

# Algorithms for Model Checking (2IW55)

## Lecture 9

### Parameterised Boolean Equation Systems

Background material:

"Model-checking processes with data" and  
"Parameterised Boolean Equation Systems",  
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# Symbolic System Specification

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Today: System specification represented by **Linear Process Equations**:

▶ **abstract data types** for reasoning about data

- **data sorts** .....  $Bool, Nat$
- **function symbols** .....  $and : Bool \times Bool \rightarrow Bool$
- **equations** .....  $and(x, true) = x$

▶ **process algebra** for reasoning about dynamic behaviour

- **parameterised atomic actions** .....  $read(n), write(n)$
- **process operators** .....  $+, \sum_{n:Nat}, \cdot$
- **parameterised recursion** .....  $X(n : Nat) = a \cdot X(n) + \sum_{m:Nat} b(m) \cdot X(m)$

## Linear Process Equation format

$$\begin{aligned}
 X(d : D) = & \sum_{e_1 : D_1} c_1(d, e_1) \longrightarrow a_1(f_1(d, e_1)) \cdot X(g_1(d, e_1)) \\
 & + \dots \\
 & + \sum_{e_n : D_n} c_n(d, e_n) \longrightarrow a_n(f_n(d, e_n)) \cdot X(g_n(d, e_n))
 \end{aligned}$$

- ▶  $d$  is a vector of **state variables**

For every summand  $i$ :

- ▶  $e_i$  is the vector of **local variables**
- ▶  $c_i$  is the **enabling condition**; free variables in  $c_i$  are  $d$  and  $e_i$
- ▶  $a_i \in Act$  is the **action label**;  $a_i$  carries parameters of sort  $D_{a_i}$ .
- ▶  $f_i$  is the **parameter** for action  $a_i$ ; free variables in  $f_i$  are  $d$  and  $e_i$
- ▶  $g_i$  is the **next-state**; free variables in  $c_i$  are  $d$  and  $e_i$

## Linear Process Equation format

$$\begin{aligned}
 X(d : D) = & \sum_{e_1 : D_1} c_1(d, e_1) \longrightarrow a_1(f_1(d, e_1)) \cdot X(g_1(d, e_1)) \\
 & + \dots \\
 & + \sum_{e_n : D_n} c_n(d, e_n) \longrightarrow a_n(f_n(d, e_n)) \cdot X(g_n(d, e_n))
 \end{aligned}$$

Semantics:  $[X(e)]$  defines the **Labelled Transition System**  $[X(e)] = \langle S, s_0, Act', \rightarrow \rangle$ :

- ▶  $S = D$  is the **state space**
- ▶  $s_0 = e$  is the **initial state**
- ▶  $Act' = \{a_i(d) \mid 1 \leq i \leq n \wedge d \in D_{a_i}\}$  is the **set of actions**
- ▶  $d \xrightarrow{a} d'$  iff for some  $i$ :  $\exists e_i : D_i. c_i(d, e_i) \wedge d' = g_i(d, e_i) \wedge a = a_i(f_i(d, e_i))$

## Example

Consider the system  $X(0, \text{true})$  given by the following LPE:

$$X(n : \text{Nat}, b : \text{Bool}) = \sum_{m:\text{Nat}} b \longrightarrow r(m) \cdot X(m, \neg b) + \neg b \longrightarrow s(n) \cdot X(n, \neg b)$$

### Intuition:

- if  $b$  holds, then an **arbitrary** natural number can be read through action  $r$
- if  $\neg b$  holds, then **value**  $n$  is sent through action  $s$

### Formally:

- State space:  $\text{Nat} \times \text{Bool}$
- Transitions: for all  $n, m \in \text{Nat}$ :  
 $(n, \text{true}) \xrightarrow{r(m)} (m, \text{false})$  and  $(n, \text{false}) \xrightarrow{s(n)} (n, \text{true})$

# Extended Hennessy-Milner Logic

- ▶ Hennessy-Milner Logic =  $\mu$ -calculus - recursion
- ▶ Grammar:

$$\phi, \psi ::= \text{true} \mid \text{false} \mid \phi \wedge \psi \mid \phi \vee \psi \mid \langle a \rangle \phi \mid [a] \phi$$

## Problem

Consider the process  $X(0, \text{true})$ , given by:

$$X(n : \text{Nat}, b : \text{Bool}) = \sum_{m:\text{Nat}} b \longrightarrow r(m) \cdot X(m, \neg b) + \neg b \longrightarrow s(n) \cdot X(n, \neg b)$$

Specify that every natural number  $n$  can be read through action  $r$ .

