Karlsruhe Institute of Technology

## A Practical Analysis of Kernelization Techniques for the Maximum Cut Problem

NII Shonan Meeting | March 5, 2019
Damir Ferizovic, Sebastian Lamm, Matthias Mnich, Christian Schulz, Darren Strash

DEPARTMENT OF INFORMATICS: INSTITUTE OF THEORETICAL INFORMATICS


## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Definition and Example

- Given $G=(V, E)$, find $S \subseteq V$ such that $|E(S, V \backslash S)|$ is maximum
- Notation: $m c(G):=\max _{S \subseteq V}|E(S, V \backslash S)|$



## Max-Cut: Importance of Studying it

Karisruhe Institute of Technology

- Member of Karp's 21 NP-complete problems
- Used in...


Circuit design


Statistical physics


Social networks

## Kernelization: Definition and Example

- Kernelization: Compress graph while preserving optimality

$$
G_{0}=G:
$$



## Kernelization: Definition and Example

- Kernelization: Compress graph while preserving optimality

$$
G_{0}=G:
$$



## Kernelization: Definition and Example

- Kernelization: Compress graph while preserving optimality
$G_{1}$ :


$$
m c\left(G_{0}\right)=m c\left(G_{1}\right)+2
$$

## Kernelization: Definition and Example

- Kernelization: Compress graph while preserving optimality
$G_{1}$ :


$$
\begin{aligned}
& m c\left(G_{0}\right)=m c\left(G_{1}\right)+2 \\
& m c\left(G_{1}\right)=6
\end{aligned}
$$

## Kernelization: Definition and Example

- Kernelization: Compress graph while preserving optimality

$$
G_{0}=G:
$$



$$
m c\left(G_{0}\right)=6+2=8
$$

## Max-Cut: Current Research on Kernelization

- Previous work mostly of theoretical nature
- Analyze problem $k+m c$-lowerbound $(G)$
- Different reformulations (Etscheid and Mnich 2018, Madathil, Saurabh, and Zehavi 2018, Prieto 2005)
- Research on practicality missing
- Present for other problems
- independent set, Vertex Cover (Hespe, Schulz, and Strash 2018, Akiba and Iwata 2016)


## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018

Karlsruhe Institute of Technology


## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018

Karisruhe Institute of Technology


## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018

Karlsruhe Institute of Technology

(1) $N_{G}(x) \cap S=N_{G}(X) \cap S$
(2) $|X|>\frac{|K|+\left|N_{G}(X) \cap S\right|}{2} \geq 1$

## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018


(1) $N_{G}(x) \cap S=N_{G}(X) \cap S$
(2) $|X|>\frac{|K|+\left|N_{G}(X) \cap S\right|}{2} \geq 1 X$

## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018


(1) $N_{G}(x) \cap S=N_{G}(X) \cap S \checkmark$
(2) $|X|>\frac{|K|+\left|N_{G}(X) \cap S\right|}{2} \geq 1 \checkmark$

## Max-Cut: Reduction Rule 8 in Etscheid and Mnich 2018

Karlsruhe Institute of Technology

(1) $N_{G}(x) \cap S=N_{G}(X) \cap S$
(2) $|X|>\frac{|K|+\left|N_{G}(X) \cap S\right|}{2} \geq 1$

## Performance of Work from Etscheid and Mnich 2018

- Kernelization mostly driven by rule 8
- Weak-points in practice
- Reliance on clique-forest
- Parameter $k$ large in practice
- Kernel size $O(k)$ too large
- $O(k \cdot|E(G)|)$ time too slow


## Overview of Our Contributions

- Implemented and evaluated work of Etscheid and Mnich 2018
- Generalized existing reduction rules
- Rules not dependent on a subgraph anymore
- Developed new reduction rules
- Simplistic but significant improvement in practice
- Identified inclusions
- Efficient implementation
- Timestamping system
- Benchmark over a variety of instances


## Overview of Our Contributions

- Five new unweighted reduction rules
- Rule to compress induced 3-paths
- Two rules reducing cliques (R8, S2)
- Two antagonizing rules - merge and divide of cliques
- Briefly investigated: Weighted path compression


## External/Internal Vertices



## Rule Generalization: R8 <br> - "Sharing Adjacencies"



## Rule Generalization: R8 <br> - "Sharing Adjacencies"



## Rule Generalization: R8 <br> - "Sharing Adjacencies"


(1) $N_{G}(X) \cup X=N_{G}(x) \cup\{x\}$
(2) $|X|>\max \left\{\left|N_{G}(X)\right|, 1\right\}$

## Rule Generalization: R8 <br> - "Sharing Adjacencies"


(1) $N_{G}(X) \cup X=N_{G}(x) \cup\{x\} \checkmark$
(2) $|X|>\max \left\{\left|N_{G}(X)\right|, 1\right\} \checkmark$

## Rule Generalization: R8 <br> - "Sharing Adjacencies"


(1) $N_{G}(X) \cup X=N_{G}(x) \cup\{x\} \checkmark$
(2) $|X|>\max \left\{\left|N_{G}(X)\right|, 1\right\} \checkmark$

# New Reduction Rule: S2 <br> - "Semi-Isolated Cliques" 



- Clique $G[S]$ with $\left|C_{\text {ext }}(G[S])\right| \leq\left\lceil\frac{|S|}{2}\right\rceil$


# New Reduction Rule: S2 <br> - "Semi-Isolated Cliques" 



- Clique $G[S]$ with $\left|C_{\text {ext }}(G[S])\right| \leq\left\lceil\frac{|S|}{2}\right\rceil$


