

# EXAMINATION MATHEMATICAL TECHNIQUES FOR IMAGE ANALYSIS

Course code: 8D020. Date: Wednesday April 22, 2009. Time: 14h00–17h00. Place: HG 10.01 C.

## Read this first!

- Use a separate sheet of paper for each problem. Write your name and student identification number on each paper.
- The exam consists of 4 problems. The maximum credit for each item is indicated in the margin.
- Motivate your answers. The use of course notes and calculator is allowed. The use of the problem companion, “opgaven- en tentamenbundel”, is *not* allowed.
- You may provide your answers in Dutch or (preferably) in English.

*GOOD LUCK!*

(35) 1. Consider the collection of square matrices,

$$\mathbb{M}_n = \left\{ X = \begin{pmatrix} X_{11} & \dots & X_{1n} \\ \vdots & & \vdots \\ X_{n1} & \dots & X_{nn} \end{pmatrix} \mid X_{ij} \in \mathbb{K} \right\}, \text{ in which } \mathbb{K} \text{ denotes either } \mathbb{R} \text{ or } \mathbb{C}.$$

(2 $\frac{1}{2}$ ) a. Provide explicit definitions for the operators  $\otimes : \mathbb{K} \times \mathbb{M}_n \rightarrow \mathbb{M}_n$  (“scalar multiplication”) and  $\oplus : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{M}_n$  (“vector addition”) needed to turn this set into a linear space over  $\mathbb{K}$ . Make sure to use parentheses so as to avoid confusion on operator precedence, if necessary.

The necessary operators are scalar multiplication and vector addition. If  $\lambda, \mu \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$ , then

$$((\lambda \otimes X) \oplus (\mu \otimes Y))_{ij} = \lambda X_{ij} + \mu Y_{ij} \quad \text{for all } i, j = 1, \dots, n.$$

Henceforth we write  $\lambda X$  instead of  $\lambda \otimes X$  and  $X + Y$  instead of  $X \oplus Y$  for  $\lambda \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$ . Furthermore, let  $\mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$  denote the linear space of linear operators on  $\mathbb{M}_n$ .

(2 $\frac{1}{2}$ ) b. Provide explicit definitions for the operators  $\otimes : \mathbb{R} \times \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n) \rightarrow \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$  and  $\oplus : \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n) \times \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n) \rightarrow \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$  that justifies the claim that  $\mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$  is a linear space over  $\mathbb{K}$ . Make sure to use parentheses so as to avoid confusion on operator precedence, if necessary.

The necessary operators are scalar multiplication and vector addition. If  $\lambda, \mu \in \mathbb{K}$  and  $A, B \in \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$ , then

$$((\lambda \otimes A) \oplus (\mu \otimes B))(X) = \lambda A(X) + \mu B(X) \quad \text{for all } X \in \mathbb{M}_n.$$

Again we write  $\lambda A$  instead of  $\lambda \otimes A$  and  $A+B$  instead of  $A \oplus B$  for  $\lambda \in \mathbb{K}$  and  $A, B \in \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$ . With  $X$  as above, the transposed matrix  $X^T$  and the conjugate matrix  $X^\dagger$  are defined as

$$X^T = \begin{pmatrix} X_{11} & \dots & X_{n1} \\ \vdots & & \vdots \\ X_{1n} & \dots & X_{nn} \end{pmatrix} \quad \text{respectively} \quad X^\dagger = \begin{pmatrix} X_{11}^* & \dots & X_{n1}^* \\ \vdots & & \vdots \\ X_{1n}^* & \dots & X_{nn}^* \end{pmatrix}.$$

Here,  $*$  denotes complex conjugation, i.e. if  $z = x + iy$  for  $x, y \in \mathbb{R}$ , then  $z^* = x - iy$ .

Furthermore, the operators  $P_\pm : \mathbb{M}_n \rightarrow \mathbb{M}_n$  and  $Q_\pm : \mathbb{M}_n \rightarrow \mathbb{M}_n$  are defined by

$$P_\pm(X) = \frac{1}{2}(X \pm X^T) \quad \text{respectively} \quad Q_\pm(X) = \frac{1}{2}(X \pm X^\dagger).$$

(2 $\frac{1}{2}$ ) **c1.** Show that *matrix transposition*,  $T : \mathbb{M}_n \rightarrow \mathbb{M}_n : X \mapsto T(X) \stackrel{\text{def}}{=} X^T$ , is a linear operator.

For all  $\lambda, \mu \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$  we have  $T(\lambda X + \mu Y) \stackrel{\text{def}}{=} (\lambda X + \mu Y)^T = \lambda X^T + \mu Y^T \stackrel{\text{def}}{=} \lambda T(X) + \mu T(Y)$ .

(2 $\frac{1}{2}$ ) **c2.** Show that *matrix conjugation*,  $C : \mathbb{M}_n \rightarrow \mathbb{M}_n : X \mapsto C(X) \stackrel{\text{def}}{=} X^\dagger$ , is not a linear operator.

