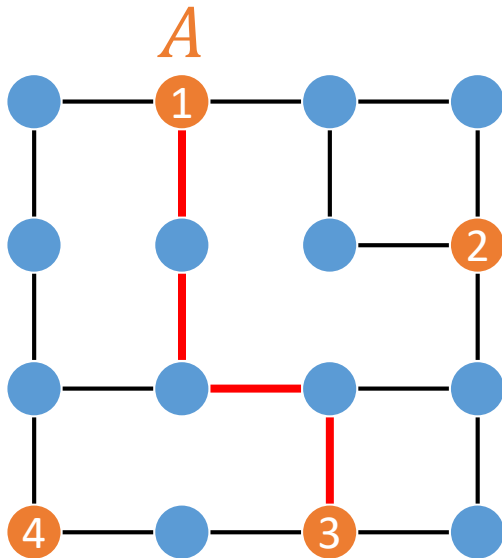




# Special Case [Erickson-Monma-Veinott 87]

If the graph is planar and all the terminals are on a single face, the running time is improved to  $O(|A|^3 n + |A|^2 n \log n)$ .

But, of course, this is too special to apply in practice...



Steiner tree for  $\{1, 3\}$  always *separates*  $\{2, 4\}$ . So we can skip the computation of  $d(\{1, 3\}, *)$ .

In general, we only need to compute  $d(\{i, i + 1, \dots, j\}, *)$

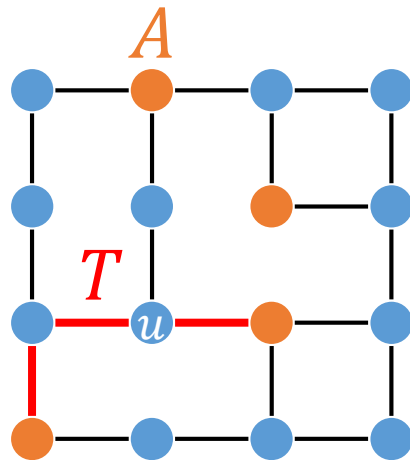
# Outline



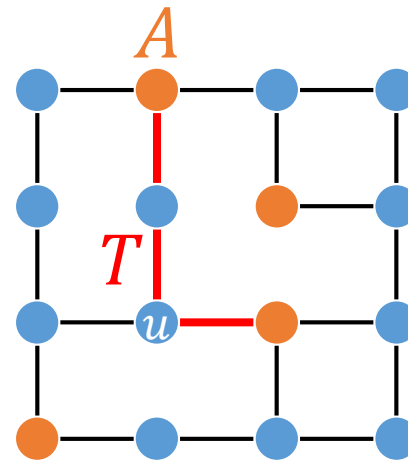
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# Important Partial Solution

A Steiner tree  $T$  for  $S \cup \{u\}$  is called *important* if there is a Steiner tree  $T'$  for  $(A \setminus S) \cup \{u\}$  s.t.  $T + T'$  is a minimum Steiner tree for  $A$ .



important



unimportant

# Important Partial Solution

A Steiner tree  $T$  for  $S \cup \{u\}$  is called *important* if there is a Steiner tree  $T'$  for  $(A \setminus S) \cup \{u\}$  s.t.  $T + T'$  is a minimum Steiner tree for  $A$ .

