

Reflections on a Geometry of Processes

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Abstract

In this note we discuss some issues concerning a geometric approach to process algebra. We mainly raise questions and are not yet able to present significant answers.

Keywords: Process algebra, process graph, geometry, periodicity, stack, bag, queue.

1 Periodic Processes

Our point of departure is the axiom system BPA in Table 1 together with guarded recursion. We are in particular interested in *non-linear* recursion, where products of recursion variables are allowed, in contrast with linear recursion exemplified by $\langle X | X = aY + b, Y = cX + dY \rangle$ yielding only regular (finite-state) processes. Non-linear recursion also allows infinite-state processes, such as the counter $\langle C | C = uDC, D = uDD + d \rangle$ (with actions u, d for “up” and “down”) or the process Stack that is definable by the infinite set of linear recursion equations over BPA (cf. the left-hand side of Table 2), and more remarkably, by the finite set of non-linear recursion equations (cf. the right-hand side of Table 2).

This simple framework is already rich in structure. In [1] this framework was linked with context-free grammars (CFG’s), in particular with those in (restricted)

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Table 1
BPA (Basic Process Algebra)

$x + y$	$=$	$y + x$
$x + (y + z)$	$=$	$(x + y) + z$
$x + x$	$=$	x
$(x + y) \cdot z$	$=$	$x \cdot z + y \cdot z$
$(x \cdot y) \cdot z$	$=$	$x \cdot (y \cdot z)$

Table 2
Stack, an infinite linear and a finite non-linear BPA-specification

$S_\lambda = 0 \cdot S_0 + 1 \cdot S_1$ $S_{d\sigma} = 0 \cdot S_{0d\sigma} + 1 \cdot S_{1d\sigma} + \underline{d} \cdot S_\sigma$ <p style="text-align: center;">(for $d = 0$ or $d = 1$, and any string σ)</p>	$S = T \cdot S$ $T = 0 \cdot T_0 + 1 \cdot T_1$ $T_0 = \underline{0} + T \cdot T_0$ $T_1 = \underline{1} + T \cdot T_1$
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Greibach normal form. There the fact was established that while the language equality problem for CFG's is unsolvable, the process equality problem for CFG's is solvable. A priori this is not implausible, because a process has much more inner 'structure' than a language (the set of its finite terminating traces). The decidability was demonstrated by Baeten, Bergstra, and Klop in [1] as a corollary of a result concerning the periodical geometry or topology of the corresponding process graph. In Figure 1 the periodicities of two examples are exhibited: of Stack on the left-hand side, and of the process $\langle X | X = bY + dZ, Y = d + dX + bYY, Z = b + bX + dZZ \rangle$ on the right-hand side (this graph repeats three finite graph fragments α, β and γ as is also illustrated in Figure 2 below).

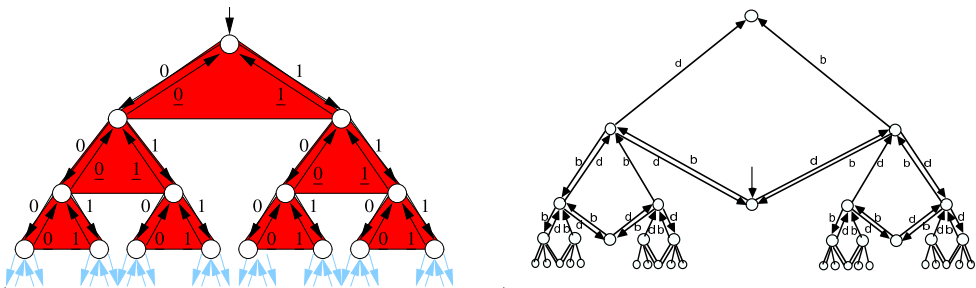


Fig. 1. Tree-like periodic processes

The geometric proof in [1] is complicated. For the corollary of the decidability more stream-lined approaches have subsequently been found by using tableaux methods and other arguments (cf. Caucal in [7], Hüttel and Stirling in [11], and Groote in [10]). Also, the geometric aspects have been studied, for example by Caucal in [8] and by Burkart, Caucal, and Steffen in [5]. Actually, the related

notion of *context-free graph* was introduced by Muller and Schupp [12] already in 1985.

