

# Algorithms for Model Checking (2IW55)

## Lecture 11

### Parameterised Boolean Equation Systems (3)

Background material:

- *Verification of Reactive Systems via Instantiation of Parameterised Boolean Equation Systems*, B. Ploeger, J.W. Wesselink and T.A.C. Willemse (*I&C 2010/2011*)
- *Static Analysis Techniques for Parameterised Boolean Equation Systems*, S. Orzan, J.W. Wesselink and T.A.C. Willemse (*TACAS 2009*)

Tim Willemse

(timw@win.tue.nl)

<http://www.win.tue.nl/~timw>

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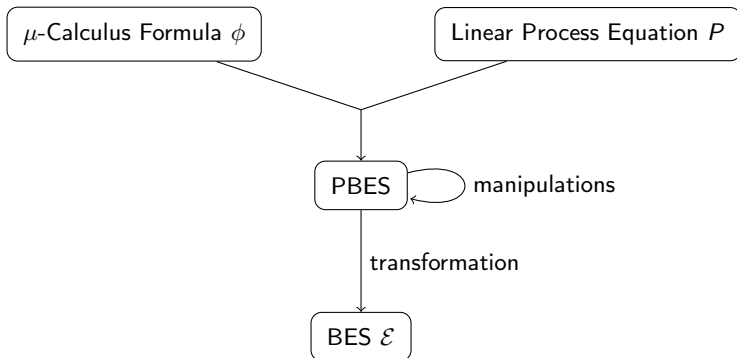
Parameterised Boolean Equation Systems

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## Verification Methodology:



Solving  $\mathcal{E}$  answers  $P \models \phi$

## Problem Description

1. Given a process  $P(e)$  described by an LPE  $P$  over  $Act$
2. Given a first-order modal  $\mu$ -calculus formula  $\sigma X.\phi$
3. Given environments  $\eta, \varepsilon$
4. Check whether  $P(e) \models \sigma X.\phi$  holds, where:

$$P(e) \models \sigma X.\phi \text{ iff } e \in \llbracket \sigma X.\phi \rrbracket_{\eta\varepsilon}$$

5. Conversion to PBES:

$$P(e) \models \sigma X.\phi \text{ iff } e \in \llbracket E(\sigma X.\phi) \rrbracket_{\eta\varepsilon(\tilde{X})} \text{ (or, more informally: } \tilde{X}(e) = \text{true)}$$

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## How to solve PBESs

$$X_i(e) \stackrel{?}{=} \text{true in } \mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

Known techniques for solving/simplifying  $\mathcal{E}$ :

- ▶ Gauß Elimination on PBES + symbolic approximation of equations
- ▶ **Instantiation to BES and subsequently solve the BES**
- ▶ Using patterns
- ▶ Using under/over approximation
- ▶ Invariants

## Definition (Logical Equivalence)

Let  $\phi, \psi$  be two predicates. Then  $\psi$  is logically equivalent to  $\phi$ , denoted  $\phi \leftrightarrow \psi$  iff

$$\forall \varepsilon, \eta : \llbracket \phi \rrbracket \eta \varepsilon = \llbracket \psi \rrbracket \eta \varepsilon$$

- ▶ If  $\phi \leftrightarrow \psi$ , then equation  $\nu X(d : D) = \phi$  has the same solution as  $\nu X(d : D) = \psi$  (likewise for  $\mu$ )
- ▶ Useful simplifications:
  - $\text{false} \wedge \phi \leftrightarrow \text{false}$
  - $\text{true} \vee \phi \leftrightarrow \text{true}$
  - if  $d \notin \text{FV}(\phi)$ , then  $(\exists d : D. \phi) \leftrightarrow (\forall d : D. \phi) \leftrightarrow \phi$
  - One-point rule:  $(\exists d : D. d = e \wedge \phi(d)) \leftrightarrow \phi(e)$
  - One-point rule:  $(\forall d : D. d = e \Rightarrow \phi(d)) \leftrightarrow \phi(e)$
- ▶ Apply logical simplifications **before** applying PBES manipulations/solving techniques.