- ▶  $\langle r(0) \rangle \text{true} \wedge \langle r(1) \rangle \text{true} \wedge \langle r(2) \rangle \text{true} \wedge \dots$
- ▶ Hennessy-Milner formulae are **finite**: the above is not a Hennessy-Milner formula

Solving infinity problems:

- ▶ Introduce first-order quantification .....  $\forall d:D.\phi(d)$
- ▶ Inject **data** in modalities .....  $[a(d)]\phi$

Extended Hennessy-Milner formulae:

$$\phi, \psi ::= b \mid \phi \wedge \psi \mid \phi \vee \psi \mid \forall d:D.\phi \mid \exists d:D.\phi \mid \langle \alpha \rangle \phi \mid [\alpha] \phi$$

- ▶  $b$  is a Boolean expression ..... e.g.  $d + e \geq 5$
- ▶  $d$  is a sorted data variable

$\alpha$  is an **action formula**:

$$\alpha, \beta ::= a(e) \mid \text{true} \mid \neg \alpha \mid \alpha \wedge \beta \mid \alpha \vee \beta$$

- ▶  $e$  is a data expression for action label  $a$

## Example

Consider the process  $X(0, \text{true})$ , given by:

$$X(n : \text{Nat}, b : \text{Bool}) = \sum_{m:\text{Nat}} b \longrightarrow r(m) \cdot X(m, \neg b) + \neg b \longrightarrow s(n) \cdot X(n, \neg b)$$

- ▶ Some number can be read .....  $\exists n:\text{Nat}. \langle r(n) \rangle \text{true}$
- ▶ Every natural number can be read .....  $\forall n:\text{Nat}. \langle r(n) \rangle \text{true}$
- ▶ Any number that is read can subsequently be sent .....  $\forall n:\text{Nat}. [r(n)] \langle s(n) \rangle \text{true}$
- ▶ Only odd numbers can be sent .....  $\forall n:\text{Nat}. [s(n)] \text{odd}(n)$

Given LPE  $X$  with  $[X(e)] = \langle S, s_0, Act', \rightarrow \rangle$

- ▶ a state formula  $\phi$  characterises a set of states in  $S$
- ▶ state formulae contain **data variables** ..... e.g.  $n + 3 \geq m$
- ▶ values for data variables are given by an environment ..... e.g.  $\varepsilon(n) = 5$

$$[b]\varepsilon = \begin{cases} \emptyset & \text{if not } \varepsilon(b) \\ S & \text{otherwise} \end{cases}$$

$$[\phi \wedge \psi]\varepsilon = [\phi]\varepsilon \cap [\psi]\varepsilon \qquad [\phi \vee \psi]\varepsilon = [\phi]\varepsilon \cup [\psi]\varepsilon$$

$$[\forall d:D.\phi]\varepsilon = \bigcap_{v \in D} [\phi]\varepsilon[d := v] \qquad [\exists d:D.\phi]\varepsilon = \bigcup_{v \in D} [\phi]\varepsilon[d := v]$$

$$[[\alpha]\phi]\varepsilon = \{v \in S \mid \forall v' \in S, a \in [\alpha]\varepsilon : v \xrightarrow{a} v' \implies v' \in [\phi]\varepsilon\}$$

$$[\langle \alpha \rangle \phi]\varepsilon = \{v \in S \mid \exists v' \in S, a \in [\alpha]\varepsilon : v \xrightarrow{a} v' \wedge v' \in [\phi]\varepsilon\}$$

## Algorithms for Model Checking (2IW55)

### Extended Hennessy-Milner Logic

### Extended Hennessy-Milner Logic — Semantics

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Extended Hennessy-Milner Logic — Semantics

Given LPE  $X$  with  $[X(e)] = \langle S, s_0, Act', \rightarrow \rangle$

- ▶ a state formula  $\phi$  characterises a set of states in  $S$
- ▶ state formulae contain **data variables** ..... e.g.  $n + 3 \geq m$
- ▶ values for data variables are given by an environment ..... e.g.  $\varepsilon(n) = 5$