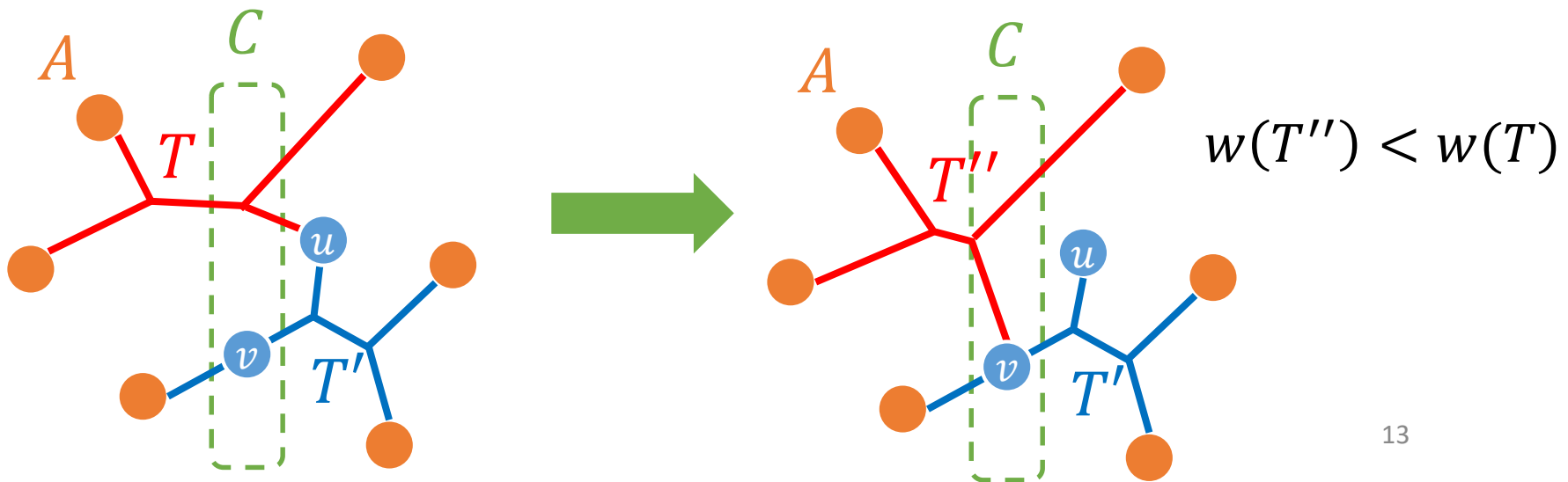
In EMV algorithm, we can safely skip computations for unimportant  $(S, u)$ .

But how can we check the importance?

# Necessary Condition of Importance

## Key Lemma:

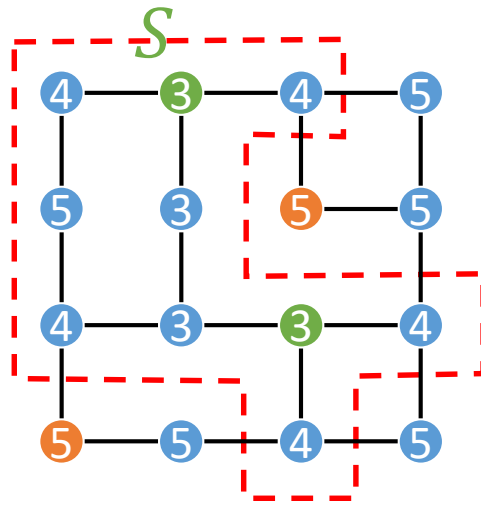
A Steiner tree  $T$  for  $S \cup \{u\}$  is not important if there is an  $(A \setminus S)$ -separator  $C$  such that for every  $v \in C$ , there is a Steiner tree for  $S \cup \{v\}$  of weight strictly less than the weight of  $T$ .



# Separator Construction

After computing  $d(S,*)$ , we compute the minimum  $x$  s.t.  $C_x := \{u \in V \mid d(S, u) \leq x\}$  separates  $A \setminus S$ .

Then,  $C_x$  satisfies the condition for every  $(S, u)$  with  $d(S, u) > x$ .