Instantiation to BES:

$$X_i(e) \stackrel{?}{=} \text{true in } \mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

- ▶ Let  $X_i^e$  be a fresh propositional variable representing instance  $X_i(e)$ .
- ▶ The procedure below creates a BES from  $\mathcal{E}$  s.t.  $X_i(e) = \text{true}$  iff  $X_i^e = \text{true}$ 
  1. For each  $X_j(e_j)$  occurring in  $\text{eval}(\phi_i[d_i := e])$  create a fresh variable  $X_j^{e_j}$
  2. Create an equation  $\sigma_i X_i^e = \tilde{\phi}_i$ , where:
    - $\overline{\phi}_i = \text{eval}(\phi_i[d_i := e])$ ,
    - $\tilde{\phi}_i$  is  $\overline{\phi}_i$  in which every  $X_j(e_j)$  is replaced by  $X_j^{e_j}$
  3. Repeat step 1 and 2 for every  $X_j^{e_j}$  introduced in step 1, for which there is no equation
  4. Order all equations  $\sigma_i X_i^e = \dots$  according to the ordering of  $\mathcal{E}$  (ordering within a block may be arbitrary)



## Example

PBES:  $(\nu X(n : \text{Nat}) = n \leq 2 \wedge Y(n)) (\mu Y(n : \text{Nat}) = \text{odd}(n) \vee X(n + 1))$

Instantiation starting at e.g.  $X(0)$  ..... introduce  $X^0$

1.  $Y(0)$  occurs in  $\text{eval}((n \leq 2 \wedge Y(n))[n := 0])$  ..... introduce  $Y^0$
2. Introduce  $\nu X^0 = \text{eval}(0 \leq 2 \wedge Y^0)$  .....  $\nu X^0 = Y^0$
3.  $X(1)$  occurs in  $\text{eval}((\text{odd}(n) \vee X(n + 1))[n := 0])$  ..... introduce  $X^1$
4. Introduce  $\mu Y^0 = \text{eval}(\text{odd}(0) \vee X^1)$  .....  $\mu Y^0 = X^1$
5.  $Y(1)$  occurs in  $\text{eval}((n \leq 2 \wedge Y(n))[n := 1])$  ..... introduce  $Y^1$
6. Introduce  $\nu X^1 = \text{eval}(1 \leq 2 \wedge Y^1)$  .....  $\nu X^1 = Y^1$
7. no variable occurs in  $\text{eval}((\text{odd}(n) \vee X(n + 1))[n := 1])$  ..... end
8. Introduce  $\mu Y^1 = \text{eval}(\text{odd}(1) \vee X^2)$  .....  $\mu Y^1 = \text{true}$
9. Order equations: first  $X^i$ , then  $Y^j$
10. Resulting BES:  $(\nu X^0 = Y^0) (\nu X^1 = Y^1) (\mu Y_0 = X^1) (\mu Y_1 = \text{true})$

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## Definition (Simple Formula)

A **simple formula** is a formula not containing predicate variables

## Observations:

1. Consider the equation  $\nu X(n : \text{Nat}) = \text{true} \wedge X(n + 1)$ 
  - $X$  has solution  $\text{Nat}$  (check!)
  - Consider formal parameter  $n$ :
  - It does not affect the value of the **simple subformula**  $\text{true}$
  - It appears to be **redundant** for the solution to  $X$
2. Consider the equation  $\nu X(n : \text{Nat}, m : \text{Nat}) = n \leq 5 \wedge X(n + m, m)$ 
  - $X$  has solution  $\{(n, 0) \in \text{Nat} \times \text{Nat} \mid n \leq 5\}$  (check!)
  - Consider formal parameter  $m$ :
  - It does not affect the value of the **simple formula**  $n \leq 5$
  - Via a single recursion through  $X$ , it **does** affect the value of  $n \leq 5$
  - It appears to become **significant** for the solution to  $X$