For all  $\lambda, \mu \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$  we have  $C(\lambda X + \mu Y) \stackrel{\text{def}}{=} (\lambda X + \mu Y)^\dagger = \lambda^* X^\dagger + \mu^* Y^\dagger \stackrel{\text{def}}{=} \lambda^* C(X) + \mu^* C(Y) \neq \lambda C(X) + \mu C(Y)$ . (If  $\mathbb{K} = \mathbb{R}$  then  $C = T$ , so then it does define a linear operator.)

(2 $\frac{1}{2}$ ) **c3.** Show that  $P_\pm : \mathbb{M}_n \rightarrow \mathbb{M}_n$  are linear operators.

For all  $\lambda, \mu \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$  we have  $P_\pm(\lambda X + \mu Y) \stackrel{\text{def}}{=} \frac{1}{2}(\lambda X + \mu Y \pm (\lambda X + \mu Y)^T) = \lambda(\frac{1}{2}(X \pm X^T)) + \mu(\frac{1}{2}(Y \pm Y^T)) \stackrel{\text{def}}{=} \lambda P_\pm(X) + \mu P_\pm(Y)$ .

(2 $\frac{1}{2}$ ) **c4.** Show that  $Q_\pm : \mathbb{M}_n \rightarrow \mathbb{M}_n$  are not linear operators.

For all  $\lambda, \mu \in \mathbb{K}$  and  $X, Y \in \mathbb{M}_n$  we have  $Q_\pm(\lambda X + \mu Y) \stackrel{\text{def}}{=} \frac{1}{2}(\lambda X + \mu Y \pm (\lambda X + \mu Y)^\dagger) = \frac{1}{2}(\lambda X \pm \lambda^* X^\dagger) + \frac{1}{2}(\mu Y \pm \mu^* Y^\dagger) \neq \lambda(\frac{1}{2}(X \pm X^\dagger)) + \mu(\frac{1}{2}(Y \pm Y^\dagger)) \stackrel{\text{def}}{=} \lambda Q_\pm(X) + \mu Q_\pm(Y)$ . (If  $\mathbb{K} = \mathbb{R}$  then  $Q_\pm = P_\pm$ , so then they do define linear operators.)

The null matrix in  $\mathbb{M}_n$  is indicated by  $\Omega$ , i.e.  $\Omega_{ij} = 0$  for all  $i, j = 1, \dots, n$ . The identity matrix in  $\mathbb{M}_n$  is indicated by  $I$ , i.e.  $I_{ij} = 1$  if  $i = j = 1, \dots, n$ , otherwise  $I_{ij} = 0$ . The null operator  $N : \mathbb{M}_n \rightarrow \mathbb{M}_n$  is defined by  $N(X) = \Omega \in \mathbb{M}_n$  for all  $X \in \mathbb{M}_n$ . The identity operator  $\text{id} : \mathbb{M}_n \rightarrow \mathbb{M}_n$  is defined by  $\text{id}(X) = X$  for all  $X \in \mathbb{M}_n$ . Operator composition (i.e. successive application of operators in right-to-left order) is indicated by the infix operator  $\circ$ .

(2 $\frac{1}{2}$ ) **d1.** Show that  $P_+ + P_- = \text{id}$ .

We have  $(P_+ + P_-)(X) \stackrel{\text{def}}{=} P_+(X) + P_-(X) \stackrel{\text{def}}{=} \frac{1}{2}(X + X^T) + \frac{1}{2}(X - X^T) = X = \text{id}(X)$  for all  $X \in \mathbb{M}_n$ , so  $P_+ + P_- = \text{id}$ .

(2 $\frac{1}{2}$ ) **d2.** Show that  $P_+ - P_- = T$ .

We have  $(P_+ - P_-)(X) \stackrel{\text{def}}{=} P_+(X) - P_-(X) \stackrel{\text{def}}{=} \frac{1}{2}(X + X^T) - \frac{1}{2}(X - X^T) = X^T = T(X)$  for all  $X \in \mathbb{M}_n$ , so  $P_+ - P_- = T$ .

(2 $\frac{1}{2}$ ) **d3.** Show that  $P_+ \circ P_- = P_- \circ P_+ = N$ .

We have  $(P_+ \circ P_-)(X) \stackrel{\text{def}}{=} P_+(P_-(X)) \stackrel{\text{def}}{=} \frac{1}{2}(P_-(X) + P_-(X)^T) = \frac{1}{2}(\frac{1}{2}(X - X^T) + \frac{1}{2}(X^T - X)) = 0$  for all  $X \in \mathbb{M}_n$ , so  $P_+ \circ P_- = N$ . By interchanging all  $+$  and  $-$  signs in the above argument, it follows that  $P_- \circ P_+ = N$ .

(2 $\frac{1}{2}$ ) **d4.** Show that  $P_\pm \circ P_\pm = P_\pm$ .