We feel that there is still much to be explained about the geometric aspects of process graphs. We present a question concerning the fact that periodic graphs in BPA come in two kinds: ‘linear’ graphs as on the left-hand side, and ‘branching’ graphs as on the right-hand side in Figure 2.

Question 1.1 Is it decidable whether a system E of equations (in Greibach normal form) yields a linear (type I) or a branching (type II) graph?

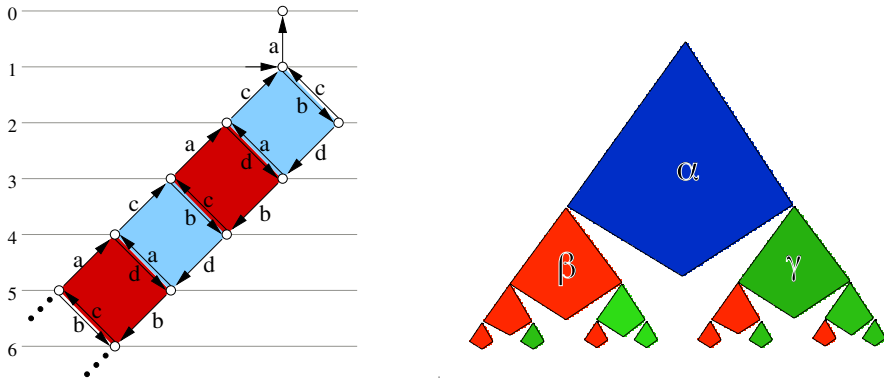


Fig. 2. ‘Linear’ periodic graphs (type I, left), ‘branching’ periodic graphs (type II, right)

Another graph of type II is the ‘butterfly’ process graph in Figure 3 of the recursive BPA-specification $\langle X|X = a + bY + fXY, Y = cX + dZ, Z = gX + eXZ \rangle$. The relevance of the distinction between type I and type II graphs is made clear

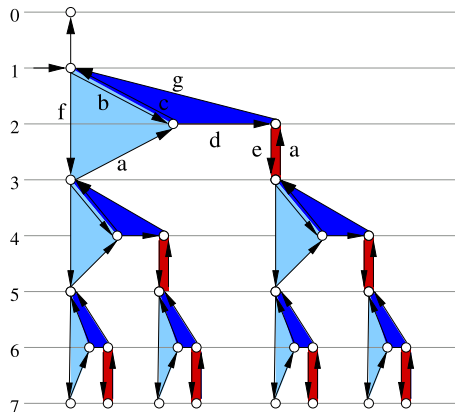


Fig. 3. A ‘butterfly’ process graph.

below, in order to show that certain graphs are *not* of type I or type II.

In the study of BPA-definable graphs an important property is that of being “normed”. A graph is *normed* if from every node in it there is a path to a terminating node. (In term rewriting terminology this is called the weak normalization property WN.) The norm of a node is then the minimum number of steps to termination. Originally, the decidability of context-free processes (BPA-definable processes)

was established in [1] only for the normed case. Subsequently this was generalized by Christensen, Hüttel, and Stirling in [9] to all BPA-definable processes.

Note that the norm of a node in a process graph is preserved under bisimulation: if norms are pictorially represented by drawing the process graph with horizontal ‘level’ lines, arranging points with the same norm on the same level (see the graph left in Figure 2 and the graph in Figure 3), then bisimulations relate only points on horizontal lines. Collapsing a normed graph to its canonical form is a compression in horizontal direction.