# Pruned DP Algorithm

$P \leftarrow \emptyset$  # set of processed  $S$

while  $\exists$  unprocessed  $S$  s.t.  $d(S, u) \neq \infty$  for some  $u$

pick smallest such  $S$

update  $d(S, u)$  for  $\forall u$  by Dijkstra

compute minimum  $x$  s.t.  $C_x$  separates  $A \setminus S$

drop  $(S, u)$  from  $d$  for  $\forall (S, u)$  s.t.  $d(S, u) > x$

for  $S' \in P$  s.t.  $S \cap S' \neq \emptyset$

update  $d(S \cup S', u)$  for  $\forall u$

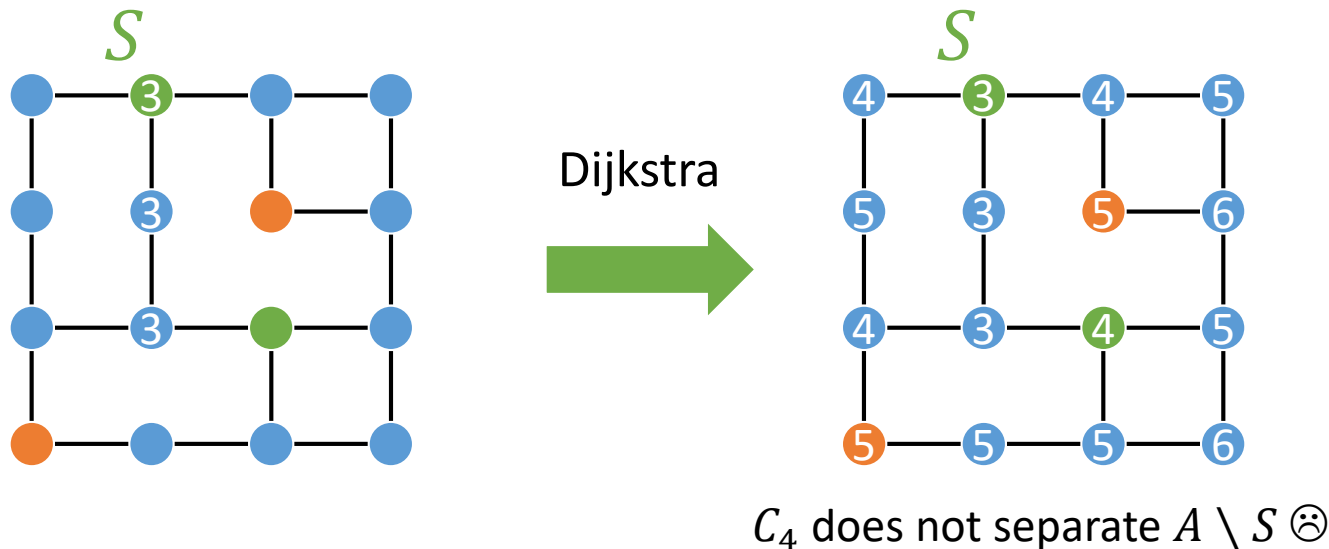
push  $S$  into  $P$

# Restore dropped information (1)

For unimportant  $(S, u)$ , we may have

$$d(S, u) > \text{opt}(S \cup \{u\}).$$

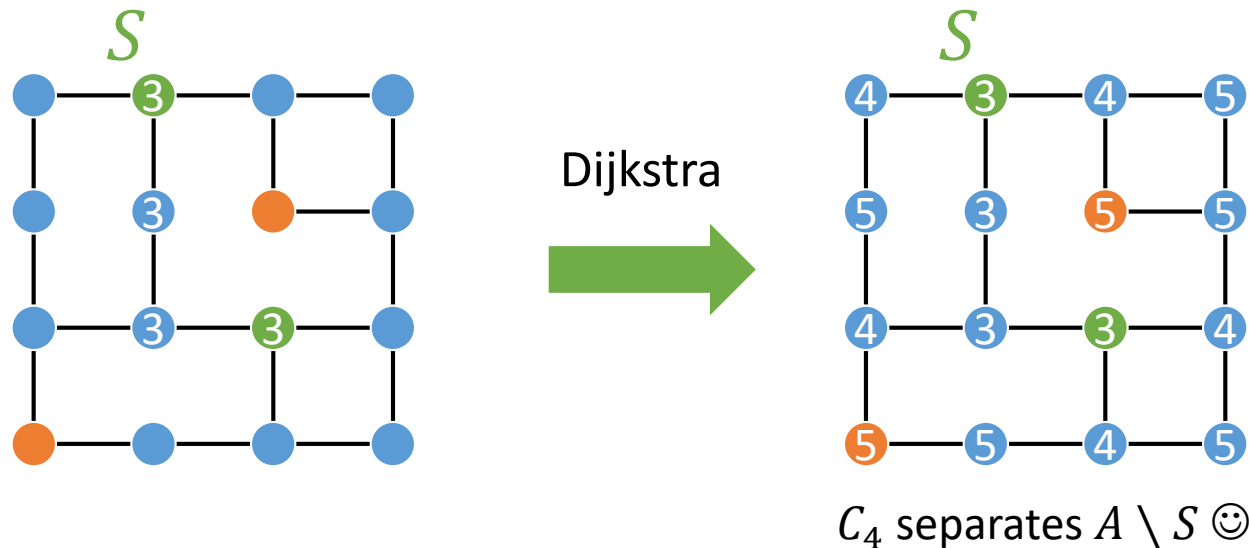
This can interfere with the pruning...





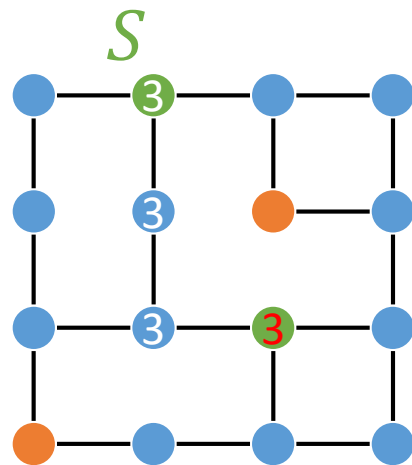
# Restore dropped information (2)

Before running Dijkstra, we partially restore  $d(S, u)$  as follows. For each  $u$  with  $d(S, u) \neq \infty$ , we construct the corresponding Steiner tree  $T_u$  for  $S \cup \{u\}$ , and update  $d(S, v)$  with  $d(S, u)$  for  $\forall v \in V(T_u)$ .