# New Reduction Rule: S2 <br> - "Semi-Isolated Cliques" 



C Clique $G[S]$ with $\left|C_{e x t}(G[S])\right| \leq\left\lceil\frac{|S|}{2}\right\rceil \sqrt{ }$

# New Reduction Rule: S2 <br> - "Semi-Isolated Cliques" 

- Clique $G[S]$ with $\left|C_{\text {ext }}(G[S])\right| \leq\left\lceil\frac{|S|}{2}\right\rceil \checkmark$




# New Reduction Rule: S2 <br> - "Semi-Isolated Cliques" 

- Clique $G[S]$ with $\left|C_{\text {ext }}(G[S])\right| \leq\left\lceil\frac{|S|}{2}\right\rceil \checkmark$



## Techniques Used for Performance

- Avoid time-intensive checks
- Vertex $v$ internal in clique: $\forall w \in N_{G}(v): \operatorname{Deg}(v) \leq \operatorname{Deg}(w)$
- Avoid checking the same reduction rules
- Timestamp of most recent change in neighborhood for each vertex
- Keep timestamp $T$ for each rule:

All vertices with timestamp $\leq T$ already processed

- Update vertex on change



## Experiments on KaGen Graphs

- Random graphs by KaGen, 150 per each graph type. $|V|=2048$
- Total runtime: 16 sec. ( 68 min . by Etscheid and Mnich 2018!)

Kernelization efficiency for KaGen graphs; metric: $e(G)=1-\frac{\left|V\left(G_{\text {rer }}\right)\right|}{|V(G)|}$


## Experiments on KaGen Graphs

- Improvement over Etscheid and Mnich 2018. $|V|=2048$
- Discrepancy between theory and practice

Absolute difference in efficiency: $e_{\text {absDiff }}=e\left(G_{\text {new }}\right)-e\left(G_{\text {old }}\right)$


## Experiments on KaGen Graphs

- Improvement on our results with weighted path compression

Absolute difference in efficiency: $e_{\text {absDiff }}=e\left(G_{\text {newWeighted }}\right)-e\left(G_{\text {new }}\right)$


## Experiments - BiqMac Solver

| Name | $\|V(G)\|$ | deg $_{\text {avg }}$ | $e(G)$ | $T_{\mathrm{BM}}(G)$ | $T_{\text {BM }}\left(G_{\text {ker }}\right)$ |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| ego-facebook | 2888 | 1.03 | 1.00 | - | 0.01 | $[\infty]$ |
| road-euroroad | 1174 | 1.21 | 0.79 | - | - | - |
| rt-twitter-copen | 761 | 1.35 | 0.85 | - | 1.77 | $[\infty]$ |
| bio-diseasome | 516 | 2.30 | 0.93 | - | 0.07 | $[\infty]$ |
| ca-netscience | 379 | 2.41 | 0.77 | - | 0.67 | $[\infty]$ |
| g000302 | 317 | 1.50 | 0.21 | 1.88 | $0.74 \quad[2.53]$ |  |
| g001918 | 777 | 1.59 | 0.12 | 31.11 | $17.45 \quad[1.78]$ |  |
| g000981 | 110 | 1.71 | 0.28 | 531.47 | $21.53[24.68]$ |  |
| imgseg_105019 | 3548 | 1.22 | 0.93 | f | 13748.62 | $[\infty]$ |
| imgseg_35058 | 1274 | 1.42 | 0.37 | - | - | - |
| imgseg_374020 | 5735 | 1.52 | 0.82 | f | - | - |

Times in seconds. 10 hour time limit with 5 iterations.

## Experiments - Localsolver

| Name | $\|V(G)\|$ | deg $_{\text {avg }}$ | $e(G)$ | $T_{\text {LS }}(G)$ | $T_{\text {LS }}\left(G_{\text {ker }}\right)$ |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| ego-facebook | 2888 | 1.03 | 1.00 | 20.09 | 0.09 | $[228.91]$ |
| road-euroroad | 1174 | 1.21 | 0.79 | - | - | - |
| rt-twitter-copen | 761 | 1.35 | 0.85 | - | 834.71 | $[\infty]$ |
| bio-diseasome | 516 | 2.30 | 0.93 | - | 4.91 | $[\infty]$ |
| ca-netscience | 379 | 2.41 | 0.77 | - | 956.03 | $[\infty]$ |
| g000302 | 317 | 1.50 | 0.21 | 0.58 | 0.49 | $[1.17]$ |
| g001918 | 777 | 1.59 | 0.12 | 1.47 | 1.41 | $[1.04]$ |
| g000981 | 110 | 1.71 | 0.28 | 10.73 | 4.73 | $[2.27]$ |
| imgseg_105019 | 3548 | 1.22 | 0.93 | 234.01 | 22.68 | $[10.32]$ |
| imgseg_35058 | 1274 | 1.42 | 0.37 | 34.93 | 24.71 | $[1.41]$ |
| imgseg_374020 | 5735 | 1.52 | 0.82 | 1739.11 | 72.23 | $[24.08]$ |

Times in seconds. 10 hour time limit with 5 iterations.

## Experiments - Localsolver

Solution size over time by Localsolver: initial vs. kernelized


## Conclusion

## Summary

- Previous work: Good in theory, bad in practice
- Set of new (unweighted) reduction rules
- Sparse graphs highly reducible
- Significant benefits for existing solvers


## Future Work

- Add parallelism?
- New (weighted) reduction rules?
- Hybrid approach: Use solver for reductions?