- ▶ Identify all **obvious significant** formal parameters ..... sig
- ▶ Identify the **dependencies** ..... dep

$$\text{sig}(b) = \text{FV}(b)$$

$$\text{sig}(X(e)) = \emptyset$$

$$\text{sig}(\phi \wedge \psi) = \text{sig}(\phi) \cup \text{sig}(\psi)$$

$$\text{sig}(\phi \vee \psi) = \text{sig}(\phi) \cup \text{sig}(\psi)$$

$$\text{sig}(\forall d:D. \phi) = \text{sig}(\phi) \setminus \{d\}$$

$$\text{sig}(\exists d:D. \phi) = \text{sig}(\phi) \setminus \{d\}$$

$$\text{dep}(b) = \emptyset$$

$$\text{dep}(X(e)) = \{X(e)\}$$

$$\text{dep}(\phi \wedge \psi) = \text{dep}(\phi) \cup \text{dep}(\psi)$$

$$\text{dep}(\phi \vee \psi) = \text{dep}(\phi) \cup \text{dep}(\psi)$$

$$\text{dep}(\forall d:D. \phi) = \text{dep}(\phi)$$

$$\text{dep}(\exists d:D. \phi) = \text{dep}(\phi)$$

Examples:

- ▶  $\text{sig}(\text{true} \wedge X(n+1)) = \emptyset$ ,  $\text{sig}(n \leq 5 \wedge X(n+m, m)) = \{n\}$
- ▶  $\text{dep}(\text{true} \wedge X(n+1)) = \{X(n+1)\}$ ,  $\text{dep}(n \leq 5 \wedge X(n+m, m)) = \{X(n+m, m)\}$

Assume the following PBES:

$$\mathcal{E} := (\sigma_1 X_1(d_1 : D_1) = \phi_1) \cdots (\sigma_n X_n(d_n : D_n) = \phi_n)$$

- ▶  $\text{arity}(X_i)$ : the length of vector  $d_i$
- ▶  $d_i[j]$  denotes the  $j$ -th element of vector  $d_i$
- ▶ Construct a **marked influence graph**  $G(\mathcal{E}) = \langle V, \longrightarrow, M \rangle$ :
  - ▶  $V = \{(X_i, j) \mid 1 \leq j \leq \text{arity}(X_i)\}$  is the set of **vertices**
  - ▶  $(X_i, k) \longrightarrow (X_j, l)$  iff for some expression  $e$ :  $X_j(e) \in \text{dep}(\phi_i)$  and  $d_i[k] \in \text{FV}(e[l])$
  - ▶  $M = \{(X_i, j) \mid 1 \leq i \leq n \text{ and } d_i[j] \in \text{sig}(\phi_i)\}$  is the **marking**

### Definition (Positively redundant parameters)

Given a Marked Influence Graph  $G(\mathcal{E}) = \langle V, \longrightarrow, M \rangle$ .

The set of **positively redundant parameters** of  $\mathcal{E}$  is:

$$\mathcal{R} = \{d_i[j] \mid \neg(\exists (X_k, l) \in M : (X_i, j) \longrightarrow^* (X_k, l))\}$$

- ▶ Computing the set  $\mathcal{R}$  requires  $\mathcal{O}(|\longrightarrow|)$  steps at most
- ▶  $\mathcal{R}$  can be computed using a standard least fixed point computation, a depth-first search or a breadth-first search.

Given closed equation system  $\mathcal{E}$  with no unbound data variables

### Procedure for eliminating redundant parameters in $\mathcal{E}$

1. Step 1 (compute redundant parameters)
  - 1.1 Construct Marked Influence Graph of  $\mathcal{E}$
  - 1.2 Compute the set  $\mathcal{R}$  of positive redundant parameters of  $\mathcal{E}$
2. Step 2 (remove redundant parameters): for every equation  $\sigma_i X_i(d_i:D_i) = \phi_i$  in  $\mathcal{E}$ :
  - 2.1 remove parameter  $d_i[j]$  from  $X_i(d_i:D_i)$  iff  $d_i[j] \in \mathcal{R}$
  - 2.2 remove expression  $e[j]$  from an occurrence  $X_k(e)$  in  $\phi_i$  iff  $d_k[j] \in \mathcal{R}$

### Theorem (Redundancy)

*The modified equation system  $\mathcal{E}$  has the “same” solution as  $\mathcal{E}$ , i.e., the solution of a variable  $X$  **does not depend** on the parameters that have been identified as positively redundant.*

## Example

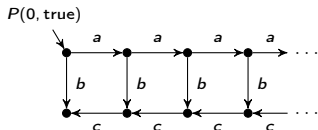
- ▶  $\nu X(b:Bool, n:Nat) = b \wedge X(b, n + 1)$  has solution  $f = \{(c, v) \in Bool \times Nat \mid c = \text{true}\}$
- ▶  $\nu X(b:Bool) = b \wedge X(b)$  has solution  $g = \{c \in Bool \mid c = \text{true}\}$
- ▶ For all  $c \in Bool, v \in Nat, (c, v) \in f$  iff  $c \in g$ .