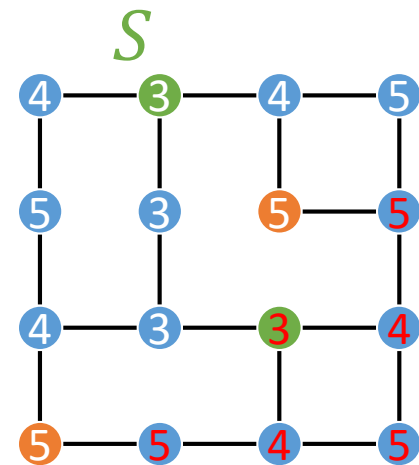


# Restore dropped information (3)

If a Steiner tree  $T$  for  $S \cup \{u\}$  is unimportant,  $T + P_{uv}$  is also unimportant. So we can safely drop such  $(S, v)$ .



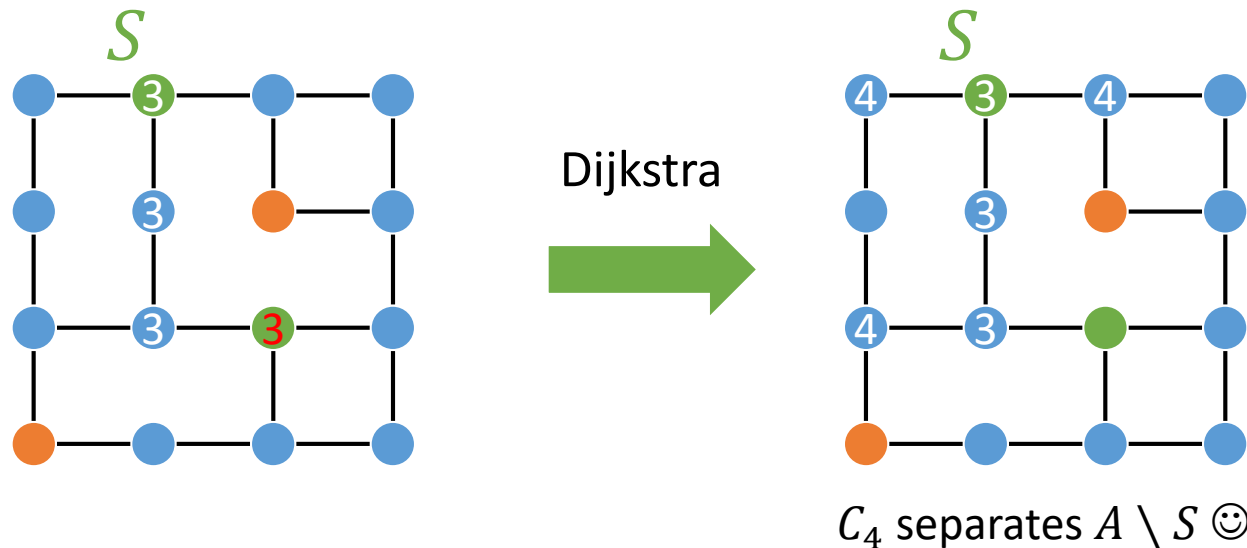
Dijkstra



$C_4$  separates  $A \setminus S$  ☺

# Restore dropped information (3)

If a Steiner tree  $T$  for  $S \cup \{u\}$  is unimportant,  $T + P_{uv}$  is also unimportant. So we can safely drop such  $(S, v)$ .



# Outline



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# Data Structure (1)

$P \leftarrow \emptyset$  # set of processed  $S$

while  $\exists$  unprocessed  $S$  s.t.  $d(S, u) \neq \infty$  for some  $u$

...

for  $S' \in P$  s.t.  $S \cap S' \neq \emptyset$

update  $d(S \cup S', u)$  for  $\forall u$

push  $S$  into  $P$

How can we apply the merge operation efficiently?

Let  $\text{valid}(S) := \{u \in V \mid d(S, u) \neq \infty\}$ .

We want to find all  $S'$  such that

1.  $S \cap S' = \emptyset$  and
2.  $\text{valid}(S) \cap \text{valid}(S') \neq \emptyset$

# Data Structure (2)

We maintain the set of processed  $S$  using the following binary trie.

Each leaf  $t$  keeps  $S_t \subseteq A$ .