We have  $(P_\pm \circ P_\pm)(X) \stackrel{\text{def}}{=} P_\pm(P_\pm(X)) \stackrel{\text{def}}{=} \frac{1}{2}(P_\pm(X) \pm P_\pm(X)^T) = \frac{1}{2}(\frac{1}{2}(X \pm X^T) \pm \frac{1}{2}(X^T \pm X)) = \frac{1}{2}(X \pm X^T) \stackrel{\text{def}}{=} P_\pm(X)$  for all  $X \in \mathbb{M}_n$ , so  $P_\pm \circ P_\pm = P_\pm$ .

Consider the following binary operator:  $\langle | \rangle : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{K} : (X, Y) \mapsto \langle X|Y \rangle \stackrel{\text{def}}{=} \text{trace}(X^T Y)$ . Here,  $\text{trace} : \mathbb{M}_n \rightarrow \mathbb{K}$  is the (linear) *trace* operator, defined as summation of diagonal elements:

$$\text{trace} X = \sum_{i=1}^n X_{ii}.$$

(2 $\frac{1}{2}$ ) **e1.** Show that if  $\mathbb{K} = \mathbb{R}$  then  $\langle | \rangle : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{R}$  defines a real inner product.

We may exploit the fact that both trace as well as transposition  $T$  are linear operators. Let  $X, Y, Z \in \mathbb{M}_n$  and  $\lambda, \mu \in \mathbb{K}$  be arbitrary. Then we have

- $\langle X|Y \rangle \stackrel{\text{def}}{=} \text{trace}(X^T Y) \stackrel{\text{def}}{=} \sum_{i=1}^n (X^T Y)_{ii} = \sum_{i=1}^n \sum_{j=1}^n X_{ij} Y_{ij} = \sum_{i=1}^n (Y^T X)_{ii} = \langle Y|X \rangle$ .
- $\langle \lambda X + \mu Y|Z \rangle \stackrel{\text{def}}{=} \text{trace}((\lambda X + \mu Y)^T Z) = \text{trace}((\lambda X^T + \mu Y^T) Z) = \lambda \text{trace}(X^T Z) + \mu \text{trace}(Y^T Z) \stackrel{\text{def}}{=} \lambda \langle X|Z \rangle + \mu \langle Y|Z \rangle$ .
- $\langle X|X \rangle \stackrel{\text{def}}{=} \text{trace}(X^T X) \stackrel{\text{def}}{=} \sum_{i=1}^n (X^T X)_{ii} = \sum_{i=1}^n \sum_{j=1}^n X_{ij} X_{ij} \geq 0$ , and clearly the sum of squares equals zero iff  $X = \Omega$ , the zero matrix.

(2 $\frac{1}{2}$ ) **e2.** Show that if  $\mathbb{K} = \mathbb{C}$  then  $\langle | \rangle : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{C}$  does not define a complex inner product.

Take  $\lambda \in \mathbb{C} \setminus \mathbb{R}$ , and  $X, Y \in \mathbb{M}_n$ , then  $\langle \lambda X|Y \rangle \stackrel{\text{def}}{=} \text{trace}((\lambda X)^T Y) = \text{trace}(\lambda X^T Y) = \lambda \text{trace}(X^T Y) \stackrel{\text{def}}{=} \lambda \langle X|Y \rangle \neq \lambda^* \langle X|Y \rangle$ .

(2 $\frac{1}{2}$ ) **f.** How would you modify the definition of  $\langle | \rangle : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{C}$  in the complex case,  $\mathbb{K} = \mathbb{C}$ , such that it does define a complex inner product? You may state your definition without proof.

We must use conjugation instead of transposition:  $\langle | \rangle : \mathbb{M}_n \times \mathbb{M}_n \rightarrow \mathbb{C} : (X, Y) \mapsto \langle X|Y \rangle \stackrel{\text{def}}{=} \text{trace}(X^\dagger Y)$ .

In the remainder of this problem we restrict ourselves to  $\mathbb{K} = \mathbb{R}$ . In particular, we consider the case of the real inner product, recall **e1**.

*Operator transposition*,  $T : \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n) \rightarrow \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n)$ , is implicitly defined by the identity

$$\langle A^T(X)|Y \rangle \stackrel{\text{def}}{=} \langle X|A(Y) \rangle \quad \text{for all } A \in \mathcal{L}(\mathbb{M}_n, \mathbb{M}_n) \text{ and } X, Y \in \mathbb{M}_n.$$

(2 $\frac{1}{2}$ ) **g.** Show that  $P_\pm^T = P_\pm$ . (Together with **d4** this shows that  $P_\pm$  are orthogonal projections.)