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$$[[\alpha]\phi]\varepsilon = \{v \in S \mid \forall v' \in S, a \in [\alpha]\varepsilon : v \xrightarrow{a} v' \implies v' \in [\phi]\varepsilon\}$$

$$[\langle \alpha \rangle \phi]\varepsilon = \{v \in S \mid \exists v' \in S, a \in [\alpha]\varepsilon : v \xrightarrow{a} v' \wedge v' \in [\phi]\varepsilon\}$$

## Example (Reconsider the example)

Consider the toggle  $X(\text{true})$ , given by:

$$X(b : \text{Bool}) = t(b) \cdot X(\neg b)$$

with  $[X(\text{true})] = \langle S, s_0, Act, \rightarrow \rangle$ .

state  $s$  satisfies  $\exists c:\text{Bool}. \langle t(c) \rangle \text{true}$  iff  $s$  satisfies  $\langle t(c) \rangle \text{true}$  for **some** value for  $c$ :

$$\begin{aligned} & [\exists c:\text{Bool}. \langle t(c) \rangle \text{true}]\varepsilon \\ = & \bigcup_{b \in \{\text{true}, \text{false}\}} [\langle t(c) \rangle \text{true}]\varepsilon[c := b] \\ = & \bigcup_{b \in \{\text{true}, \text{false}\}} \{v \in S \mid \exists v' \in S, a \in [t(c)]\varepsilon[c := b] : v \xrightarrow{a} v' \wedge v' \in [\text{true}]\varepsilon[c := b]\} \\ = & \bigcup_{a \in [t(c)]\varepsilon[c := \text{true}] \cup [t(c)]\varepsilon[c := \text{false}]} \{v \in S \mid v \xrightarrow{a}\} \end{aligned}$$

Given LPE  $X$  with  $[X(e)] = \langle S, s_0, Act', \rightarrow \rangle$

- ▶ an action formula characterises a set of **actions**

$$[a(e)]_{\varepsilon} = \{a(\varepsilon(e))\}$$

$$[\text{true}]_{\varepsilon} = Act'$$

$$[\neg\alpha]_{\varepsilon} = Act' \setminus [\alpha]_{\varepsilon}$$

$$[\alpha \wedge \beta]_{\varepsilon} = [\alpha]_{\varepsilon} \cap [\beta]_{\varepsilon}$$

$$[\alpha \vee \beta]_{\varepsilon} = [\alpha]_{\varepsilon} \cup [\beta]_{\varepsilon}$$

## Examples

- ▶ any action but  $read(3)$  .....  $\neg read(3)$
- ▶ any action other than  $read(d)$ , for quantified  $d$  .....  $\neg read(d)$

- ▶ First-order Modal mu-Calculus = Extended Hennessy-Milner logic + fixed points
- ▶ **State formulae** directly in **Positive Normal Form**:

$$\phi, \psi ::= b \mid \phi \vee \psi \mid \phi \wedge \psi \mid \exists d:D. \phi \mid \forall d:D. \phi \mid [\alpha]\phi \mid \langle \alpha \rangle \phi \mid Z \mid \mu Z. \phi \mid \nu Z. \phi$$

- ▶  $Z$  is a **formal variable**
- ▶  $\mu Z. \phi$  is the least fixed point;  $\nu Z. \phi$  is the greatest fixed point
- ▶  $\alpha$  is an **action formula** (see extended Hennessy-Milner logic)

Given LPE  $X$  with  $[X(e)] = \langle S, s_0, Act', \rightarrow \rangle$

- ▶ Extended Hennessy-Milner logic is interpreted in **one** environment  $\varepsilon$
- ▶ First-order Modal  $\mu$ -calculus requires **two** .....  $\varepsilon$  (for data) and  $\eta : Var \rightarrow 2^S$
- ▶ Semantics of  $\phi$  is given by  $[\phi]\eta\varepsilon$  .....  $\subseteq S$
- ▶ The set  $(2^S, \subseteq)$  is a **complete lattice**

For formulae  $\phi$  and variable  $Z$ , define  $\Phi_{\eta\varepsilon}^Z(S') := [\phi]\eta[Z := S']\varepsilon$

- ▶  $\Phi_{\eta\varepsilon}^Z$  is **monotone**:  $S' \subseteq T'$  implies  $\Phi_{\eta\varepsilon}^Z(S') \subseteq \Phi_{\eta\varepsilon}^Z(T')$
- ▶ The existence of least and greatest fixed points of  $\Phi_{\eta\varepsilon}^Z$  in  $(2^S, \subseteq)$  is thus guaranteed
- ▶ Notation:  $\nu\Phi_{\eta\varepsilon}^Z$  and  $\mu\Phi_{\eta\varepsilon}^Z$