Each internal node  $t$  with leaves  $L_t$  keeps

1.  $I_i := \bigcap_{t \in L_i} S_t$
2.  $U_i := \bigcup_{t \in L_i} \text{valid}(S_t)$

When searching  $S'$ , we can stop if  $S \cap I_i \neq \emptyset$  or  $\text{valid}(S) \cap U_i = \emptyset$ .

# Meet in the Middle

Any Steiner tree for  $A$  can be written as a sum of three Steiner trees for  $S_1, S_2, S_3$  with  $1 \leq |S_1| \leq |S_2| \leq |S_3| \leq |A|/2$ .

1. We can stop after processing all  $S$  of size  $\leq |A|/2$ .
2. When merging, we can iterate only over  $S'$  of size at most  $2|A| - 2|S|$ .

```
 $P \leftarrow \emptyset$  # set of processed  $S$   
while  $\exists$  unprocessed  $S$  s.t.  $d(S, u) \neq \infty$  for some  $u$   
  ...  
  for  $S' \in P$  s.t.  $S \cap S' \neq \emptyset$   
    update  $d(S \cup S', u)$  for  $\forall u$   
  push  $S$  into  $P$ 
```

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# Environment

**Data set:** from the DIMACS and PACE

## List of Solvers:

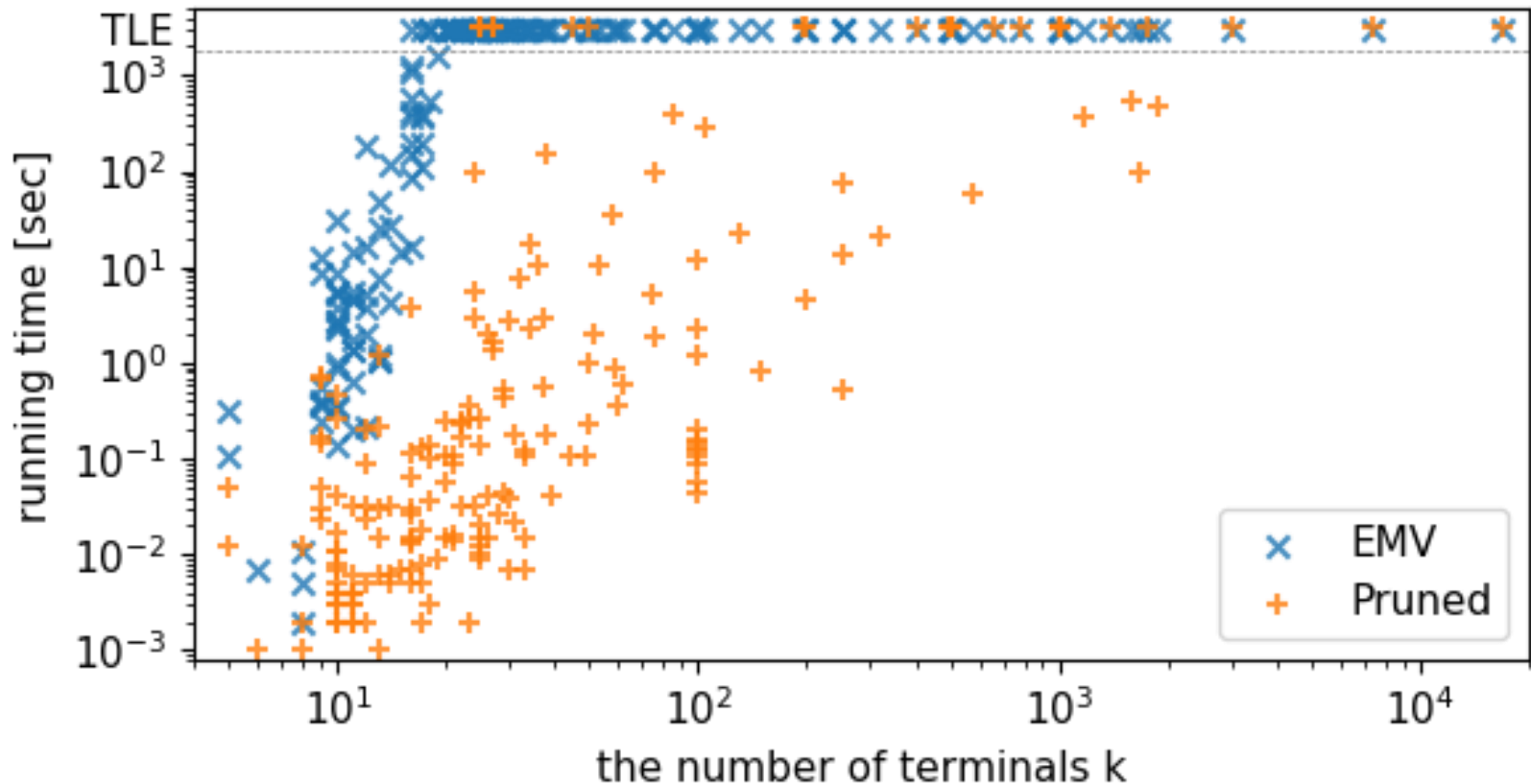
- Pruned: the proposed pruned DP algorithm
- EMV: the classical DP algorithm
- HSV: EMV +  $A^*$ -search
- SCIP-Jack [Gamrath,Koch,Maher,Rehfeldt,Shinano 17]:  
ILP solver (PACE version)