Let  $X, Y \in \mathbb{M}_n$ . Using the properties of the inner product and previous definitions we find  $\langle X|P_\pm(Y) \rangle \stackrel{\text{def}}{=} \langle X|\frac{1}{2}(Y \pm Y^T) \rangle = \frac{1}{2}\langle X|Y \rangle \pm \frac{1}{2}\langle X|Y^T \rangle \stackrel{*}{=} \frac{1}{2}\langle X|Y \rangle \pm \frac{1}{2}\langle X^T|Y \rangle = \langle \frac{1}{2}(X \pm X^T)|Y \rangle \stackrel{\text{def}}{=} \langle P_\pm(X)|Y \rangle$ . In  $*$  we have used the fact that  $\langle X|Y^T \rangle = \text{trace}(X^T Y^T) = \text{trace}((Y X)^T) = \text{trace}(Y X) = \text{trace}(X Y) = \langle X^T|Y \rangle$ , which in turn follows from the properties  $\text{trace}(X) = \text{trace}(X^T)$ ,  $\text{trace}(X Y) = \text{trace}(Y X)$ , and  $X^{TT} = X$ .



(32 $\frac{1}{2}$ ) **2.** Consider the Laplace equation for the function  $u \in C^\infty(\mathbb{R}^2)$ :

$$\Delta u = 0 \quad \text{in which } \Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}.$$

Our aim is to find a first order partial differential equation, such that its solutions also satisfy the Laplace equation. To this end we introduce a real linear space  $V$ , the dimension  $n \geq 2$  of which is yet to be determined, and furnish it with an additional operator henceforth referred to as “multiplication”. The product of  $v, w \in V$  is then simply written as  $vw \in V$ . In this way  $V$  is turned into a so-called algebra, for which we stipulate the following algebraic axioms, viz. for all  $u, v, w \in V$  and  $\lambda, \mu \in \mathbb{R}$ :

- $(uv)w = u(vw)$ ,
- $u(v + w) = uv + uw$ ,
- $(u + v)w = uw + vw$ ,
- $\lambda(uv) = (\lambda u)v = u(\lambda v)$ ,

(Multiplication takes precedence over vector addition unless parentheses indicate otherwise.)

We now attempt to decompose the Laplacian operator as follows:

$$\Delta = \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right) \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right).$$

Here  $a, b \in V$  are two fixed, independent elements (vectors). For consistency we assume that  $u(x, y) \in V$  (instead of our original assumption  $u(x, y) \in \mathbb{R}$ ).

**a.** Show that  $V$  is *not* commutative, and that it must possess an identity element  $1 \in V$  that has to be formally identified with the scalar number  $1 \in \mathbb{R}$ , by showing that

(2 $\frac{1}{2}$ ) **a1.**  $ab + ba = 0$ ,

(2 $\frac{1}{2}$ ) **a2.**  $a^2 = b^2 = 1$ .

Expanding

$$\left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right) \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right) = a^2 \frac{\partial^2}{\partial x^2} + (ab + ba) \frac{\partial^2}{\partial x \partial y} + b^2 \frac{\partial^2}{\partial y^2} \stackrel{\text{def}}{=} \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

shows that we must set  $ab + ba = 0$  and  $a^2 = b^2 = 1$ . Notice that we may *not* assume that  $ab = ba$ .

(5) **b.** Show that the (unordered) pair  $(a, b)$  satisfying the conditions of **a1** and **a2** is not unique. (*Hint:* Suppose  $a' = a_1 a + a_2 b$ ,  $b' = b_1 a + b_2 b$  for some  $a_1, a_2, b_1, b_2 \in \mathbb{R}$ .)

Following the hint we subject the transformed pair  $(a', b')$  to the required conditions of **a1–a2**. This leads to the following system of equations for the coefficients  $a_1, a_2, b_1, b_2 \in \mathbb{R}$ :

$$\begin{cases} a_1^2 + a_2^2 & = & 1 \\ b_1^2 + b_2^2 & = & 1 \\ a_1 b_1 + a_2 b_2 & = & 0. \end{cases}$$

In other words, apart from the choice  $(a_1, a_2) = (1, 0)$ ,  $(b_1, b_2) = (0, 1)$  corresponding to the solution under **a1–a2** we may take any pair of mutually perpendicular unit vectors  $(a_1, a_2), (b_1, b_2) \in \mathbb{R}^2$ . (This ambiguity is not surprising, since the Laplacian is invariant under orthogonal transformations of  $(x, y)$ -coordinates.)

**c.** Suppose  $v, w \in \text{span}\{a, b\} \subset V$  are such that, say,  $v = v_1a + v_2b$  and  $w = w_1a + w_2b$  for some  $v_1, v_2, w_1, w_2 \in \mathbb{R}$ . Compute

$$(2\frac{1}{2}) \quad \mathbf{c1.} \quad vw + wv,$$

$$(2\frac{1}{2}) \quad \mathbf{c2.} \quad v^2.$$

We find  $vw + wv = (v_1a + v_2b)(w_1a + w_2b) = 2v_1w_1a^2 + (v_1w_2 + v_2w_1)(ab + ba) + 2v_2w_2b^2 \stackrel{\mathbf{a1-a2}}{=} 2(v_1w_1 + v_2w_2)$ , from which it follows, by setting  $v_1 = w_1$  and  $v_2 = w_2$ , that  $v^2 = v_1^2 + v_2^2$ .

$$(2\frac{1}{2}) \quad \mathbf{d.} \quad \text{Show that } \dim V > 2.$$

(Hint: Alternatively, show that  $\text{span}\{a, b\} \subset V$  is not closed under multiplication.)