Semantics of First-order Modal  $\mu$ -calculus formulae:

$$[Z]\eta\varepsilon = \eta(Z) \qquad [\nu Z. \phi]\eta\varepsilon = \nu\Phi_{\eta\varepsilon}^Z \qquad [\mu Z. \phi]\eta\varepsilon = \mu\Phi_{\eta\varepsilon}^Z$$

## Example

1. Some action is enabled .....  $\langle \text{true} \rangle \text{true}$
2. Absence of deadlock .....  $\nu X. [\text{true}]X \wedge \langle \text{true} \rangle \text{true}$
3. Reading value  $n$  is always inevitably followed by sending value  $n$   
 $\nu X. \forall n: \text{Nat}. [\text{true}]X \wedge [r(n)]\mu Y. ([\neg s(n)]Y \wedge \langle \text{true} \rangle \text{true})$
4. Every stream of numbers is increasing.  $\nu X. \forall n: \text{Nat}. [r(n)](X \wedge \forall m: \text{Nat}. [r(m)](m > n))$

## Problem Description

1. Given a process  $X(e)$  described by an LPE  $X$  over  $Act$
2. Given a first-order modal  $\mu$ -calculus formula  $\phi$
3. Given environments  $\eta, \varepsilon$
4. Check whether  $X(e) \models \phi$  holds, where:

$$X(e) \models \phi \text{ iff } e \in [\phi]_{\eta\varepsilon}$$

- ▶ Decidable for **finite data types**
  - Compute LTS  $[X(e)]$
  - Evaluate  $\phi$  on  $[X(e)]$  using standard model algorithms
- ▶ In general **undecidable**
- ▶ Transform problem to **Parameterised** Boolean Equation Systems (PBESs)

## Grammar for predicate formulae

$$\phi, \psi ::= b \mid X(e) \mid \phi \wedge \psi \mid \phi \vee \psi \mid \forall d : D. \phi \mid \exists d : D. \phi$$

- ▶  $b$  is a **boolean expression** .....  $n + m \geq 5$
- ▶  $X \in \mathcal{P}$  is a **sorted** predicate variable .....  $X : D \rightarrow Bool$
- ▶  $e$  is an expression of sort  $D$
- ▶ Interpreting  $\phi$  requires **two** environments .....  $\varepsilon$  (for data) and  $\eta : \mathcal{P} \rightarrow (D \rightarrow Bool)$

$$[b]_{\eta\varepsilon} = \begin{cases} \text{true} & \text{if } \varepsilon(b) \\ \text{false} & \text{else} \end{cases}$$

$$[X(e)]_{\eta\varepsilon} = \eta(X)(\varepsilon(e))$$

$$[\phi \wedge \psi]_{\eta\varepsilon} = [\phi]_{\eta\varepsilon} \wedge [\psi]_{\eta\varepsilon}$$

$$[\phi \vee \psi]_{\eta\varepsilon} = [\phi]_{\eta\varepsilon} \vee [\psi]_{\eta\varepsilon}$$

$$[\forall d : D. \phi]_{\eta\varepsilon} = \forall v \in D : [\phi]_{\eta(\varepsilon[d := v])}$$

$$[\exists d : D. \phi]_{\eta\varepsilon} = \exists v \in D : [\phi]_{\eta(\varepsilon[d := v])}$$



- ▶ The set of functions  $f: D \rightarrow Bool$  is denoted  $Bool^D$
- ▶ For  $f, g \in Bool^D$ , let  $f \sqsubseteq g$  iff for all  $d \in D$ ,  $f(d) \Rightarrow g(d)$
- ▶  $(Bool^D, \sqsubseteq)$  is a complete lattice

To formulae  $\phi$ , variables  $Z$  and  $d$ , associate  $\Phi_{\eta\varepsilon}^Z(f) := \lambda v \in D. [\phi]\eta[Z := f]\varepsilon[d := v]$

- ▶  $\Phi_{\eta\varepsilon}^{Z,d}$  is **monotone**:  $f \sqsubseteq g$  implies  $\Phi_{\eta\varepsilon}^{Z,d}(f) \sqsubseteq \Phi_{\eta\varepsilon}^{Z,d}(g)$
- ▶ Least and greatest fixed points of  $\Phi_{\eta\varepsilon}^{Z,d}$  in  $(Bool^D, \sqsubseteq)$  are guaranteed to exist
- ▶ Least fixed point is denoted  $\mu\Phi_{\eta\varepsilon}^{Z,d}$ ; dually:  $\nu\Phi_{\eta\varepsilon}^{Z,d}$