**Setting:** Intel Xeon E5-2670 (2.6 GHz), single thread,  
time limit = 30 minutes, memory limit = 6GB

(same as PACE)

# Comparison with EMV

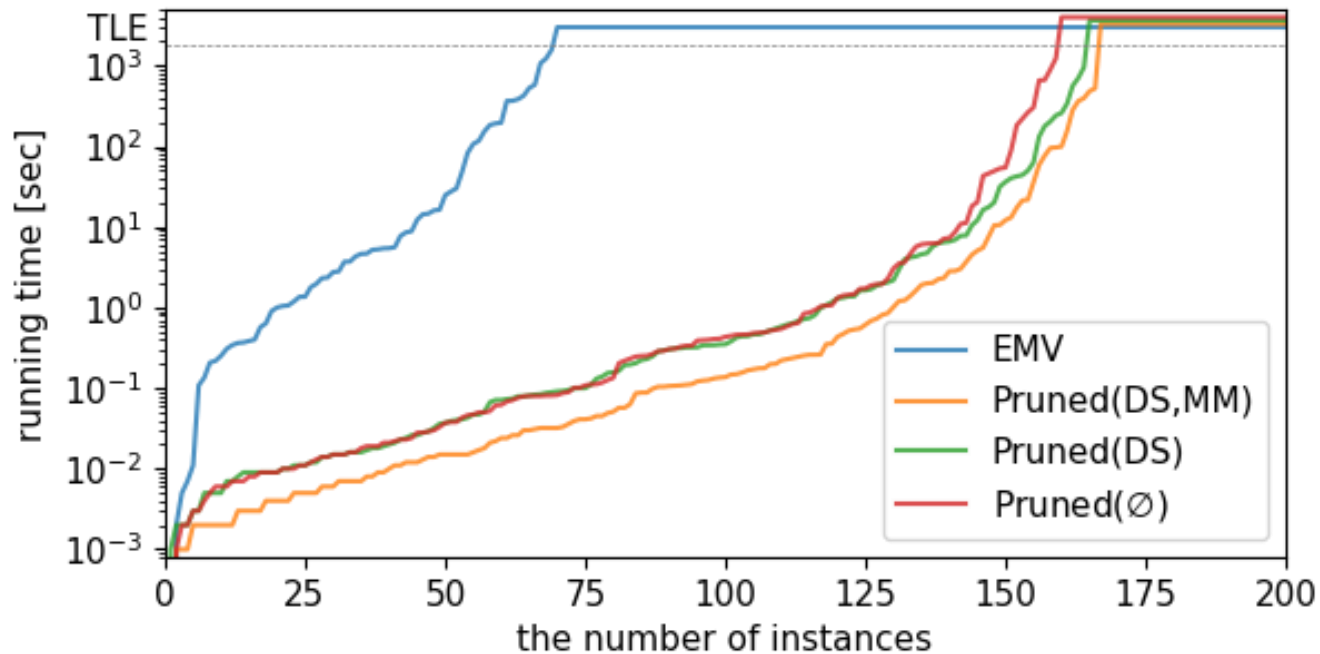
- ✓ No reductions
- ✓ 200 public instances from PACE