Take  $v = v_1a + v_2b \in V$ , with  $v_1, v_2 \in \mathbb{R}$  arbitrary. Suppose  $1 \in \text{span}\{a, b\}$ , i.e. there exist  $e_1, e_2 \in \mathbb{R}$ , at least one of which is nonzero, such that  $1 = e_1a + e_2b$ , then, again using **a1–a2** and the definition of the unit element  $1 \in V$ ,

$$v_1a + v_2b = v \stackrel{\text{def}}{=} 1v = e_1v_1 + e_2v_2 + (e_1v_2 - e_2v_1)ab \quad \text{for all } v_1, v_2 \in \mathbb{R}.$$

However,  $a, b, ab \notin \mathbb{R}$ , whereas  $e_1v_1 + e_2v_2 \in \mathbb{R}$ , so that we conclude that  $e_1v_1 + e_2v_2 = 0$  for all  $v_1, v_2 \in \mathbb{R}$ , implying  $e_1 = e_2 = 0$ , which is a contradiction. (To see that  $a, b, ab \notin \mathbb{R}$ , consider **a1–a2**, from which it is immediately obvious that  $a, b \notin \mathbb{R}$ . That  $ab \notin \mathbb{R}$  follows e.g. by taking its square:  $(ab)^2 = abab = -ab^2a = -a^2 = -1$ .)

We add two more independent elements to the set  $\{a, b\}$ , viz. the unit element  $1$  and the element  $ab$ , and define  $V = \text{span}\{1, a, b, ab\}$ . Instead of  $\lambda 1 + \mu a + \nu b + \rho ab$  ( $\lambda, \mu, \nu, \rho \in \mathbb{R}$ ) we write  $\lambda + \mu a + \nu b + \rho ab$  for an arbitrary element of  $V$ .

$$(5) \quad \mathbf{e.} \quad \text{Show that } V \text{ is closed under multiplication, i.e. show that if } v = v_0 + v_1a + v_2b + v_3ab \in V, w = w_0 + w_1a + w_2b + w_3ab \in V, \text{ then also } vw \in V.$$

The easiest answer is as follows. Multiplication of  $v$  and  $w$ , expanded as given, will generate  $4 \times 4 = 16$  terms, each of which is a multiple of any of the following product forms:  $1, a, b, ab, a^2, b^2, ba, a^2b, ab^2, aba, bab, (ab)^2$ . With the properties **a1–a2** of  $a$  and  $b$  these can all be reduced to multiples involving only  $1, a, b, ab$  (for we have  $a^2 = 1, b^2 = 1, ba = -ab, a^2b = b, ab^2 = a, aba = -a^2b = -b, bab = -b^2a = -a$ , and finally  $(ab)^2 = -ab^2a = -a^2 = -1$ ). The more cumbersome answer is to write out the product explicitly, and to apply the above simplification rules, yielding  $vw = (v_0 + v_1a + v_2b + v_3ab)(w_0 + w_1a + w_2b + w_3ab) = v_0w_0 + v_1w_1 + v_2w_2 - v_3w_3 + (v_0w_1 + v_1w_0 - v_2w_3 + v_3w_2)a + (v_0w_2 + v_1w_3 + v_2w_0 - v_3w_1)b + (v_0w_3 + v_1w_2 - v_2w_1 + v_3w_0)ab \in V$ .

We now try to realize elements of  $V$  in terms of real-valued  $2 \times 2$ -matrices. To this end we hypothesize that

$$V \subset \mathbb{M}_2 = \left\{ \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \mid a_{ij} \in \mathbb{R} \right\}.$$

$$(5) \quad \mathbf{f.} \quad \text{Construct explicit matrices } A, B \in \mathbb{M}_2 \text{ corresponding to } a, b \in V \text{ in the sense that}$$

$$\bullet \quad AB + BA = \Omega,$$

- $A^2 = B^2 = I$ .

Here  $\Omega \in \mathbb{M}_2$  is the null matrix, corresponding to the null element  $0 \in V$ , and  $I \in \mathbb{M}_2$  is the identity matrix, corresponding to the identity element  $1 \in V$ .

(*Hint:* As an ansatz, stipulate a diagonal matrix  $A$ , and show that  $B$  must then be anti-diagonal.)

Some examples of  $a \sim A$  and  $b \sim B$ , and  $ab \sim AB$ , and the element  $1 \sim I$ :

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad AB = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

Many other choices are possible, recall **b**. Examples such as the above are found by trial and error. Following the hint ( $a_{12} = a_{21} = 0$ ), setting  $A = \text{diag}\{a_{11}, a_{22}\}$ , and taking  $B$  arbitrary, one finds by writing out the conditions  $A^2 = I$  and  $AB + BA = \Omega$  that  $a_{11} = \pm 1$ ,  $a_{22} = \mp 1$ , and that  $B$  must have zeros on its diagonal, and writing out  $B^2 = I$  reveals that its remaining elements must equal  $b_{12} = b_{21} = \pm 1$ .