An important question is whether BPA-definable processes are closed under minimization (i.e. under compressing a graph such that it is minimal under bisimulation; the resulting graph is also called the “canonical” graph). The question whether such a statement does in fact hold was left open in [1]. Making a graph canonical can alter its geometry considerably. For instance, consider the counter C mentioned above. The process graph g of C is a linear sequence of nodes C, DC, DDC, \dots connected by u -steps to the right and d -steps to the left. The merge $C \parallel C$ in the process algebra PA has a grid-like graph similar to that of the process Bag on the left side in Figure 6 below. But if we collapse this graph g for $C \parallel C$ to its canonical form by identifying the bisimilar nodes on diagonal lines, we obtain again the graph g for C . So a grid may collapse to a linear graph.

Normedness plays a part when graphs are compressed to their canonical form. In [5] Burkart, Caucal, and Steffen give the following example of a BPA-graph that after compression to canonical form no longer is a BPA-graph: For the process with recursive definition $\langle Z|Z = aAZ+cD, A = aAA+cD+b, D = dD \rangle$ in BPA, the graph on the left in Figure 4 is its associated BPA-process graph, while the graph on the right is the respective minimization, which does not have the periodical structure of a BPA-graph. Note that neither of these graphs is normed.

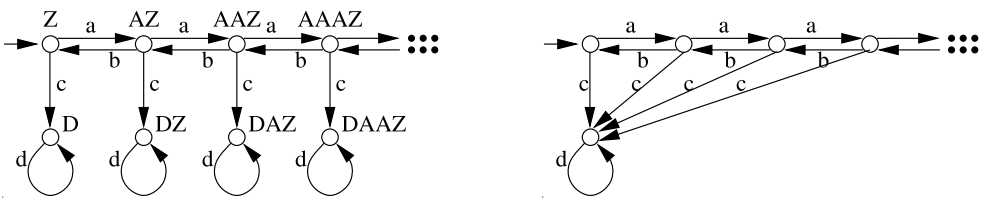


Fig. 4. Counterexample against the preservation of BPA-graphs under minimization.

Question 1.2 How can those BPA-graphs be characterized whose canonical graphs are again BPA-graphs?

We note that Question 1.2 has already received quite some attention in Caucal’s work. Contrasting with the counterexample for the unnormed case given above, in [7] he has shown the following theorem.

Theorem 1.3 (Caucal, 1990) *The class of normed BPA-graphs is closed under minimization.*

The (obvious) link between CFG’s and BPA-definable processes was first mentioned in [1]. An example is the graph on the right in Figure 1 and in Figure 2

above: it determines as context-free language (CFL) the language of words having equal numbers of letter b and d. An intriguing question is the following.

Question 1.4 How does the classical pumping lemma for CFL’s relate to the periodicity present in BPA-definable processes?

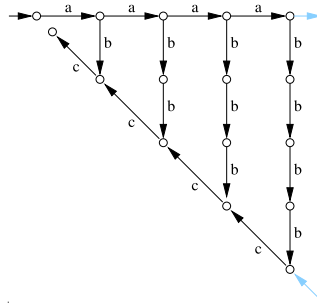


Fig. 5. The language L .

Another interesting observation, due to H.P. Barendregt, is the following. It is well-known that the language $L = \{a^n b^n c^n | n \geq 0\}$ is not a CFL. This language can be obtained as the set of finite traces of the triangular, infinite, minimal graph in Figure 5. Intuitively it is obvious that this graph is not tree-like periodic. This leads to the next question.

Question 1.5 Can the fact that the graph in Figure 5 is not a BPA-graph (when established rigorously) be used to conclude that L is not a CFL, applying the correspondence between CFL’s and definability in BPA as well as the ensuing tree-like periodicity?

2 Non-definability of Bag in BPA

The expressiveness of the operations defined by the axioms of BPA is limited; basically only sequential processes can be defined. The axiom system PA is an extension of BPA with axioms for the merge \parallel (interleaving) and the auxiliary operator $\underline{\parallel}$ (left merge). In PA we have a succinct recursive definition for the process Bag (over data $\{0, 1\}$) as follows:

$$B = 0(\underline{0} \parallel B) + 1(\underline{1} \parallel B).$$

It has been proved by Bergstra and Klop in [3] that the process Bag cannot be defined by means of a finite recursive specification over BPA. Considering the minimal process graph for it in Figure 6, this does not come as a surprise: it is not tree-like, but “grid-like”. Below we give an alternative proof of this fact.