# Power of other techniques

DS: Data Structure

MM: Meet in the Middle



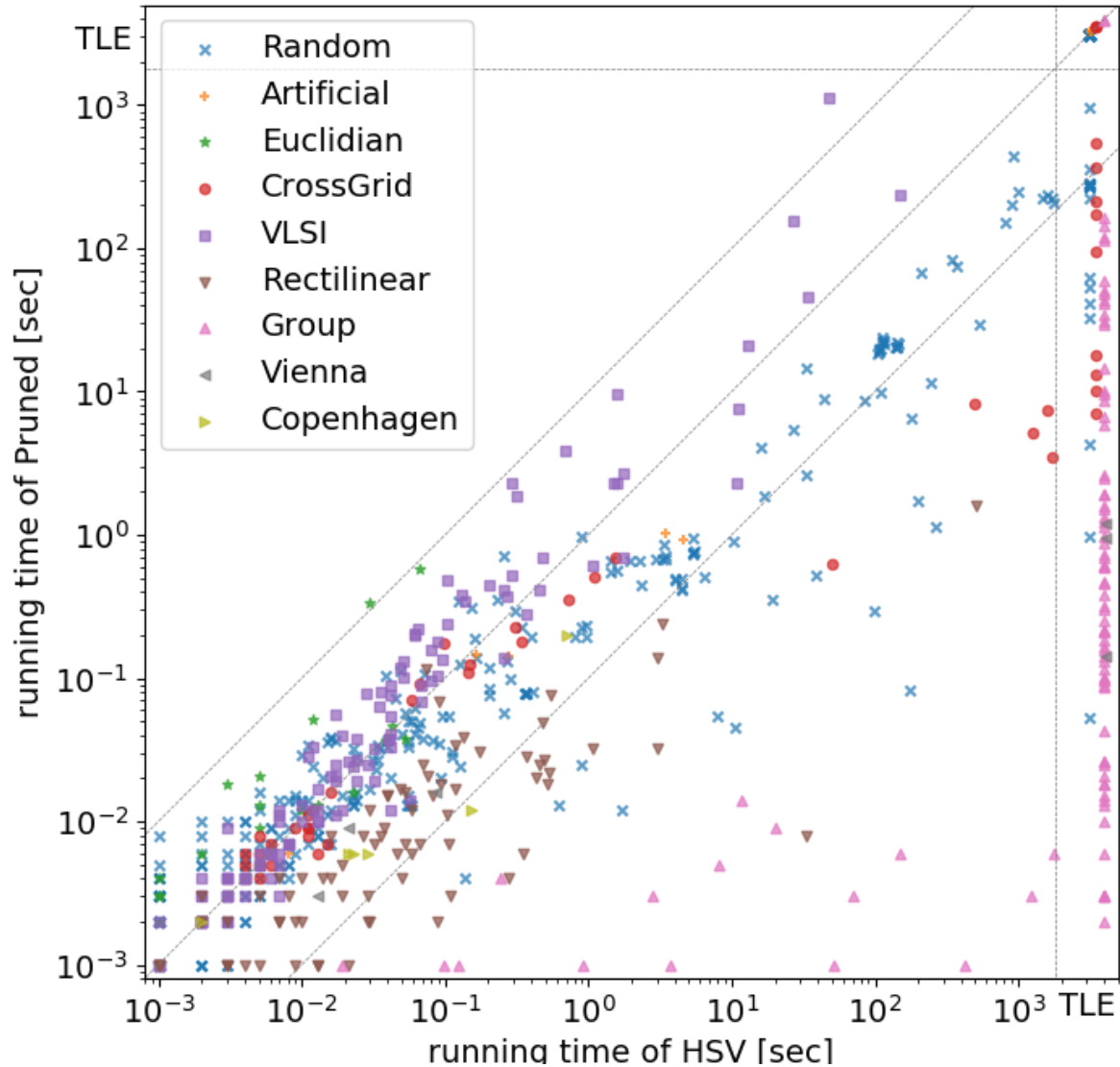
# Comparison with HSV

Dataset	#	HSV		PRUNED	
		solved	better	solved	better
Random	418	262	0	<b>281</b>	<b>35</b>
Artificial	21	11	0	11	0
Euclidian	26	26	0	26	0
CrossGrid	45	33	0	<b>42</b>	<b>14</b>
VLSI	128	128	1	128	0
Rectilinear	93	93	0	93	4
Group	89	16	0	<b>87</b>	<b>82</b>
Vienna	6	3	0	<b>6</b>	<b>3</b>
Copenhagen	10	10	0	10	0

✓ No reductions

$A$  is '**better**' than  $B$  on an instance  $i$  if  
 $A$  could solve  $i$  but  $B$  couldn't or  
 $(\text{run-time of } B) > (\text{run-time of } A) \times 10 + 1s.$