## Example

Consider the following process:

$$\begin{aligned}
 & P(n: \text{Nat}, d: \text{Bool}) \\
 = & d \longrightarrow a \cdot P(n+1, d) \\
 + & d \longrightarrow b \cdot P(n, \neg d) \\
 + & \neg d \wedge n > 0 \longrightarrow c \cdot P(n-1, d)
 \end{aligned}$$



Along every  $a$  path, always a  $b$  action is attainable:

$$\nu V. ([a]V \wedge \mu W. (\langle a \rangle W \vee \langle b \rangle \text{true}))$$

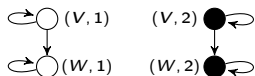
$$\begin{aligned}
 \text{PBES: } \left\{ \begin{aligned}
 \nu V(n: \text{Nat}, d: \text{Bool}) &= (d \implies V(n+1, d)) \wedge W(n, d) \\
 \mu W(n: \text{Nat}, d: \text{Bool}) &= d \vee (d \wedge W(n+1, d))
 \end{aligned} \right.
 \end{aligned}$$

Instantiation of the PBES does not terminate.

## Example (Cont'd)

$$\text{PBES: } \begin{cases} (\nu V(n:\text{Nat}, d:\text{Bool}) = (d \implies V(n+1, d)) \wedge W(n, d)) \\ (\mu W(n:\text{Nat}, d:\text{Bool}) = d \vee (d \wedge W(n+1, d))) \end{cases}$$

- ▶  $\text{dep}((d \implies V(n+1, d)) \wedge W(n, d)) = \{V(n+1, d), W(n, d)\}$
- ▶  $\text{dep}(d \vee (d \wedge W(n+1, d))) = \{W(n+1, d)\}$
- ▶ Marked Influence Graph ( $\text{arity}(V) = \text{arity}(W) = 2$ ):



Marked states are black;  
non-marked white

- ▶  $\mathcal{R} = \{(V, 1), W(1)\}$ , i.e., parameter  $n$  is positively redundant for  $V$  and  $W$ .
- ▶ Reduced PBES: 
$$\begin{cases} (\nu V(d:\text{Bool}) = (d \implies V(d)) \wedge W(d)) \\ (\mu W(d:\text{Bool}) = d \vee (d \wedge W(d))) \end{cases}$$
- ▶ Instantiation of the above PBES **terminates**

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Consider the lossy channel system described by the following LPE:

$$\begin{aligned}
 C(b : Bool, m : M) &= \sum_{k:M} b \longrightarrow r(k) \cdot C(false, k) \\
 &+ \neg b \longrightarrow s(m) \cdot C(true, m) \\
 &+ \neg b \longrightarrow l \cdot C(true, m)
 \end{aligned}$$

Action  $r$  stands for reading,  $s$  stands for sending and  $l$  stands for losing a message.

- $\nu X.([\text{true}]X \wedge (\mu Y.[l]Y \wedge \forall m:M.[r(m)]Y \wedge \langle \text{true} \rangle \text{true}))$
- $\nu X.\mu Y.\nu Z.(\forall m:M.[s(m)]X) \wedge ((\forall m:M.[s(m)]\text{false}) \vee ([l]Y \wedge \forall m:M.[r(m)]Y)) \wedge [l]Z \wedge \forall m:M.[r(m)]Z$

### Questions:

- ▶ Translate both formulae to PBESs given process  $C(\text{true}, m_0)$
- ▶ Use instantiation to compute BESs when  $M = Bool$ , and solve the BES ( $m_0 = \text{true}$ )
- ▶ Can you remove redundant parameters? If so, remove these redundant parameters and try instantiation to compute a BES when  $M = Nat$  ( $m_0 = 0$ )