Theorem 2.1 (Bergstra, Klop, 1984) Bag is not BPA-definable.

Proof (Sketch) Suppose that the process Bag is BPA-definable. Then there exists a recursive specification E in BPA such that Bag is bisimilar with a tree-like periodic

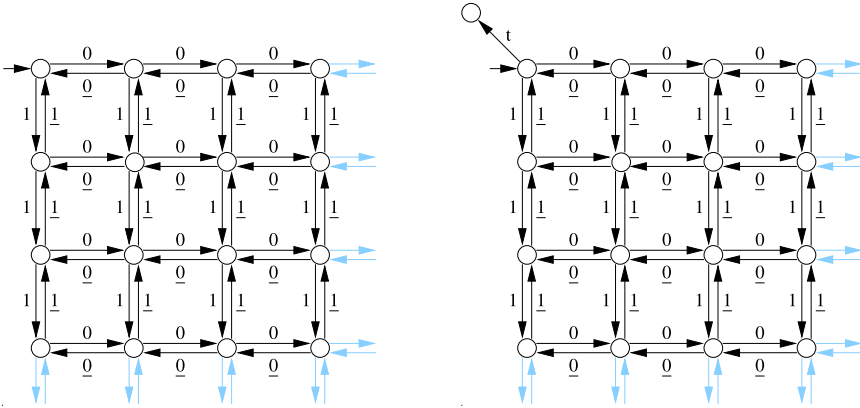


Fig. 6. The minimal process graphs of the process Bag (on the left-hand side), and of a terminating variant Bag_t of Bag (on the right-hand side).

graph $g(E)$ as defined by Baeten, Bergstra, and Klop in [1]. Then $g(E)$ is a “BPA-graph” according to the terminology used in [5].⁵

In [5] Burkart, Caucal, and Steffen have shown that, for every BPA-graph G , the canonical graph of G is a “pattern graph”, which means that it can be generated from a finite (hyper)graph by a reduction sequence of length ω according to a deterministic (hypergraph) grammar.⁶ Since Bag is itself a canonical graph and since therefore Bag is the canonical graph of the BPA-graph $g(E)$, it follows that Bag is a pattern graph.

A theorem due to Caucal in [8] states that all (rooted) pattern graphs of finite degree are “context-free” according to the definition of Muller and Schupp in [12].⁷ It follows that Bag is context-free. However, it is not difficult to verify that Bag is actually *not* a context-free graph according to the definition in [12].

In this way we have arrived at a contradiction with our assumption that Bag is definable in BPA. \square

By using Caucal’s theorem, Theorem 1.3, it is also possible to establish quickly the non-definability in BPA of many normed graphs. For example, for the terminating version Bag_t of Bag (where Bag_t is normed) with the process graph on the right in Figure 6, it can be reasoned as follows. This graph is canonical, so if it were BPA-definable, then it would be a graph of type I or type II. However, for a type I graph it holds that the number of nodes in a sphere $B(s, \rho)$, where s is the center and ρ is the radius, depends linearly on ρ ; for a type II graph this dependence is of exponential form. But for the graph under consideration the number of nodes in a ball $B(s, \rho)$ only depends quadratically on ρ . Hence this graph is not BPA-definable.

⁵ In earlier papers of Caucal (e.g. in [6] and [8]) BPA-graphs were known under the name “alphabetic graphs”.

⁶ “Pattern graphs” according to this definition used by Caucal and Montfort in [6] are called “regular graphs” in the later paper [5] by Burkart, Caucal, and Steffen. Because the use of the attribute “regular” for process graphs could lead to wrong associations, we avoid this terminology from (hyper)graph rewriting here.