- (2 $\frac{1}{2}$ ) **g.** Given  $A$  and  $B$  as determined under **f**, what is the matrix form  $v_0 + v_1A + v_2B + v_3AB \in \mathbb{M}_2$  corresponding to a general element  $v_0 + v_1a + v_2b + v_3ab \in V$ ?

From **f** it follows by superposition  $X = v_0I + v_1A + v_2B + v_3AB$  that

$$X = \begin{pmatrix} v_0 + v_1 & v_2 + v_3 \\ v_2 - v_3 & v_0 - v_1 \end{pmatrix}.$$

Note that *any* matrix  $Y \in \mathbb{M}_2$  can be realized in this way, viz. by setting

$$v_0 = \frac{1}{2}(Y_{11} + Y_{22}) \quad v_1 = \frac{1}{2}(Y_{11} - Y_{22}) \quad v_2 = \frac{1}{2}(Y_{12} + Y_{21}) \quad v_3 = \frac{1}{2}(Y_{12} - Y_{21}).$$

- (2 $\frac{1}{2}$ ) **h.** Show that if  $u : \mathbb{R}^2 \rightarrow V$  satisfies the first order partial differential equation

$$a \frac{\partial u}{\partial x} + b \frac{\partial u}{\partial y} = 0,$$

then it is also a solution of  $\Delta u = 0$ .

Recall **a1–a2**. By construction we now have

$$\Delta u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \left( a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} \right) \left( a \frac{\partial u}{\partial x} + b \frac{\partial u}{\partial y} \right) = 0 \quad \text{since} \quad \left( a \frac{\partial u}{\partial x} + b \frac{\partial u}{\partial y} \right) = 0.$$



- (5) **3.** Consider a strictly monotonic, continuously differentiable function  $f : \mathbb{R} \rightarrow \mathbb{R} : x \mapsto f(x)$ , with  $f'(x) > 0$  for all  $x \in \mathbb{R}$ , and  $f(\pm\infty) = \pm\infty$ . The inverse function theorem states that such a function has an inverse,  $f^{-1} : \mathbb{R} \rightarrow \mathbb{R} : y \mapsto f^{-1}(y)$ , such that  $(f^{-1} \circ f)(x) = x$  for all  $x \in \mathbb{R}$ , and  $(f \circ f^{-1})(y) = y$  for all  $y \in \mathbb{R}$ .

- (2 $\frac{1}{2}$ ) **a.** Argue why the equation  $f(x) = 0$  has precisely one solution for  $x \in \mathbb{R}$  ( $x = a$ , say). (*Hint:* Sketch the graph of such a function  $f$ .)

Suppose there are two distinct solutions,  $f(a) = f(b) = 0$ , with  $a < b$ , say. According to the mean value theorem there exists a  $c$  in-between  $a$  and  $b$ , such that  $f'(c) = (f(b) - f(a))/(b - a) = 0$  (average slope on  $(a, b)$ ). This is a contradiction. Rephrased in terms of the graph of  $f$ , the argument is as follows. Since  $f$  is continuous, the graph of  $f$  is uninterrupted. Since  $f' > 0$ , the graph is monotonically increasing, so it can intersect the  $x$ -axis at most once. It actually does intersect the  $x$ -axis exactly once, since  $f$  is continuous and  $f$  assumes both negative and positive values, whence it must assume all intermediate values, in particular  $f(a) = 0$  for some unique  $a \in \mathbb{R}$ .

(27 $\frac{1}{2}$ ) **b.** Show that  $\delta(f(x)) = \frac{\delta(x - a)}{f'(a)}$ , in which  $a \in \mathbb{R}$  is the unique point for which  $f(a) = 0$ .

(Hint: Evaluate the distribution corresponding to the Dirac function on the left hand side on an arbitrary test function  $\phi \in \mathcal{S}(\mathbb{R})$ , i.e.  $\int_{-\infty}^{\infty} \delta(f(x)) \phi(x) dx$ , and apply substitution of variables.)

Consider

$$\int_{-\infty}^{\infty} \delta(f(x)) \phi(x) dx \stackrel{*}{=} \int_{-\infty}^{\infty} \delta(y) \phi(f^{-1}(y)) \frac{dy}{f'(f^{-1}(y))} \stackrel{*}{=} \frac{\phi(f^{-1}(0))}{f'(f^{-1}(0))} \stackrel{\circ}{=} \frac{\phi(a)}{f'(a)} \stackrel{*}{=} \int_{-\infty}^{\infty} \frac{\delta(x - a)}{f'(a)} \phi(x) dx.$$

In  $*$  substitution  $y = f(x)$  has been carried out, which implies  $dy = f'(x) dx$  and, by the inverse function theorem,  $x = f^{-1}(y)$ . Boundary values remain unchanged because  $f(\pm\infty) = \pm\infty$ . In  $*$  the definition of the Dirac- $\delta$  “function” has been used. In  $\circ$  the identity  $a = f^{-1}(0)$  (the equivalent of  $f(a) = 0$ , cf. **a**) has been invoked. Since this holds for all  $\phi \in \mathcal{S}(\mathbb{R})$  we conclude that  $\delta(f(x)) = \frac{\delta(x - a)}{f'(a)}$ .