A **parameterised Boolean equation** is an equation of the form  $\sigma X(d : D) = \phi$

- ▶  $\sigma$  is a least fixed point sign  $\mu$  or a greatest fixed point sign  $\nu$ .
- ▶  $\phi$  is a predicate formula,  $X$  a predicate variable
- ▶ a **parameterised Boolean equation system** is a sequence of such equations

- ▶ As in BESs, the **order** of equations is important.
- ▶ **bounded, free, well-formedness, open, close** as in BESs
- ▶ The **solution** of a PBES is an environment:  $\eta : \mathcal{P} \rightarrow (D \rightarrow Bool)$

Given a PBES  $\mathcal{E}$ , we define  $[\mathcal{E}]\eta\varepsilon$  by recursion on  $\mathcal{E}$ .

$$\left\{ \begin{array}{l} [\varepsilon]\eta\varepsilon \quad \quad \quad := \eta \\ [(\mu X(d : D) = \phi) \mathcal{E}]\eta\varepsilon \quad := [\mathcal{E}]\eta[X := \mu\Phi_{([\mathcal{E}]\eta\varepsilon)\eta\varepsilon}^{X,d}] \varepsilon \\ [(\nu X(d : D) = \phi) \mathcal{E}]\eta\varepsilon \quad := [\mathcal{E}]\eta[X := \nu\Phi_{([\mathcal{E}]\eta\varepsilon)\eta\varepsilon}^{X,d}] \varepsilon \end{array} \right.$$

Note:  $\Phi_{\theta\varepsilon}^{X,d}$  is the monotone functional associated to  $\phi$ ,  $X$  and  $d$

- ▶ Consider the process  $X$ , given by:

$$X(n : Nat, b : Bool) = \sum_{m:Nat} b \longrightarrow r(m) \cdot X(m, \neg b) \\ + \quad \neg b \longrightarrow s(n) \cdot X(n, \neg b)$$

- ▶  $X(n, b) \models \nu Y. [\text{true}]Y \wedge \langle \text{true} \rangle \text{true}$  is encoded by the PBES:

$$\nu \bar{Y}(n : Nat, b : Bool) = \forall m : Nat. b \implies \bar{Y}(m, \neg b) \\ \wedge \quad \neg b \implies \bar{Y}(n, \neg b) \\ \wedge \quad ((\exists m : Nat. b) \vee (\neg b))$$

- ▶ for all  $n, b$ ,  $\bar{Y}(n, b) = \text{true}$  iff  $X(n, b) \models \nu Y. [\text{true}]Y \wedge \langle \text{true} \rangle \text{true}$
- ▶ Intuition: the outcome should not depend on the value of  $n$
- ▶ Reduced and simplified PBES:

$$\nu \bar{Y}(b : Bool) = (b \implies \bar{Y}(\neg b)) \wedge (\neg b \implies \bar{Y}(\neg b))$$

- ▶ Translates to the following BES:  $(\nu \bar{Y}_{\text{true}} = \bar{Y}_{\text{false}}) (\nu \bar{Y}_{\text{false}} = \bar{Y}_{\text{true}})$

Next week:

- ▶ Translate  $X(d) \models \phi$  to a PBES
- ▶ Reduce complexity of PBES
- ▶ Procedures for solving PBESs

Let  $X$  be an LPE with  $Act = \{r, s, i\}$ , where:

- ▶  $r$  (read) and  $s$  (send) take natural numbers as parameters
- ▶  $i$  (internal activity) is a parameterless action

Specify the following requirements in the First-order modal  $\mu$ -calculus

- ▶ No infinite sequence of  $i$  actions is reachable
- ▶ In all states, every  $r$  action is inevitably followed by a  $s$  action
- ▶ In all states, every  $r(n)$  action can eventually be followed by a  $s(n)$  action
- ▶ There is a path on which infinitely many  $r$  actions occur

Explain the following requirements in natural language

- ▶  $\nu Y. [\text{true}]Y \wedge \forall n: \text{Nat}. [r(n)]\mu Z. [i]Z \wedge \langle s(n) \rangle \text{true}$
- ▶  $\nu Y. [i]Y \wedge \langle \text{true} \rangle \text{true}$