⁷ Note that the class of “context-free” graphs in Muller and Schupp’s definition does not coincide with the graphs associated with “context-free” processes (the class of BPA-graphs), but that it forms a strictly richer class of graphs corresponding to the class of transition graphs of push-down automata.

Where do we need the preservation of BPA-definability under minimization? The process graph of Bag_t is clearly not one obtainable by a BPA-definition, as it is not of type I or type II. But equality of processes is considered here modulo bisimulation—so it is not inconceivable that there is a BPA-definition E of Bag_t such that $g(E)$ after compression to canonical form $\text{can}(g(E))$ were just the process graph $\text{graph}(\text{Bag}_t)$ for Bag_t on the right in Figure 6. So $\text{can}(g(E)) = \text{graph}(\text{Bag}_t)$ holds. But with the preservation property, Theorem 1.3, we have $\text{can}(g(E)) = g(E')$ for some BPA-specification E' , hence $g(E')$, and therefore $\text{graph}(\text{Bag}_t)$, are of type I or type II, quod non.

3 The strange geometry of Queue

After the paradigmatic processes Stack and Bag, we now turn to the third paradigmatic process Queue (the first-in-first-out version with unbounded capacity). Table 3 gives the infinite BPA-specification.

Table 3
Queue, infinite BPA-specification

$$\begin{aligned}
 Q &= Q_\lambda = \sum_{d \in D} r_1(d) \cdot Q_d \\
 Q_{\sigma d} &= s_2(d) \cdot Q_\sigma + \sum_{e \in D} r_1(e) \cdot Q_{e\sigma d} \\
 &\text{(for } d \in D, \text{ and } \sigma \in D^*)
 \end{aligned}$$

As before, the endeavour is to specify Queue in a finite way. It was proved by Bergstra and Tiuryn [4] that the system BPA is not sufficient for that; in fact, they showed that Queue cannot even be defined in ACP with handshaking communication (see [2] for a complete treatment of the axiom system ACP). But Queue has a finite recursive specification in ACP with renaming operators (see Table 4, the specification is originally due to Hoare using the ‘chaining’-operation).

Table 4
Queue, finite ACP-specification with renaming

$$\begin{aligned}
 Q &= \sum_{d \in D} r_1(d) (\rho_{c_3 \rightarrow s_2} \circ \partial_H) (\rho_{s_2 \rightarrow s_3}(Q) \parallel s_2(d) \cdot Z) \\
 Z &= \sum_{d \in D} r_3(d) \cdot Z
 \end{aligned}$$

An ambitious question is the following.

Question 3.1 Is there a geometric (topological) property of processes definable by handshaking communication?

Finally, we turn to geometric properties of the process Queue. Surprisingly, it is unexpectedly problematic to draw the process graph of Queue in a ‘neat’ way (cf. also Figure 7), similar to Stack and Bag. We would like to uncover the ‘deep’ reason for this difficulty.

Question 3.2 Is it possible to fit $g(\text{Queue})$ in the binary tree space?

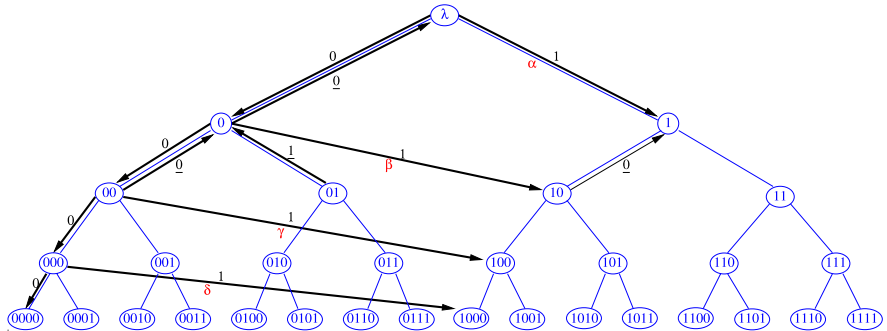


Fig. 7. Attempt at drawing Queue in ‘tree space’.

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