(27 $\frac{1}{2}$ ) **4.** In this problem we consider a synthetic signal  $f : \mathbb{R} \rightarrow \mathbb{R}$ , defined as follows:

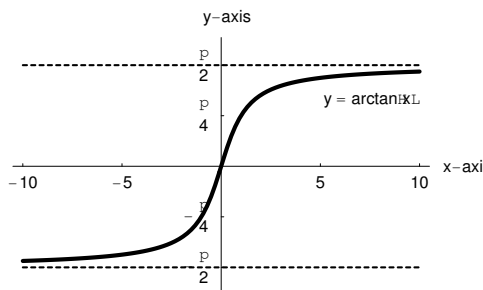
$$f(x) = \begin{cases} 0 & \text{if } x < 0 \\ \frac{1}{2} & \text{if } x = 0 \\ 1 & \text{if } x > 0 \end{cases}$$

Furthermore, we define the so-called Poisson filter  $\phi_\sigma : \mathbb{R} \rightarrow \mathbb{R}$  for  $\sigma > 0$  as

$$\phi_\sigma(x) = \frac{1}{\pi} \frac{\sigma}{x^2 + \sigma^2}.$$

In this problem you may use the following standard formulas (cf. the graph shown below):

$$\int \frac{1}{1 + x^2} dx = \arctan x + c \quad \text{resp.} \quad \lim_{x \rightarrow \pm\infty} \arctan x = \pm \frac{\pi}{2}.$$



Throughout this problem we employ the following Fourier convention:

$$\widehat{u}(\omega) = \mathcal{F}(u)(\omega) = \int_{-\infty}^{\infty} e^{-i\omega x} u(x) dx \quad \text{whence} \quad u(x) = \mathcal{F}^{-1}(\widehat{u})(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega x} \widehat{u}(\omega) d\omega.$$

(2½) **a.** Show that  $\int_{-\infty}^{\infty} \phi_{\sigma}(x) dx = 1$  regardless of the value of  $\sigma$ .

$\int_{-\infty}^{\infty} \phi_{\sigma}(x) dx = \frac{\sigma}{\pi} \int_{-\infty}^{\infty} \frac{1}{x^2 + \sigma^2} dx = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1}{1+y^2} dy = \frac{1}{\pi} [\arctan y]_{y \rightarrow -\infty}^{y \rightarrow +\infty} = \frac{1}{\pi} (\frac{\pi}{2} + \frac{\pi}{2}) = 1$ . Hierin is de volgende substitutie van variabelen toegepast:  $y = x/\sigma$ .

(2½) **b1.** Prove that for any, sufficiently smooth, integrable filter  $\phi$  we have:

$$(f * \phi)(x) = \int_{-\infty}^x \phi(\xi) d\xi.$$

$(f * \phi)(x) = \int_{-\infty}^{\infty} f(y) \phi(x-y) dy = \int_0^{\infty} \phi(x-y) dy = \int_{-\infty}^x \phi(\xi) d\xi$ . In de laatste stap is substitutie van variabelen,  $\xi = x - y$ , toegepast.

(2½) **b2.** Show by explicit computation that the convolution product  $f * \phi_{\sigma}$  is given by

$$(f * \phi_{\sigma})(x) = \frac{1}{2} + \frac{1}{\pi} \arctan \frac{x}{\sigma}.$$

$(f * \phi_{\sigma})(x) = \int_{-\infty}^{\infty} f(y) \phi_{\sigma}(x-y) dy = \frac{\sigma}{\pi} \int_0^{\infty} \frac{1}{(x-y)^2 + \sigma^2} dy = \int_{-\infty}^{x/\sigma} \frac{1}{1+\xi^2} d\xi = \frac{1}{\pi} [\arctan \xi]_{\xi \rightarrow -\infty}^{\xi = x/\sigma} = \frac{1}{\pi} (\arctan \frac{x}{\sigma} + \frac{\pi}{2}) = \frac{1}{2} + \frac{1}{\pi} \arctan \frac{x}{\sigma}$ . Hierin is de volgende substitutie van variabelen toegepast:  $\xi = (x-y)/\sigma$ . Gebruik van onderdeel **b1** leidt uiteraard tot hetzelfde resultaat.

(5) **c.** Show that the Fourier transform  $\widehat{f} = \mathcal{F}(f)$  of  $f$  is given by

$$\widehat{f}(\omega) = \frac{1}{i\omega}.$$

(Hint: From part **b1** it follows that  $\frac{d}{dx} (f * \phi)(x) = \phi(x)$ . Subject this to Fourier transformation.)