# Comparison with HSV



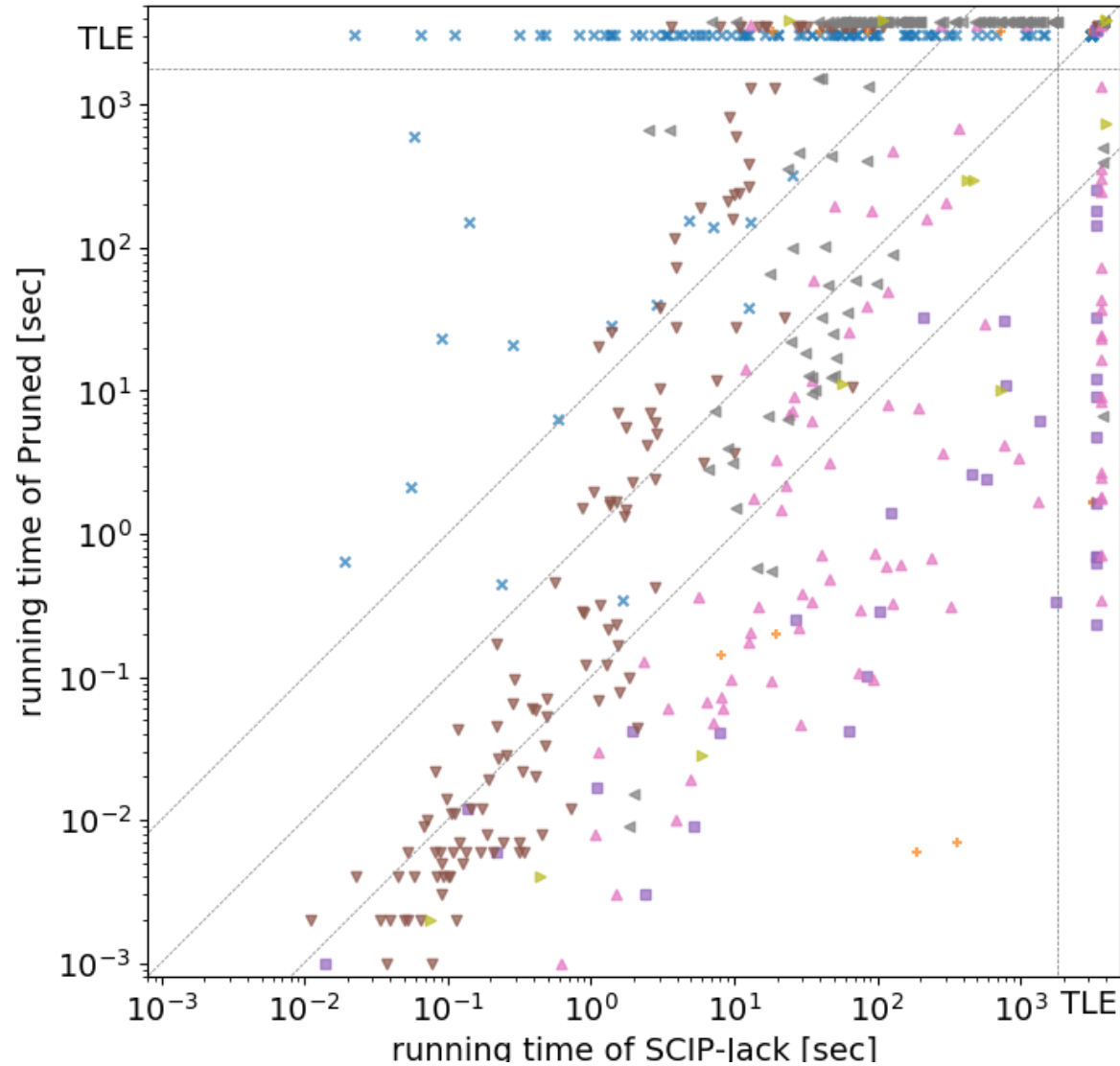
# Comparison with SCIP-Jack

Dataset	#	$k/n$	SCIP-JACK		PRUNED	
			solved	better	solved	better
Random	133	.256	<b>96</b>	<b>91</b>	16	0
Artificial	53	.239	8	4	6	6
VLSI	40	.046	20	0	<b>32</b>	<b>27</b>
Rectilinear	143	.425	<b>138</b>	<b>41</b>	113	1
Group	85	.086	65	4	<b>79</b>	<b>58</b>
Vienna	210	.145	<b>129</b>	<b>97</b>	42	7
Copenhagen	12	.140	8	2	7	3

↑  
average of  $k/n$

- ✓ Pruned used the same reductions as SCIP-Jack
- ✓ Omit too-easy instances solved by the reductions alone

# Comparison with SCIP-Jack



# Conclusion and Open Problems

- ✓ Pruned DP is quite effective for Steiner Tree.
- ✓ Further speedup?
  - Pruning interferes with future pruning...
- ✓ Pruning for tree-decomposition DP?