Uit  $\frac{d}{dx} (f * \phi_{\sigma})(x) = \phi_{\sigma}(x)$  volgt dat  $\mathcal{F}\left(\frac{d}{dx} (f * \phi_{\sigma})\right)(\omega) = \mathcal{F}(\phi_{\sigma})(\omega)$ . Met behulp van Result 6 op blz. 97 en Theorem 17 op blz. 104 volgt dat dit equivalent is met  $i\omega \mathcal{F}(f)(\omega) \mathcal{F}(\phi_{\sigma})(\omega) = \mathcal{F}(\phi_{\sigma})(\omega)$ . Ervan uitgaand dat  $\mathcal{F}(\phi_{\sigma})(\omega) \neq 0$  voor (bijna) alle  $\omega$  concluderen we dat  $\mathcal{F}(f)(\omega) = \frac{1}{i\omega}$ .

**d.** Without proof we state the Fourier transform  $\widehat{\phi}_{\sigma} = \mathcal{F}(\phi_{\sigma})$  of  $\phi_{\sigma}$ :

$$\widehat{\phi}_{\sigma}(\omega) = e^{-\sigma|\omega|}.$$

(2½) **d1.** Explain the behaviour of  $\widehat{\phi}_{\sigma}(\omega)$  for  $\omega \rightarrow 0$  in terms of properties of the corresponding spatial filter  $\phi_{\sigma}(x)$ .

(Hint: Cf. problem **a**.)

(2½) **d2.** Explain the behaviour of  $\widehat{f}(\omega)$  for  $\omega \rightarrow 0$  in terms of properties of the corresponding spatial



signal  $f(x)$ .

Zie de definitie van  $\widehat{u}(\omega)$ : Indien  $\widehat{u}(0)$  bestaat dan moet hiervoor kennelijk gelden  $\widehat{u}(0) = \int_{-\infty}^{\infty} u(x) dx$ . Dit verklaart zowel het gedrag van  $\widehat{\phi}_\sigma(\omega)$  als van  $\widehat{f}(\omega)$  voor  $\omega \rightarrow 0$ :  $\widehat{\phi}_\sigma(0) = \int_{-\infty}^{\infty} \phi_\sigma(x) dx = 1$  (zie **a**), terwijl  $\widehat{f}(0)$  niet bestaat omdat  $\int_{-\infty}^{\infty} f(x) dx = \int_0^{\infty} dx$  niet convergeert.

(5) **e.** Determine the function  $\mathcal{F}(f * \phi_\sigma)$ .

Noteren we gemakshalve  $f_\sigma = f * \phi_\sigma$  dan geldt hiervoor in de gehanteerde Fourierconventie  $\widehat{f}_\sigma = \mathcal{F}(f * \phi_\sigma) = \mathcal{F}(f) \mathcal{F}(\phi_\sigma) = \widehat{f} \widehat{\phi}_\sigma$ , dus  $\widehat{f}_\sigma(\omega) = \frac{1}{i\omega} e^{-\sigma|\omega|}$ .

(2 $\frac{1}{2}$ ) **f.** Show that  $\lim_{\sigma \rightarrow 0} f * \phi_\sigma = f$ . Hint: Take the “Fourier route”.

Schrijf wederom  $f_\sigma = f * \phi_\sigma$ . Uit **e** blijkt dat in het Fourierdomein geldt  $\lim_{\sigma \rightarrow 0} \widehat{f}_\sigma(\omega) = \lim_{\sigma \rightarrow 0} \frac{1}{i\omega} e^{-\sigma|\omega|} = \frac{1}{i\omega} = \widehat{f}(\omega)$ , dus volgt  $\lim_{\sigma \rightarrow 0} f_\sigma(x) = f(x)$ .

(2 $\frac{1}{2}$ ) **g.** Prove the claim under **d**:  $\widehat{\phi}_\sigma(\omega) = e^{-\sigma|\omega|}$ .  
(Hint: Apply the inverse Fourier transform.)

Following the hint we get

$$\begin{aligned} \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega x} e^{-\sigma|\omega|} d\omega &= \frac{1}{2\pi} \left( \int_{-\infty}^0 e^{(\sigma+ix)\omega} d\omega + \int_0^{\infty} e^{(-\sigma+ix)\omega} d\omega \right) = \frac{1}{2\pi} \left( \left[ \frac{e^{(\sigma+ix)\omega}}{\sigma+ix} \right]_{-\infty}^0 + \left[ \frac{e^{(-\sigma+ix)\omega}}{-\sigma+ix} \right]_0^{\infty} \right) \\ &= \frac{1}{2\pi} \left( \frac{1}{\sigma+ix} + \frac{1}{\sigma-ix} \right) = \frac{1}{\pi} \frac{\sigma}{x^2 + \sigma^2} \stackrel{\text{def}}{=} \phi_\sigma(x). \end{aligned}$$

**THE END**